Translation of the original operating instructions / Project planning manual | EN


## Inverter

i510 cabinet frequency inverter
0.25 kW ... 15 kW
$0.33 \mathrm{hp} . . .20 \mathrm{hp}$

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## About this document

## Document description

This document is intended for all persons who want to configure inverters with the products described.

This document assists you with the configuration and selection of your product. It contains information on mechanical and electrical installation, on product expansions, and on accessories.

## Further documents

For certain tasks, information is available in further documents.

| Document | Contents/topics |
| :--- | :--- |
| Mounting sheet | General safety instructions and important UL/CSA instructions, connection diagram and technical <br> data. <br> - The mounting sheet is included in the delivery of the product. |
| Operating instructions | Basic information on installing and commissioning the product. |
| Commissioning manual | Detailed information on setting and parameterizing the product. |

## More information

For certain tasks, information is available in other media.

| Medium | Contents/topics |
| :--- | :--- |
| Engineering Tools | For commissioning |
| AKB articles | Additional technical information for users in the Application Knowledge Base |
| CAD data | Download in different formats from the EASY Product Finder |
| EPLAN macros | Project planning, documentation and management of projects for EPLAN P8. |
| Device descriptions | Standardized files for network configuration |

Information and tools with regard to the Lenze products can be found on the Internet:
www.Lenze.com $\rightarrow$ Downloads

## Notations and conventions

Conventions are used in this document to distinguish between different types of information.

| Numeric notation |  |  |
| :---: | :---: | :---: |
| Decimal separator | Point | Generally shown as a decimal point. Example: 1234.56 |
| Warnings |  |  |
| UL Warnings | UL | Are used in English and French. |
| UR warnings | UR |  |
| Text |  |  |
| Engineering Tools | " " | Software <br> Example: "Engineer", "EASY Starter" |
| Icons |  |  |
| Page reference | $\square$ | Reference to another page with additional information. Example: 16 = see page 16 |
| Documentation reference | (6) | Reference to other documentation with additional information. Example: (:) EDKxxx = see documentation EDKxxx |

## Layout of the safety instructions

## 4. DANGER!

Indicates an extremely hazardous situation. Failure to comply with this instruction will result in severe irreparable injury and even death.

## WARNING!

Indicates an extremely hazardous situation. Failure to comply with this instruction may result in severe irreparable injury and even death.

## ©CAUTION!

Indicates a hazardous situation. Failure to comply with this instruction may result in slight to medium injury.

## NOTICE

Indicates a material hazard. Failure to comply with this instruction may result in material damage.

## Product information

## Product description

The i510 cabinet frequency inverter is a compact control cabinet device with scalable functionality. It is versatile, reliable and easy to use.

The requirements of the Ecodesign Directive, Standard EN 50598-2, are met.
Application areas: Conveyor drives, traveling drives, pumps, fans, agitators, ...

| Overview | $0.25 \ldots 15 \mathrm{~kW}$ |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| Power range | $1 \times 230 \mathrm{~V}$ | $3 \times 230 \mathrm{~V}$ | $3 \times 400 \mathrm{~V}$ | $3 \times 480 \mathrm{~V}$ |
| Mains connection | IP20 |  |  |  |
| Degree of protection | CANopen, Modbus RTU |  |  |  |
| Communication |  |  |  |  |

## Highlights

- Space saving design: 60 mm wide (up to 4 kW ), 130 mm deep (up to 11 kW ), with zeroclearance mounting
- Innovative interaction (e.g. over WLAN) makes new record-breaking commissioning times and convenient diagnostics a reality
- Special user-friendliness
- Can be directly connected without external cooling
- All typical motor control types of modern inverters
- Stroke and continuous operation of the motor according to common operating modes
- Networking options via CANopen/Modbus
- Extensive integrated functions


## The concept

The i510 cabinet frequency inverter consisting of Control Unit and Power Unit is always supplied as a complete inverter.
2 variants are available:

- Without network
- With CANopen/Modbus, switchable


## Load characteristics

The inverters have two different load characteristics: "Light Duty" and "Heavy Duty".
The "Light Duty" load characteristic allows for a higher output current with restrictions regarding overload capacity, ambient temperature and switching frequency. This allows the motor required for the application to be driven by a less powerful inverter. Select the load characteristic according to the application.

|  | Heavy Duty | Light Duty |
| :--- | :--- | :--- |
| Characteristic | High dynamic requirements | Low dynamic requirements |
| Typical applications | Main tool drives, travelling drives, hoist drives, <br> winders, forming drives and conveyors | Pumps, fans, general horizontal materials handling <br> technology and line drives |
| Overload capacity | 3 s $/ 200 \%, 60 \mathrm{~s} / 150 \%$ <br> See technical data | Restricted <br> See technical data |

## Features

The following figures give an overview of the elements and connections on the devices. Position, size and appearance of elements and connections may vary depending on the capacity and size of the equipment.

Some equipment may be optional.
Example of $0.25 \mathrm{~kW} . . .4 \mathrm{~kW}$


## Example of 5.5 kW



Example of $\mathbf{7 . 5} \mathbf{~ k W} . . .11 \mathrm{~kW}$


## Position and meaning of the nameplates


(1) Technical data
(2) Type and serial number of the inverter

## Product information

Features
Topologies / network

## Topologies / network

The inverters can be equipped with different fieldbus networks.
The topologies and protocols typical for the prevailing networks are supported.
Currently available networks:


CANopen ${ }^{\circledR}$ is a communication protocol based on CAN.
CANopen ${ }^{\circledR}$ is a registered community trademark of the CAN user organisation CiA ${ }^{\circledR}$ (CAN in Automation e. V.). Device descriptions for the download: EDS files for Lenze devices

The Modbus protocol is an open communication protocol based on a client/server architecture and developed for the communication with programmable logic controllers.
Further development is carried out by the international user organisation Modbus Organization, USA.
More information on the supported networks can be found at:
www.Lenze.com

## Functions

## Overview

The inverters i510 are adjusted to simple applications regarding their functionality.

| Functions |  |
| :---: | :---: |
| Motor control | Monitoring |
| V/f characteristic control linear/square-law (VFC plus) | Short circuit |
| Energy saving function (VFC-ECO) | earth fault |
| Sensorless vector control (SLVC) | Device overload monitoring ( $\mathrm{i}^{*} \mathrm{t}$ ) |
| Sensorless control for synchronous motors (SL-PSM/SLSM-PSM) | Motor overload monitoring ( $\mathrm{i}^{2 *} \mathrm{t}$ ) |
| Torque mode | Mains phase failure |
| Motor functions | Stalling protection |
| Flying restart circuit | Motor current limit |
| Slip compensation | Maximum torque |
| DC braking | Ultimate motor current |
| Oscillation damping | Motor speed monitoring |
| Skip frequencies | Load loss detection |
| Automatic identification of the motor data | Diagnostics |
| Brake energy management | Error history buffer |
| Holding brake control | Logbook |
| Voltage add - function | LED status displays |
| Rotational Energy Ride Through (RERT) | Keypad language selection German, English |
| Application functions | Network |
| Process controller | CANopen |
| Process controller - idle state and rinse function | Modbus RTU |
| Freely assignable favourite menu |  |
| Parameter change-over |  |
| S-shaped ramps for smooth acceleration |  |
| Motor potentiometer |  |
| Flexible I/O configuration |  |
| Access protection |  |
| Automatic restart |  |
| OEM parameter set |  |
| Sequencer |  |
| Complete control with 8-key keypad |  |
| UPS operation |  |
| "Light Duty" load characteristic can be adjusted for selected inverters |  |

## Motor control types

The following table contains the possible control types with Lenze motors.

| Motors | V/f characteristic control <br> VFCplus | Sensorless vector control <br> SLVC |  |
| :--- | :---: | :---: | :---: |
| Three-phase AC motors |  |  |  |
| MD | $\bullet$ | $\bullet$ |  |
| $M F$ | $\bullet$ | $\bullet$ |  |
| $m H$ | $\bullet$ | $\bullet$ |  |
| $m 500$ | $\bullet$ | $\bullet$ |  |

## Motor functions

## Motor setting range

Rated point 120 Hz
Only possible with Lenze MF motors.

The rated motor torque is available up to 120 Hz .
Compared to the $50-\mathrm{Hz}$ operation, the setting range increases by 2.5 times.
Thus, a smaller motor can be selected at the same rated power.
V/f at $\mathbf{1 2 0 ~ H z}$

## Rated point 87 Hz

The rated motor torque is available up to 87 Hz .
Compared to the $50-\mathrm{Hz}$ operation, the setting range increases by 1.74 times.
For this purpose, a motor with 230/400 V in a triangle is driven by a 400 V inverter.
The inverter must be dimensioned for a rated motor current of 230 V .

## V/f at 87 Hz



| V | Voltage |
| :--- | :--- |
| M | Torque |
| f | Frequency |

$$
\begin{array}{ll}
\mathrm{U}_{\mathrm{AC}} & \text { Mains voltage } \\
\mathrm{M}_{\text {rated }} & \text { Rated torque } \\
\mathrm{f}_{\text {rated }} & \text { Rated frequency }
\end{array}
$$

## Rated point 50 Hz

The rated motor torque is available up to 50 Hz .

## V/f at 50 Hz



| V | Voltage |
| :--- | :--- |
| M | Torque |
| f | Frequency |

$U_{A C} \quad$ Mains voltage
$M_{\text {rated }}$ Rated torque
$f_{\text {rated }} \quad$ Rated frequency

## Identification of the products

When the technical data of the different versions was listed, the product name was entered because it is easier to read than the individual product code of the product. The product name is also used for categorising the accessories. The assignment of product name and order code can be found in the "Order" chapter. 144

The product name contains the power in kW, the mains voltage class $120 \mathrm{~V}, 230 \mathrm{~V}$ or 400 V and the number of phases.

In the product name, the power information always refers to the "Heavy Duty" load characteristic.
The 1/3-phase inverters are marked at the end with "-2".
"C" marks the "Cabinet" version = inverter for the installation into the control cabinet.

| Device series | Design | Rated | ower | Rated mains voltage | No. of phases | Inverter |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Light Duty | Heavy Duty |  |  |  |
|  |  | kW | kW | V |  |  |
| i510 | C | - |  | 230 | 1 | i510-C0.25/230-1 |
|  |  |  |  |  | 1/3 | i510-C0.25/230-2 |
|  |  |  |  |  | 1 | i510-C0.37/230-1 |
|  |  |  |  |  | 1/3 | i510-C0.37/230-2 |
|  |  |  | 0.55 |  | 1 | i510-C0.55/230-1 |
|  |  |  |  |  | 1/3 | i510-C0.55/230-2 |
|  |  |  | 0.75 |  | 1 | i510-C0.75/230-1 |
|  |  |  |  |  | 1/3 | i510-C0.75/230-2 |
|  |  |  |  |  | 1 | i510-C1.1/230-1 |
|  |  |  |  |  | 1/3 | i510-C1.1/230-2 |
|  |  |  |  |  | 1 | i510-C1.5/230-1 |
|  |  |  |  |  | 1/3 | i510-C1.5/230-2 |
|  |  |  | 2.2 |  | 1 | i510-C2.2/230-1 |
|  |  |  |  |  | 1/3 | i510-C2.2/230-2 |


| Device series | Design | Rated power |  | Rated mains voltage | No. of phases | Inverter |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Light Duty | Heavy Duty |  |  |  |
|  |  | kW | kW | V |  |  |
| i510 | C | - | 0.25 | 240 | 1/3 | i510-C0.25/230-2 |
|  |  |  | 0.37 |  |  | i510-C0.37/230-2 |
|  |  |  | 0.55 |  |  | i510-C0.55/230-2 |
|  |  |  | 0.75 |  |  | i510-C0.75/230-2 |
|  |  |  | 1.1 |  |  | i510-C1.1/230-2 |
|  |  |  | 1.5 |  |  | i510-C1.5/230-2 |
|  |  |  | 2.2 |  |  | i510-C2.2/230-2 |
|  |  | 5.5 | 4 |  | 3 | i510-C4.0/230-3 |
|  |  | 7.5 | 5.5 |  |  | i510-C5.5/230-3 |


| Device series | Design | Rated power |  | Rated mains voltage | No. of phases | Inverter |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Light Duty | Heavy Duty |  |  |  |
|  |  | kW | kW | V |  |  |
| i510 | C | - | 0.37 | 400 | 3 | i510-C0.37/400-3 |
|  |  |  | 0.55 |  |  | i510-C0.55/400-3 |
|  |  |  | 0.75 |  |  | i510-C0.75/400-3 |
|  |  |  | 1.1 |  |  | i510-C1.1/400-3 |
|  |  |  | 1.5 |  |  | i510-C1.5/400-3 |
|  |  |  | 2.2 |  |  | i510-C2.2/400-3 |
|  |  | 4 | 3 |  |  | i510-C3.0/400-3 |
|  |  | 5.5 | 4 |  |  | i510-C4.0/400-3 |
|  |  | 7.5 | 5.5 |  |  | i510-C5.5/400-3 |
|  |  | 11 | 7.5 |  |  | i510-C7.5/400-3 |
|  |  | 15 | 11 |  |  | i510-C11/400-3 |


| Device series | Design | Rated power |  | Rated mains voltage | No. of phases | Inverter |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Light Duty | Heavy Duty |  |  |  |
|  |  | kW | kW | V |  |  |
| i510 | C | - | 0.37 | 480 | 3 | i510-C0.37/400-3 |
|  |  |  | 0.55 |  |  | i510-C0.55/400-3 |
|  |  |  | 0.75 |  |  | i510-C0.75/400-3 |
|  |  |  | 1.1 |  |  | i510-C1.1/400-3 |
|  |  |  | 1.5 |  |  | i510-C1.5/400-3 |
|  |  |  | 2.2 |  |  | i510-C2.2/400-3 |
|  |  | 4 | 3 |  |  | i510-C3.0/400-3 |
|  |  | 5.5 | 4 |  |  | i510-C4.0/400-3 |
|  |  | 7.5 | 5.5 |  |  | i510-C5.5/400-3 |
|  |  | 11 | 7.5 |  |  | i510-C7.5/400-3 |
|  |  | 15 | 11 |  |  | i510-C11/400-3 |

## Product code

|  |  | 1 | 5 | 1 | A | E | 믐 | $\square$ | 1 | 0 | 미 | - | ㅁำ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Product type | Inverter | 1 |  |  |  |  |  |  |  |  |  |  |  |
| Product family | i500 |  | 5 |  |  |  |  |  |  |  |  |  |  |
| Product | i510 |  |  |  |  |  |  |  |  |  |  |  |  |
| Product generation | Generation 1 |  |  |  | A |  |  |  |  |  |  |  |  |
|  | Generation 2 |  |  |  | B |  |  |  |  |  |  |  |  |
| Mounting type | Control cabinet mounting |  |  |  |  | E |  |  |  |  |  |  |  |
| Rated power | 0.25 kW |  |  |  |  |  | 125 |  |  |  |  |  |  |
| (Examples) | 0.55 kW |  |  |  |  |  | 155 |  |  |  |  |  |  |
|  | 2.2 kW |  |  |  |  |  | 222 |  |  |  |  |  |  |
| Mains voltage and connection | 1/N/PE AC 230/240 V |  |  |  |  |  |  | B |  |  |  |  |  |
|  | 1/N/PE AC 230/240 V |  |  |  |  |  |  | D |  |  |  |  |  |
|  | 2/N/PE AC 230/240 V |  |  |  |  |  |  |  |  |  |  |  |  |
|  | 3/PE AC 230/240 V |  |  |  |  |  |  | C |  |  |  |  |  |
|  | 3/PE AC 400 V <br> 3/PE AC 480 V |  |  |  |  |  |  | F |  |  |  |  |  |
| Motor connections | Single axis |  |  |  |  |  |  |  | 1 |  |  |  |  |
| Integrated functional safety | Without |  |  |  |  |  |  |  |  | 0 |  |  |  |
| Degree of protection | IP20 |  |  |  |  |  |  |  |  |  | 0 |  |  |
|  | IP20, coated |  |  |  |  |  |  |  |  |  | V |  |  |
| Interference suppression | Without |  |  |  |  |  |  |  |  |  | 0 |  |  |
|  | Integrated RFI filter |  |  |  |  |  |  |  |  |  | 1 |  |  |
| Application | Default parameter setting: Region EU ( $50-\mathrm{Hz}$ networks) |  |  |  |  |  |  |  |  |  |  | 0 |  |
|  | Default parameter setting: Region US (60-Hz networks) |  |  |  |  |  |  |  |  |  |  | 1 |  |
| Design types | Basic I/O without network |  |  |  |  |  |  |  |  |  |  |  | 000S |
|  | Basic I/O with CANopen/Modbus |  |  |  |  |  |  |  |  |  |  |  | 0015 |

## Example:

| Product code | Meaning |
| :--- | :--- |
| I51AE215F10010001S | Inverter i510 cabinet, 1.5 kW, three-phase, $400 \mathrm{~V} / 480 \mathrm{~V}$ <br> IP20, integrated RFI filter, $50-\mathrm{Hz}$ version <br> Basic I/O with CANopen/Modbus network |

## Ways of commissioning

There are three ways to commission the inverter quickly and easily.
Thanks to Lenze's engineering philosophy, the high functionality is still easy to grasp. Parameterization and commissioning are a breeze thanks to clear structure and simple dialogs, leading to the desired outcome quickly and reliably.

## Keypad

If it's only a matter of setting a few key parameters such as acceleration and deceleration time, this can be done quickly on the keypad.


## »EASY Starter"

If functions such as the holding brake control or sequencer need to be set, it's best to use the »EASY Starter« engineering tool.


## SMART Keypad App

The Lenze SMART Keypad App for Android or iOS allows you to diagnose and parameterize an inverter. A WLAN module on the inverter is required for communication.

- Ideal for the parameterization of simple applications such as a conveyor belt.
- Ideal for the diagnostics of the inverter.

The app can be found in the Google Play Store or in the Apple App Store.


Android

iOS

## Safety instructions

## Basic safety instructions

Disregarding the following basic safety instructions and safety information may lead to severe personal injury and damage to property!

- Only use the product as directed.
- Never commission the product in the event of visible damage.
- Never modify the product technically.
- Never commission the product before assembly has been completed.
- Never operate the product without the required covers.
- Connect/disconnect all pluggable connections only in deenergized condition!
- Only remove the product from the installation in the deenergized state.
- The product can - depending on their degree of protection - have live, movable or rotating parts during or after operation. Surfaces can be hot.
- Observe the specifications of the corresponding documentation. This is the condition for safe and trouble-free operation and the achievement of the specified product features.
- The procedural notes and circuit details given in the associated documentation are suggestions and their transferability to the respective application has to be checked. The manufacturer of the product does not take responsibility for the suitability of the process and circuit proposals.
- All work with and on the product may only be carried out by qualified personnel. IEC 60364 and CENELEC HD 384 define the qualifications of these persons:
- They are familiar with installing, mounting, commissioning, and operating the product.
- They have the corresponding qualifications for their work.
- They know and can apply all regulations for the prevention of accidents, directives, and laws applicable at the place of use.

Please observe the specific safety information in the other sections!

## Application as directed

- The product is a professional equipment intended for use by trades, specific professions or industry and not for sale to the general public. IEC 60050 [IEV 161-05-05]
- To prevent personal injury and damage to property, higher-level safety and protection systems must be used!
- All transport locks must be removed.
- The product may only be operated under the specified operating conditions and in the specified mounting positions.
- The product is exclusively suitable for installation in control cabinets and, depending on the protection class and design, for wall and motor mounting.
- The product must only be actuated with motors that are suitable for the operation with inverters.
- The product must not be operated in private areas, in potentially explosive atmospheres and in areas with harmful gases, oils, acids and radiation.


## Additional information for the intended use in North America:

The cables must be installed in accordance with US National Electrical Code NFPA 70 or Canadian Electrical Code C22.1.

## Use of explosion-protected motors

Explosion-protected motors that are not designed for use with an inverter lose their approval if they are used for variable speed applications. Due to the many areas of liability that may arise when handling these applications, the following policy statement applies:


Lenze inverters are sold without warranty of suitability for use with explosionprotected motors. Lenze assumes no responsibility for direct, incidental or consequential damages, costs or losses that may result from the use of AC inverters with explosion-protected motors. Buyer expressly agrees to assume any risk of loss, expense or damage that may result from such application.

## Foreseeable misuse

Inverters are not to be operated with DC motors.

## Safety instructions

Handling

## Handling

## Transport, storage

Observe the notes regarding transport, storage and correct handling. Ensure proper handling and avoid mechanical stress. Do not bend any components and do not change any insulation distances during transport or handling. Do not touch any electronic components and contacts. Inverters contain electrostatically sensitive components which can easily be damaged by inappropriate handling. Do not damage or destroy any electrical components since thereby your health could be endangered!

## Installation

The technical data and supply conditions can be obtained from the nameplate and the documentation. They must be strictly observed.
The inverters must be installed and cooled according to the instructions given in the corresponding documentation. Observe the climatic conditions according to the technical data. The ambient air must not exceed the degree of pollution 2 according to EN 61800-5-1.

## Electrical connection

When working on energized inverters, comply with the applicable national accident prevention regulations.

The electrical installation must be carried out according to the appropriate regulations (e. g. cable cross-sections, fuses, PE connection). Additional information can be obtained from the documentation.

The documentation contains information about installation according to EMC regulations (shielding, grounding, filters and cable routing). Please also observe this information for CEmarked inverters. The manufacturer of the system or machine is responsible for adherence to the limit values required in connection with EMC legislation.

The inverters must be installed in housings (e. g. control cabinets) to meet the limit values for radio interferences valid at the site of installation. The housings must enable an EMCcompliant installation. Observe in particular that e. the control cabinet doors should have a circumferential metal connection to the housing. Reduce housing openings and cutouts to a minimum.

## Protection in the event of short circuit or earth fault

To ensure protection according to EN 61800-5-1 in the event of an electrical short circuit or earth fault (protection against electric shock, thermal hazards and fire), the following must be taken into account in the installation:

- Use fuses according to the technical data.
- The installation must meet the requirements of the IEC 60364.
- The continuity of all associated protective conductors and equipotential bonding conductors including all connection points must be ensured.
- If the maximum permissible switch-off time according to IEC 60364 is exceeded with a high system impedance (especially with TT mains) or a high loop impedance with the prescribed fuses, a residual current device (RCD) can be used. Alternatively, other protective measures can be used, e. g. isolation from the environment by means of double or reinforced insulation, or isolation from the supply system by using a transformer.
- If a residual current device (RCD) is connected upstream of the inverter for protection in the event of an earth fault, only type $B / B+$ is permitted for three-phase devices.


## Operation

If necessary, systems including inverters must be equipped with additional monitoring and protection devices. Also comply with the safety regulations and provisions valid at the installation site.

After the inverter has been disconnected from the supply voltage, all live components and power terminals must not be touched immediately because capacitors can still be charged. Please observe the corresponding stickers on the inverter.

All protection covers and doors must be shut during operation.

You may adapt the inverters to your application by parameter setting within the limits available. For this, observe the notes in the documentation.

## Safety functions

Certain inverter versions support safety functions (e. g. "safe torque off", formerly "safe standstill") according to the requirements of the EC Machinery Directive 2006/42/EC [UKCA: S.I. 2008/1597] . The notes on the integrated safety provided in this documentation must be observed.

Maintenance and servicing
The inverters do not require any maintenance if the prescribed operating conditions are observed.

## Disposal

In accordance with the current provisions, Lenze products and accessories have to be disposed of by means of professional recycling. Lenze products contain contain recyclable raw material such as metal, plastics and electronic components.

## Safety instructions

Residual hazards

## Residual hazards

Even if notes given are taken into consideration and protective measures are implemented, the occurrence of residual risks cannot be fully prevented.

The user must take the residual hazards mentioned into consideration in the risk assessment for his/her machine/system.

If the above is disregarded, this can lead to severe injuries to persons and damage to property!

## Product

Observe the warning labels on the product!


## Dangerous electrical voltage:

Before working on the product, make sure there is no voltage applied to the power terminals! After mains disconnection, the power terminals will still carry the hazardous electrical voltage for the time given next to the symbol!


Electrostatic sensitive devices: Before working on the product, the staff must ensure to be free of electrostatic charge!


High leakage current:
Carry out fixed installation and PE connection in compliance with: EN 61800-5-1 / EN 60204-1
 Hot surface: Use personal protective equipment or wait until the device has cooled down!

## Degree of protection - protection of persons and device protection

- Information applies to the mounted and ready-for-use state.
- Information does not apply to the wire range of the terminals.
- Terminals that are not wired have low protection against physical contact.
- Terminals for large cable cross-sections have lower classes of protection, e. g. from 15 kW IP10 only.


## Protection of persons

Before working on the inverter, check if no voltage is applied to the power terminals.

- Depending on the device, the power terminals X105 remain live for up to 20 minutes.
- The power terminals X100 and X105 remain live even when the motor is stopped.


## Device protection

- The maximum test voltage for insulation tests between a control potential of 24 V and PE must not exceed 110 V DC (EN 61800-5-1).


## Motor protection

With some settings of the inverter, the connected motor can be overheated.

- E. g. by longer operation of self-ventilated motors at low speed.
- E. g. by longer operation of DC-injection braking.


## Protection of the machine/system

Drives can reach dangerous overspeeds.

- E. g. by setting high output frequencies in connection with motors and machines not suitable for this purpose.
- The inverters do not provide protection against such operating conditions. For this purpose, use additional components.

Switch contactors in the motor cable only if the controller is inhibited.

- Switching while the inverter is enabled is only permissible if no monitoring functions are activated.

Residual hazards

## Motor

If there is a short circuit of two power transistors, a residual movement of up to $180^{\circ} /$ number of pole pairs can occur at the motor! (e. g. 4-pole motor: residual movement max. 180 $/ 2=$ $90^{\circ}$ ).

## Information on project planning

Project planning process
Dimensioning

## Information on project planning

## Project planning process

## Dimensioning

## 3 methods for dimensioning

Fast: Selection of the inverter based on the motor data of a 4-pole asynchronous motor.
Detailed: In order to optimize the selection of the inverter and all drive components, it is worthwhile to execute the detailed system dimensioning based on the physical requirements of the application. For this purpose, Lenze provides the Drive Solution Designer (DSD) design program.

Manual: The following chapter guides you step by step through the selection of a drive system.
Workflow of a configuration process
Define required input variable

Calculate range of adjustment and determine rated point


Define required input variables

| Operating mode |  |  | S1 or S6 |
| :--- | :--- | :--- | :--- |
| Max. load torque | $\mathrm{M}_{\mathrm{L}, \max }$ | Nm |  |
| Max. load speed | $\mathrm{n}_{\mathrm{L}, \max }$ | rpm |  |
| Min. load speed | $\mathrm{n}_{\mathrm{L}, \min }$ | rpm |  |
| Site altitude | H | m |  |
| Ambient temperature (inverter) | $\mathrm{T}_{\mathrm{U}}$ | ${ }^{\circ} \mathrm{C}$ |  |

Calculate range of adjustment and determine rated point

|  | Calculation |  |
| :---: | :---: | :---: |
| Setting range | $V=\frac{n_{L, \max }}{n_{L, \min }}$ |  |
|  | Setting range | Rated point |
| Motor with integral fan | $\begin{aligned} & \leq 2.50(20-50 \mathrm{~Hz}) \\ & \leq 4.35(20-87 \mathrm{~Hz}) \\ & \leq 6(20-120 \mathrm{~Hz}) \end{aligned}$ | 50 Hz <br> 87 Hz <br> 120 Hz |
| Motor with blower <br> Motor with integral fan (reduced torque) | $\begin{aligned} & \leq 10.0(5-50 \mathrm{~Hz}) \\ & \leq 17.4(5-87 \mathrm{~Hz}) \\ & \leq 24(5-120 \mathrm{~Hz}) \end{aligned}$ | $\begin{aligned} & 50 \mathrm{~Hz} \\ & 87 \mathrm{~Hz} \\ & 120 \mathrm{~Hz} \end{aligned}$ |

## Determine motor based on the rated data

|  |  |  | Check |  |
| :---: | :---: | :---: | :---: | :---: |
| Rated torque |  |  |  |  |
| Operating mode S1 | $M_{\text {rated }}$ | Nm |  | $\mathrm{M}_{\mathrm{N}} \geq \frac{\mathrm{M}_{\mathrm{L}, \max }}{\mathrm{~T}_{\mathrm{H}, \mathrm{Mot}} \times \mathrm{T}_{\mathrm{U}, \mathrm{Mot}}}$ |
| Operating mode S6 | $\mathrm{M}_{\text {rated }}$ | Nm |  | $M_{N} \geq \frac{M_{L, \max }}{2 \times T_{H, M o t} \times T_{U, M o t}}$ |
| Rated speed | $\mathrm{n}_{\text {rated }}$ | rpm | $n_{\text {rated }} \geq n_{L, \max }$ | $\frac{\mathrm{n}_{\mathrm{n}}}{\mathrm{~V}} \leq \mathrm{n}_{\mathrm{L}, \text { min }}$ |


|  |  |  | Note |  |
| :--- | :--- | :--- | :--- | :---: |
| Rated torque | $\mathrm{M}_{\text {rated }}$ | Nm | Rated motor data |  |
| Rated speed | $\mathrm{n}_{\text {rated }}$ | rpm |  |  |
| Rated point at |  | Hz | $\rightarrow$ setting range |  |
| Power factor | $\cos \varphi$ |  |  |  |
| Rated current | $\mathrm{I}_{\mathrm{N}, \mathrm{MOT}}$ | A |  |  |
| Rated power | $\mathrm{P}_{\text {rated }}$ | kW |  |  |
| Correction factor - site altitude | $\mathrm{T}_{\mathrm{H}, \mathrm{MOT}}$ |  | $\rightarrow$ Technical motor data |  |
| Correction factor - ambient temperature | $\mathrm{T}_{\mathrm{U}, \mathrm{MOT}}$ |  |  |  |
| Select motor |  |  |  |  |

Correction factors for the inverter

| Site altitude Amsl |  | H |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | [m] | $\leq 1000$ | $\leq 2000$ | $\leq 3000$ | $\leq 4000$ |
|  | $\mathrm{k}_{\mathrm{H}, \mathrm{INV}}$ |  | 1.00 | 0.95 | 0.90 | 0.85 |
| Temperature in the control cabinet |  | $\mathrm{T}_{\mathrm{U}}$ |  |  |  |  |
|  |  | [ ${ }^{\circ} \mathrm{C}$ ] | $\leq 40$ | $\leq 45$ | $\leq 50$ | $\leq 55$ |
| Switching frequency |  |  |  |  |  |  |
| 2 or 4 kHz | $\mathrm{k}_{\text {TU,INV }}$ |  | 1.00 | 1.00 | 0.875 | 0.750 |
| 8 or 16 kHz |  |  | 1.00 | 0.875 | 0.750 | 0.625 |
| Switching frequency with the "Light Duty" load characteristic |  |  |  |  |  |  |
| 2 or 4 kHz | $\mathrm{k}_{\text {Tu,INV }}$ |  | 1.00 | 0.875 | 0.750 | - |
| 8 or 16 kHz |  |  | - | - | - | - |

Determine the inverter based on the rated data

|  |  |  | Check |
| :--- | :--- | :--- | :--- |
| Output current |  |  |  |
| Continuous operation | $I_{\text {out }}$ | A | $I_{\text {out }} \geq I_{N, M o t} /\left(k_{H, I N V} \times \mathrm{k}_{\mathrm{TU}, \mathrm{INV}}\right)$ |
| Overcurrent operation cycle 15 s | $\mathrm{I}_{\text {out }}$ | A | $\mathrm{I}_{\text {out }} \geq \mathrm{I}_{\mathrm{N}, \mathrm{Mot}} \times 2 /\left(\mathrm{k}_{\mathrm{H}, \mathrm{INV}} \times \mathrm{k}_{\mathrm{TU}, \mathrm{INV}}\right)$ |
| Overcurrent operation cycle 180 s | $\mathrm{I}_{\text {out }}$ | A | $\mathrm{I}_{\text {out }} \geq \mathrm{I}_{\mathrm{N}, \mathrm{Mot}} \times 1.5 /\left(\mathrm{k}_{\mathrm{H}, \mathrm{INV}} \times \mathrm{k}_{\mathrm{TU}, \mathrm{INV}}\right)$ |

Determine the inverter based on the rated data for the "Light Duty" load characteristic

|  |  |  | Check |
| :---: | :---: | :---: | :---: |
| Output current |  |  |  |
| Continuous operation | ${ }_{\text {out }}$ | A | $\mathrm{I}_{\text {out }} \geq \mathrm{I}_{\mathrm{N}, \mathrm{Mot}} /\left(\mathrm{k}_{\mathrm{H}, \mathrm{INV}} \times \mathrm{k}_{\text {TU,INV }}\right)$ |
| Overcurrent operation cycle 15 s | ${ }^{\text {out }}$ | A | $\mathrm{I}_{\text {out }} \geq \mathrm{I}_{\mathrm{N}, \mathrm{Mot}} \times 1.65 /\left(\mathrm{k}_{\mathrm{H}, \mathrm{INV}} \times \mathrm{k}_{\text {TU,INV }}\right)$ |
| Overcurrent operation cycle 180 s | ${ }_{\text {out }}$ | A | $\mathrm{I}_{\text {out }} \geq \mathrm{I}_{\mathrm{N}, \mathrm{Mot}} \times 1.25 /\left(\mathrm{k}_{\mathrm{H}, \mathrm{INV}} \times \mathrm{k}_{\mathrm{TU}, \mathrm{INV}}\right)$ |

Check motor/inverter combination

|  |  |  | Calculation |
| :--- | :--- | :--- | :--- |
| Motor torque | M | Nm | $\mathrm{M}=\sqrt{\left(\frac{\left.\mathrm{I}_{\text {out,INV }}\right)^{2}}{\mathrm{~N}_{\mathrm{NOT}}}\right)^{2}-\left(1-\cos \varphi^{2}\right) \times \frac{\mathrm{M}_{\mathrm{N}}}{\cos \varphi}}$ |
|  |  |  |  |
| Inverter overload capacity |  | Check |  |

## Braking operation without additional measures

To decelerate small masses, the "DC injection brake DCB" function can be parameterised. DCinjection braking enables a quick deceleration of the drive to standstill without the need for an external brake resistor.

- A code can be used to select the braking current.
- The maximum braking torque to be realised by the DC braking current amounts to approx. $20 \ldots 30 \%$ of the rated motor torque. It is lower compared to braking action in generator mode with external brake resistor.
- Automatic DC-injection braking (Auto-DCB) improves the starting performance of the motor when the operation mode without speed feedback is used.


## Final configuration

Product extensions and accessories can be found here:

- Product extensions 124
- Accessories 띠 132


## Operation in motor and generator mode

The energy analysis differs between operation in motor mode and generator mode.
During operation in motor mode, the energy flows from the supplying mains via the inverter to the motor which converts electrical energy into mechanical energy (e. g. for lifting a load).

During operation in generator mode, the energy flows back from the motor to the inverter. The motor converts the mechanical energy into electrical energy - it acts as a generator (e. g. when lowering a load).
The drive brakes the load in a controlled manner.
The energy recovery causes a rise in the DC-bus voltage. If this voltage exceeds an upper limit, the output stage of the inverter will be blocked to prevent the device from being destroyed.
The drive coasts until the DC-bus voltage reaches the permissible value range again.

## Overcurrent operation

The inverters can be driven at higher amperages beyond the rated current if the duration of this overcurrent operation is time limited.

Two utilisation cycles of 15 s and 180 s are defined. Within these utilisation cycles, an overcurrent is possible for a certain time if afterwards an accordingly long recovery phase takes place.

Cycle 15 s
During this operation, the inverter may be loaded for 3 s with up to $200 \%$ of the rated current if afterwards a recovery time of 12 s with max. $75 \%$ of the rated current is observed. A cycle corresponds to 15 s .

## Cycle 180 s

During this operation, the inverter may be loaded for 60 s with up to $150 \%$ of the rated current if afterwards a recovery time of 120 s with max. $75 \%$ of the rated current is observed. A cycle corresponds to 180 s .

The monitoring of the device utilization (lxt) triggers an error if the utilization value exceeds a threshold of $100 \%$.

The maximum output currents correspond to the switching frequencies and the overload behaviour of the inverters are given in the rated data.
In case of rotating frequencies $<10 \mathrm{~Hz}$, the time-related overload behaviour may be reduced.

The graphics shows a cycle. The basic conditions given in the table (graphics field highlighted in grey) have to be complied with in order that the inverter will not be overloaded. Both cycles can be combined with each other.


| Cycle | Max. output current | Max. overload time | Max. output current during <br> the Recovery time | Min. recovery time |
| :---: | :---: | :---: | :---: | :---: |
|  | $\mathbf{A}$ | $\mathbf{T}_{1}$ | $\mathbf{B}$ | $\mathbf{T}_{2}$ |
| $\mathbf{s}$ | $\%$ | $\mathbf{s}$ | $\%$ | $\mathbf{s}$ |
| 15 | 200 | 3 | 75 | 12 |
| 180 | 150 | 60 | 75 | 120 |

## Control cabinet structure

## Control cabinet requirements

- Protection against electromagnetic interferences
- Compliance with the ambient conditions of the installed components


## Mounting plate requirements

- The mounting plate must be electrically conductive.
- Use zinc-coated mounting plates or mounting plates made of V2A.
- Varnished mounting plates are unsuitable, even if the varnish is removed from the contact surfaces.
- When using several mounting plates, make a conductive connection over a large surface (e. g. using grounding strips).


## Arrangement of components

- Division into power and control areas


Fig. 1: Example for the ideal arrangement of components in the control cabinet

## Cables

Requirements

- The cables used must correspond to the requirements at the location (e. g. EN 60204-1, UL).
- The cable cross-section must be dimensioned for the assigned fusing. Observe national and regional regulations.
- You must observe the regulations for minimum cross-sections of PE conductors. The crosssection of the PE conductor must be at least as large as the cross-section of the power connections.
Installation inside the control cabinet
- Always install cables close to the mounting plate (reference potential), as freely suspended cables act like antennas.
- Use separated cable ducts for motor cables and control cables. Do not mix up different cable types in one cable duct.
- Route cables so that they are straight-lined to the terminals (do not form cable bundles).
- Minimize coupling capacities and coupling inductances by avoiding unnecessary cable lengths and reserve loops.
- Short-circuit unused cores to the reference potential.
- Install the cables of a 24 V DC supply (positive and negative cable) close to each other or twisted over the entire length to avoid loops.
- Before leaving the control cabinet, connect the shield of the fieldbus cable to the mounting plate in accordance with EMC requirements.

Installation outside the control cabinet

- In the case of greater cable lengths, a greater cable distance between the cables is required.
- In the case of parallel routing (cable trays) of cables with different types of signals, the degree of interference can be minimized by using a metallic cable separator or isolated cable ducts.


## Earthing concept

- Set up the earthing system with a star topology.
- Connect all components (inverters, filters, chokes) to a central earthing point (PE rail).
- Comply with the corresponding minimum cross-sections of the cables.
- When using several mounting plates, make a conductive connection over a large surface (e. g. using grounding strips).


## Mechanical installation

## Important notes

## Measures for cooling during operation

- Ensure unimpeded ventilation of cooling air and outlet of exhaust air.
- If the cooling air is polluted (fluff, (conductive) dust, soot, grease, aggressive gases), take adequate countermeasures.
- Install filters.
- Arrange for regular cleaning of the filters.
- Use air conditioners with hermetic separation of the inside and outside air of the control cabinet.
- If required, implement a separate air guide.


## Mounting of the suppliers and axes

- Standard mounting: Mount the supplier to the left of the axis system.

For mounting to the right of the axis system, the swivel hooks for the busbar system must be relocated.

- The DC infeed adapter i700 E70AZEVE001 can be connected to the left or right side of suppliers or axes.


## Preparation

Further data and information for mechanical mounting:

- Control cabinet structure 32
- Dimensions 113


## Mounting position

- Vertical alignment - all mains connections are at the top and the motor connections at the bottom.


## Installation clearances

- Maintain the specified installation clearances above and below to the other installations.
- Several devices of the same series can be lined up directly, regardless of the device size. No installation clearance is required between the devices.


## Mechanical installation

- The mounting location and material must ensure a durable mechanical connection.
- Do not mount onto DIN rails!
- In case of continuous vibrations or shocks use vibration dampers. If non-conductive vibration dampers are used, an EMC-compliant design must be ensured.

How to mount the inverters onto the mounting plate.
Preconditions:

- Mounting plate with conductive surface

Required:

- Tool for drilling and thread cutting
- Screwdriver
- Screw and washer assemblies or hexagon socket screws with washers.

1. Prepare mounting plate with corresponding threaded holes.
2. Fit screws and washers (if applicable).
3. Do not yet tighten the screws.
4. Mount the inverter on the prepared mounting plate via keyhole suspension.
5. Only tighten the screws hand-tight.
6. Pre-assemble further units if necessary.
7. Adjust the units.
8. Screw the units onto the mounting plate.

The inverter and any other units are mounted on the mounting plate. You can begin with the wiring.

Screw and washer assemblies or hexagon socket screws with washers are recommended..
M5 x $\geq 10 \mathrm{~mm}$ for devices up to and including 2.2 kW
M5 $x \geq 12 \mathrm{~mm}$ for devices up to and including 11 kW

## Electrical installation

## Important notes

## © DANGER!

Dangerous electrical voltage
During operation and up to 20 minutes after power-off, hazardous electrical voltages may be present at the connections of the product.
The leakage current against earth (PE) is $>3.5 \mathrm{~mA} \mathrm{AC}$ or $>10 \mathrm{~mA} \mathrm{DC}$.
Possible consequences: Death or serious injury from electric shock
Protective measures

- Any work on the product must only be carried out in a deenergized state.
- Check that no voltage is present!
- After switching off the mains voltage, observe the signs on the product.
- After switching off, wait until the drive comes to a standstill.
- Implement the measures required by EN 61800-5-1 or EN 60204-1, i.e. fixed installation and standard-compliant PE connection.


## \. DANGER!

Use of the inverter on a phase earthed mains with a rated mains voltage $\geq 400 \mathrm{~V}$
The protection against accidental contact is not ensured without external measures.

- If protection against accidental contact according to EN 61800-5-1 is required for the control terminals of the inverters and the connections of the plugged device modules, ...
- an additional basic insulation has to be provided.
- the components to be connected have to come with a second basic insulation.


## WARNING!

## Dangerous electrical voltage

Device error causes an overvoltage in the system.

- For a voltage supply with DC $24 \mathrm{~V}( \pm 20 \%$ ), use only a safely separated power supply unit according to the valid SELV/PELV requirements.


## NOTICE

No protection against excessively high mains voltage
The mains input is not fused internally.
Possible consequences: Destruction of the product in the event of excessively high mains voltage.

- Take note of the maximum permissible mains voltage.
- On the mains supply side, use fuses to adequately protect the product against mains fluctuations and voltage peaks.


## NOTICE

Overvoltage at devices with 230-V mains connection
An impermissible overvoltage may occur if the central supply of the N conductor is interrupted if the devices are connected to a TN three-phase system.

Possible consequences: Destruction of the device - Provide for the use of isolating transformers.

## NOTICE

The product contains electrostatic sensitive devices.
Possible consequences: Destruction of the device
Before working in the connection area, the personnel must be free of electrostatic charge.

## NOTICE

Use of mains filters and RFI filters in IT systems
Mains filters and RFI filters from Lenze contain components that are interconnected against PE.

Possible consequences: The filters may be destroyed when an earth fault occurs.
Possible consequences: Monitoring of the IT system may be triggered.

- Do not use mains filters and RFI filters from Lenze in IT systems.
- Before using the inverter in the IT system, remove the IT screws.


## NOTICE

Overvoltage at components
In case of an earth fault in IT systems, intolerable overvoltages may occur in the plant.
Possible consequences: Destruction of the device.
Before using the inverter in the IT system, the contact screws must be removed.
Positions and number of the contact screws depend on the device.
When implementing machines and systems for the use in the UL/CSA scope, you
have to observe the relevant special notes.
These notes are marked with "UL marking".

| You have to install the devices into housings (e. g. control cabinets) to comply |
| :--- |
| with valid regulations. |
| Stickers with warning notes must be displayed prominently and close to the |
| device. |

## Electrical isolation

Ensure a trouble-free operation:
Carry out the total wiring so that the separation of the separate potential areas is preserved.

Preparation
Installation of shield connection sheet for motor cable 0.25 kW to 4 kW (optional accessories)

(2)

(3)


iTogether with the inverter, the shield connection sheet is screwed onto the mounting plate.

Installation of shield connection sheet for motor cable 5.5 kW (optional accessories)


Installation of shield connection sheet for motor cable 7.5 kW to 11 kW (optional accessories)

(3)


## Further data and information

[^0]
## EMC-compliant installation

The drive system (inverter and drive) only complies with the directive 2014/30/EU: EMC Directive [UKCA: S.I. 2016/1091 - The Electromagnetic Compatibility Regulations 2016] if it is installed according to the guidelines for CE-typical drive systems.

These guidelines should also be followed in installations requiring FCC Part 15 or ICES 001 compliance.

The structure in the control cabinet must support the EMC-compliant installation with shielded motor cables.

- Please use sufficiently conductive shield connections.
- Connect the housing with shielding effect to the grounded mounting plate with a surface as large as possible, e.g. of inverters and RFI filters.
- Use central grounding points.

Matching accessories makes effective shielding easier.

- Motor shield plates as alternative shield connections for the motor cable
- Shield clips/shield clamps
- Metallic cable ties

The example below shows the effective wiring:

A Shield connection for control cables
B Control cable
C Mounting plate with conductive surface
D Shield connection for motor cable (alternatively: shield connection on an optional motor shield plate)
E Motor cable with low capacity

## Mains connection

- Inverters, mains chokes, or mains filters may be connected to the mains via unshielded single cores or unshielded cables.
- Cable between line filter and inverter:

|  | Cable length |  |
| :--- | :---: | :---: |
|  | $\leq \mathbf{3 0 0} \mathbf{~ m m}$ | $\mathbf{3 0 0} \mathbf{~ m m ~}$ |
|  | unshielded twisted option | always shielded |

- In DC-bus operation or DC supply, use shielded cables.


## External RFI filters

In order to meet the EMC requirements according to EN IEC 61800-3,

- an external RFI filter according to IEC EN 60939 must be used with certain inverters and
- one or both screws marked "IT" on the product must be removed when using certain external RFI filters.

More information can be found under: Technical data $\square 57$

## Motor cable

EMC-compliant installation must be carried out with shielded low-capacitance motor cables.

## Capacitance per unit length

- Cable cross-section $\leq 2.5 \mathrm{~mm}^{2}$ ( $\geq$ AWG 14): C-core-core/C-core-shield $<75 / 150 \mathrm{pF} / \mathrm{m}$
- Cable cross-section $\leq 4 \mathrm{~mm}^{2}$ ( $\geq$ AWG 12): C-core-core/C-core-shield $<150 / 300 \mathrm{pF} / \mathrm{m}$


## Braid

- Only use motor cables with braids made of tinned or nickel-plated copper.
- Shields made of steel braids are not suitable.
- The overlap rate of the braid must be at least $70 \%$ with an overlap angle of $90^{\circ}$.


## Shield connection

- Apply shielding over a large area.
- Shield mounting with metal cable tie or conductive clip.
- The following is suitable for connecting the shield:
- The mounting plate
- A central grounding rail
- A shield plate, if necessary, optional •Shield mounting kit $\amalg 140$


## Cable for motor temperature monitoring

- Shield the cable for motor temperature monitoring (PTC or thermal contact) and install it separately from the motor cable.
- In Lenze system cables, the cable for the brake control is integrated into the motor cable. If this cable is not required, it can also be used to connect the motor temperature monitoring up to a length of 50 m .


## Measures on the motor

- Connect the shield with PE over a large area at the terminal box of the motor, e.g. via a metallic EMC cable gland.
- For motors with plug connectors, the large-area shield connection is ensured via the plug connection.


## Further supporting measures

- Route the motor cable separately from the mains cables and control cables.
- Lay the motor cable so that it only crosses mains cables and control cables at right angles.
- Do not disconnect the motor cable.
- If the motor cable must be disconnected (e.g. by chokes, contactors, or terminals):
- Install the shield of the motor cable directly before and behind the point of separation to the mounting plate with a large surface.
- The unshielded cable ends must not be longer than 100 mm .
- Mount the separating component at least 100 mm away from other components.


## Control cables

- Install the cables so that no induction-sensitive loops arise.
- Distance of shield connections of control cables to shield connections of motor cables and DC cables:
- At least 50 mm
- Control cables for analog signals:
- Must always be shielded
- Connect the shield on one side of the inverter
- Control cables for digital signals:

|  | Cable length |  |  |
| :--- | :---: | :---: | :---: |
|  | <ca. $\mathbf{5} \mathbf{~ m}$ | ca. $\mathbf{5 ~ m} \ldots \mathbf{c a . 3 0 ~ m}$ | $>\mathbf{c a . 3 0 \mathbf { m }}$ |
|  | unshielded option | unshielded twisted option | always shielded <br> connected on both sides |

## Fieldbus cables, networks

Please observe the following recommendations for trouble-free operation, especially in the event of Ethernet-based networks.

- Cables and wiring must meet the specifications and requirements of the network being used to allow reliable operation of the network in typical installations. In this context, also observe the recommendations for action of the respective user organization.
- Lay network cables separately from power cables. Maintain as large a distance as possible to the motor cables which are subject to interference.
- To avoid compensating currents via the shielding of the network cable, install an independent, low-resistance equipotential bonding over the shortest possible distance parallel to the network cable. This applies in particular to long cables.
- Observe bending radii according to manufacturer information. Minimum bending radii of 10 x cable diameter or 20 x diameter for frequent manipulation of the cables are standard.
- Fix longer cables 30 cm after the connection point.
- Before leaving the control cabinet, connect the shield of the network cable with the equipotential bonding system (e. g. mounting plate) on a large surface.


## Patch cable/CAT5 cables:

- Cables must comply with CAT5 and be suitable for $\geq 10 \mathrm{Mbps}$.
- CAT5 cables according to specification establish the shield connection via the RJ45 plug connection. Additional shield connections are not required.
- Patch cables of 25 cm length are suitable for the network connection of inverters $\leq 4 \mathrm{~kW}$ installed side by side. When wiring from right to left, a sufficient bending radius can be maintained.
- Only certified, tested and fully assembled patch cables from well-known manufacturers are recommended.

RJ45 plug connections:

- RJ45 plug connections only function properly if they are not subjected to mechanical stress or lateral forces.
- For all communication modules of the i-series, the connection of the cable shielding at the RJ45 sockets is carried out as follows:
- At the first RJ45 socket, the shielding is directly connected to functional earth (FE).
- At the second RJ45 socket, the shielding is connected to functional earth (FE) via an RC element.
This measure prevents potential equalization currents and the resulting interference effects (see also IEC 61158-2, section 11.8.7).
Note: High-frequency interference is dissipated via the low-impedance capacitor to functional earth (FE), but for low-frequency signals this system has a high loop impedance. Measuring systems that use low impedance test signals therefore indicate too high impedance values for the shielding at the second RJ45 socket


## Detecting and eliminating EMC interferences

| Trouble | Cause | Remedy |
| :---: | :---: | :---: |
| Interferences of analog setpoints of your own or other devices and measuring systems | Unshielded motor cable has been used | Use shielded motor cable |
|  | Shield contact is not extensive enough | Carry out optimal shielding as specified |
|  | Shield of the motor cable is interrupted, e. g. by terminal strips, switches etc. | - Separate components from other component parts with a minimum distance of 100 mm <br> - Use motor chokes or motor filters |
|  | Additional unshielded cables inside the motor cable have been installed, e. g. for motor temperature monitoring | Install and shield additional cables separately |
|  | Too long and unshielded cable ends of the motor cable | Shorten unshielded cable ends to max. 40 mm |
| Conducted interference level is exceeded on the supply side | Terminal strips for the motor cable are directly located next to the supply terminals | Spatially separate the terminal strips for the motor cable from mains terminals and other control terminals with a minimum distance of 100 mm |
|  | Mounting plate varnished | Optimize PE connection: <br> - Remove varnish <br> - Use zinc-coated mounting plate |
|  | HF short circuit | Check cable routing |
| Malfunctions of the fieldbus communication or exceedance of the permissible interference levels | Shield contact is not extensive enough | Before leaving the control cabinet, connect the shield of the fieldbus cable with the equipotential bonding system (e. g. mounting plate) on a large surface. |
|  | Shield connection on the inverter only |  |
|  | Shield of fieldbus cable connected on one side only | Shield connection on both sides |

## Connection according to UL

## Important notes

## WARNING!

- UL marking
- The integral solid state short circuit protection included in the inverter does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electrical Code / Canadian Electrical Code and any additional local codes.


## - Marquage UL

- La protection statique intégrée contre les courts-circuits n’offre pas la même protection que le dispositif de protection du circuit de dérivation. Un tel dispositif doit être fourni, conformément au National Electrical Code / Canadian Electrical Code et aux autres dispositions applicables au niveau local.


## \. WARNING!

- UL marking
- Use $75^{\circ} \mathrm{C}$ copper wire only, except for control circuits.
- Marquage UL
- Utiliser exclusivement des conducteurs en cuivre $75^{\circ} \mathrm{C}$, sauf pour la partie commande.


## WARNING!

## UL marking

- Suitable for motor group installation or use on a circuit capable of delivering not more than the RMS symmetrical amperes (SCCR) of the drive at its rated voltage.
Approved fusing is specified in SCCR tables below.
- Marquage UL
- Convient pour l'utilisation sur une installation avec un groupe de moteurs ou sur un circuit capable de fournir au maximum une valeur de courant efficace symétrique en ampères à la tension assignée de l'appareil.
Les dispositifs de protection adaptés sont spécifiés dans les SCCR tableaux suivants.


## NOTICE

- UL marking
- The opening of the Branch Circuit Protective Device may be an indication that a fault has been interrupted. To reduce the risk of fire or electric shock, current carrying parts and other components of the controller should be examined and replaced if damaged. If burnout of the current element of an overload relay occurs, the complete overload relay must be replaced.


## - Marquage UL

- Le déclenchement du dispositif de protection du circuit de dérivation peut être dû à une coupure qui résulte d'un courant de défault. Pour limiter le risque d'incendie ou de choc électrique, examiner les pièces porteuses de courant et les autres éléments du contrôleur et les remplacer s'ils sont endommagés. En cas de grillage de l'élément traversé par le courant dans un relais de surcharge, le relais tout entier doit être remplacé.


## NOTICE

- UL marking
- Internal overload protection rated for 125 \% of the rated FLA.
- Marquage UL
- Protection contre les surcharges conçue pour se déclencher à 125 \% de l'intensité assignée à pleine charge.


## Fusing data

## Branch Circuit Protection (BCP)

## Short Circuit Current Ratings (SCCR) with Standard Fuses or Circuit Breaker

(Tested per UL61800-5-1, reference UL file E132659)
These devices are suitable for motor group installation when used with Standard Fuses or Circuit Breaker. For single motor installation, if the fuse value indicated is higher than $400 \%$ of the motor current (FLA), the fuse value has to be calculated. If the value of the fuse is below two standard ratings, the nearest standard ratings less than the calculated value shall apply.

| Inverter |  |  | Standard Fuses (UL248) |  |  | Circuit Breaker (UL489) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Mains | Rated power |  | Max. SCCR | Max. rated current | Class | Max. SCCR | Max. rated current | Min. cabinet dimensions |  |
|  | kW | hp | kA | A |  | kA | A | $\mathrm{m}^{3}$ | $\mathrm{ft}^{3}$ |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 0.25 | 0.33 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 0.37 | 0.5 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 0.55 | 0.75 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 0.75 | 1 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 1.1 | 1.5 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 1.5 | 2 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| 230 V, 1-ph | 2.2 | 3 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1 / 3-\mathrm{ph}$ | 0.25 | 0.33 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| 230 V, 1/3-ph | 0.37 | 0.5 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1 / 3-\mathrm{ph}$ | 0.55 | 0.75 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1 / 3-\mathrm{ph}$ | 0.75 | 1 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1 / 3-\mathrm{ph}$ | 1.1 | 1.5 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 1 / 3-\mathrm{ph}$ | 1.5 | 2 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| 230 V, 1/3-ph | 2.2 | 3 | 65 | 30 | CC, CF, J, T | 65 | 30 | 0.042 | 1.48 |
| $230 \mathrm{~V}, 3-\mathrm{ph}$ | 4 | 5 | 100 | 40 | CC, CF, J, T | 65 | 40 | 0.042 | 1.48 |
| 230 V, 3-ph | 5.5 | 7.5 | 100 | 40 | CC, CF, J, T | 65 | 40 | 0.042 | 1.48 |
| 480 V, 3-ph | 0.37 | 0.5 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| 480 V, 3-ph | 0.55 | 0.75 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| 480 V, 3-ph | 0.75 | 1 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| 480 V, 3-ph | 1.1 | 1.5 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| 480 V, 3-ph | 1.5 | 2 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| 480 V, 3-ph | 2.2 | 3 | 65 | 15 | CC, CF, J, T | 65 | 15 | 0.042 | 1.48 |
| 480 V, 3-ph | 3 | 4 | 65 | 35 | CC, CF, J, T | 65 | 25 | 0.042 | 1.48 |
| 480 V, 3-ph | 4 | 5 | 65 | 35 | CC, CF, J, T | 65 | 25 | 0.042 | 1.48 |
| 480 V, 3-ph | 5.5 | 7.5 | 65 | 30 | CC, CF, J, T | 65 | 25 | 0.042 | 1.48 |
| 480 V, 3-ph | 7.5 | 10 | 65 | 40 | CC, CF, J, T | 65 | 40 | 0.042 | 1.48 |
| 480 V, 3-ph | 11 | 15 | 65 | 40 | CC, CF, J, T | 65 | 40 | 0.042 | 1.48 |

## Short Circuit Current Ratings (SCCR) with Semiconductor Fuses

(Tested per UL61800-5-1, reference UL file E132659)
These devices are suitable for standard installation when used with Semiconductor Fuses. For single motor installation, if the fuse value indicated is higher than $400 \%$ of the motor current (FLA), the fuse value has to be calculated. If the value of the fuse is below two standard ratings, the nearest standard ratings less than the calculated value shall apply.

| Inverter |  |  | Alternate Fuse (Semiconductor Fuse) |  |
| :---: | :---: | :---: | :---: | :---: |
| Mains | Rated power |  | Max. SCCR | Max. rated current |
|  | kW | hp | kA | A |
| $230 \mathrm{~V}, 1$-ph | 0.25 | 0.33 | 100 | 16 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 0.37 | 0.5 | 100 | 16 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 0.55 | 0.75 | 100 | 40 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 0.75 | 1 | 100 | 40 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 1.1 | 1.5 | 100 | 50 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 1.5 | 2 | 100 | 50 |
| $230 \mathrm{~V}, 1-\mathrm{ph}$ | 2.2 | 3 | 100 | 50 |
| 230 V, 1/3-ph | 0.25 | 0.33 | 100 | 16 |
| 230 V, 1/3-ph | 0.37 | 0.5 | 100 | 16 |
| 230 V, 1/3-ph | 0.55 | 0.75 | 100 | 40 |
| 230 V, 1/3-ph | 0.75 | 1 | 100 | 40 |
| 230 V, 1/3-ph | 1.1 | 1.5 | 100 | 40 |
| 230 V, 1/3-ph | 1.5 | 2 | 100 | 40 |
| 230 V, 1/3-ph | 2.2 | 3 | 100 | 40 |
| 230 V, 3-ph | 4 | 5 | 100 | 50 |
| 230 V, 3-ph | 5.5 | 7.5 | 100 | 50 |
| 480 V, 3-ph | 0.37 | 0.5 | 100 | 6 |
| 480 V, 3-ph | 0.55 | 0.75 | 100 | 16 |
| 480 V, 3-ph | 0.75 | 1 | 100 | 16 |
| 480 V, 3-ph | 1.1 | 1.5 | 100 | 16 |
| 480 V, 3-ph | 1.5 | 2 | 100 | 16 |
| 480 V, 3-ph | 2.2 | 3 | 100 | 20 |
| 480 V, 3-ph | 3 | 4 | 100 | 40 |
| 480 V, 3-ph | 4 | 5 | 100 | 40 |
| 480 V, 3-ph | 5.5 | 7.5 | 100 | 50 |
| $480 \mathrm{~V}, 3-\mathrm{ph}$ | 7.5 | 10 | 100 | 63 |
| 480 V, 3-ph | 11 | 15 | 100 | 80 |

Electrical installation
Connection according to UL
Fusing data

Approved manufacturers for BCP fusing

| Manufacturer | Max. rated current | Designation |
| :---: | :---: | :---: |
|  | A |  |
| Eaton/Bussmann | 6 | FWP-6A14F |
|  | 16 | FWP-15B, FWP-15A14F |
|  |  | 170M1309, 170M1359, 170M1409 |
|  | 20 | FWP-20B, FWP-20A14F |
|  |  | 170M1310, 170M1360, 170M1410 |
|  | 40 | FWP-40A22F, FWP-40B, FWP-40A14F, FWP-40A |
|  |  | 170M1313, 170M1363, 170M1413 |
|  | 50 | FWP-50A22F, FWP-50B, FWP-50A14F, FWP-50A |
|  |  | 170M1314, 170M1364, 170M1414 |
|  | 63 | FWP-63A22F, FWP-60B, FWP-60A |
|  |  | 170M1315, 170M1365, 170M1415 |
|  | 80 | FWP-80A22F, FWP-80B, FWP-80A |
|  |  | 170M1316, 170M1366, 170M1416 |
| Littelfuse | 40 | L70QS040 |
|  | 50 | L70QS050 |
|  | 63 | L70QS060 |
|  | 80 | L70QS080 |
| Mersen | 6 | A70QS6-14F, A70QS6-14FI |
|  | 16 | A60Q15-2 |
|  |  | A70QS16-14F, A70QS16-14FI, A70QS15-22F, A70QS15-22FI |
|  | 20 | A70QS20-14F, A70QS20-14FI, A70QS20-22F, A70QS20-22FI |
|  | 40 | A70QS40-14F, A70QS40-14FI, A70QS40-22F, A70QS40-22FI, A70QS40-4 |
|  | 50 | A70QS50-22F, A70QS50-14F, A70QS50-14FI, A70QS50-22FI, A70QS50-4 |
|  | 63 | A70QS63-22F, A70QS63-22FI, A70QS60-4 |
|  | 80 | A70QS80-22F, A70QS80-4, A70QS80-22FI |
| SIBA | 16 | 5020106.16, 5020206.16 |
|  | 20 | 5020106.20, 5020206.20 |
|  | 40 | 5020106.40, 5020206.40 |
|  | 50 | 5020106.50, 5020206.50 |
|  | 63 | 2029220.63 |
|  |  | 5020106.63, 5020206.63 |
|  | 80 | 2029220.80 |

## Mains connection

The following should be considered for the mains connection of inverters:
Single inverters are connected directly to the AC system or via upstream filters. RFI filters are already integrated in many inverters. Depending on the requirements, mains chokes or mains filters can be used.
This enables the energy exchange in phases with operation in generator and motor mode of several drives in the network.

The technical data informs about the possible applications in the given groups. In the dimensioning, data and further notes have to be observed.

## 1-phase mains connection 230/240 V

The connection plan is valid for the inverters i510-Cxxx/230-1.


Fig. 2: Wiring example
S1 Start/Stop

Q1
Mains contactor
Fx Fuses
--- Dashed line = options

The connection plan is valid for the inverters i510-Cxxx/230-2.


Inverters i510-Cxxx/230-2 do not have an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.


CAN open/Modbus


Fig. 3: Wiring example
S1 Start/Stop
Fx Fuses

Q1 Mains contactor
--- Dashed line = options

Mains connection
3 -phase mains connection $230 / 240 \mathrm{~V}$

3-phase mains connection 230/240 V
The connection plan is valid for the inverters $\mathrm{i} 510-\mathrm{Cxxx}^{2} / 230-3$ and $\mathrm{i} 510-\mathrm{Cxxx}^{2} / 230-2$.


Fig. 4: Wiring example
S1 Start/Stop
Fx Fuses

Q1 Mains contactor
--- Dashed line = options

3-phase mains connection 400 V
The connection plan is valid for the inverters i510-Cxxx/400-3.


Fig. 5: Wiring example
S1 Start/Stop
Fx Fuses
$\begin{array}{ll}\text { Q1 } & \text { Mains contactor } \\ \text {--- } & \text { Dashed line = options }\end{array}$

## Electrical installation

Mains connection
3-phase mains connection 480 V

3-phase mains connection 480 V
The connection plan is valid for the inverters i510-Cxxx/400-3.


Fig. 6: Wiring example
S1 Start/Stop
Fx Fuses

Q1
Mains contactor
--- Dashed line = options

## Motor connection

## Motor cable lengths

- The rated data for the motor cable length must be observed.
- Keep the motor cable as short as possible as this has a positive effect on the drive behaviour and the EMC.
- Several motors connected to an inverter form a group drive.

In case of group drives, the resulting motor cable length $I_{\text {res }}$ is relevant:
$I_{\text {res }}[m]=\left(I_{1}+I_{2}+I_{3} \ldots I_{\mathrm{i}}\right) \cdot \mathrm{Vi}$
$I_{\text {res }} \quad$ Resulting length of the motor cables
$I_{x} \quad$ Length of the single motor cable
i Number of the single motor cables

## Switching in the motor cable

Switching on the motor side of the inverter is permissible:
For safety shutdown (emergency stop).
In case several motors are driven by one inverter (only in V/f operating mode).
Please note the following:
The switching elements on the motor side must be dimensioned for with the maximum occurring load.

## Connection to the IT system

## NOTICE

Internal components have earth/ground potential
Possible consequence: The monitoring devices of the IT system will be triggered.

- Upstream an isolation transformer.
- Before connection to an IT system be absolutely sure to remove the screws labeled with "IT" on the product.
I51AE125x, I51AE137x

I51AE240C, I51AE255x, I51BE275F, I51BE311F


## Control connections



In case of long cables and/or high interference the effect of the shielding can be improved. To do this, connect the shield of cables for the analog inputs and outputs at one end of the cable via a capacitor with PE potential (e. g. $10 \mathrm{nF} /$ 250 V).

| Connection description |  |  | Control terminals | Relay output |
| :--- | :---: | :--- | :---: | :---: |
| Connection |  |  | X3 | X9 |
| Connection type |  | Non-pluggable | Pluggable |  |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 1.5 | 1.5 |
| Max. Cable cross-section |  | AWG | 16 | 14 |
| Min. Cable cross-section |  | $\mathrm{mm}^{2}$ | 0.5 | 0.5 |
| Min. Cable cross-section |  | AWG | 22 | 22 |
| Stripping length | mm | 9 | 6 |  |
| Stripping length | in | 0.35 | 0.2 |  |
| Required tool |  |  |  |  |

## Electrical installation

Networks
CANopen/Modbus

## Networks



When planning networks, consider the recommendations listed in the chapter "EMC-compliant installation" for low-interference operation, especially of Ethernet-based networks.

EMC-compliant installation $\rightarrow$ Fieldbus cables, networks $\amalg 41$

## CANopen/Modbus



The network must be terminated with a $120 \Omega$ resistor at the physically first and last node.
Connect resistor to terminals $\mathrm{CH} / \mathrm{TB}$ and $\mathrm{CL} / \mathrm{TA}$.

## Typical topologies



| Connection description |  |  |  |
| :--- | :--- | :--- | :--- |
| Connection |  |  | CANopen/Modbus |
| Connection type |  |  | X216 |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | Pluggable |
| Max. Cable cross-section |  | AWG | 2.5 |
| Stripping length |  | mm | 12 |
| Stripping length |  | in | 10 |
| Required tool |  |  | 0.39 |

## Basic network settings

1. Select network CANopen or Modbus using the switch on the front of the inverter.

2. Set node address and baud rate via the corresponding parameters.

## Technical data

## Standards and operating conditions

## Conformities and approvals

| Conformities |  |  |
| :---: | :---: | :---: |
| CE | 2009/125/EC | Ecodesign Directive |
|  | 2011/65/EU | RoHS Directive |
|  | 2014/30/EU | EMC Directive (reference: CE-typical drive system) |
|  | 2014/35/EU | Low-Voltage Directive |
| EAC | TP TC 020/2011 | Eurasian conformity: Electromagnetic compatibility of technical means |
|  | TR TC 004/2011 | Eurasian conformity: Safety of low voltage equipment |
| UKCA | S.I. 2008/1597 | The Supply of Machinery (Safety) Regulations 2008 |
|  | S.I. 2012/3032 | The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012 |
|  | S.I. 2016/1091 | The Electromagnetic Compatibility Regulations 2016 |
|  | S.I. 2021/745 | The Ecodesign for Energy-Related Products and Energy Information Regulations 2021 |
| Approvals |  |  |
| UL | UL 61800-5-1 | File No. E132659 |
|  |  | For USA and Canada (requirements of the CSA 22.2 No. 274) |

## Protection of persons and device protection

| Degree of protection |  |  | Data applies to operationally ready mounted state and not in wire range of terminals |
| :---: | :---: | :---: | :---: |
| EN | EN IEC 60529 | IP20 | In the connection area of mains and motor partly IP10 |
| NEMA | NEMA 250 | Type 1 | Protection against accidental contact only |
| Insulation resistance |  |  |  |
| Overvoltage category | EN IEC 61800-5-1 | II | >2000 m amsl |
|  |  | III | 0 ... 2000 m amsl |
| Isolation of control circuits |  |  |  |
|  | EN IEC 61800-5-1 | Safe mains isolation | Double/reinforced insulation |
| Leakage current |  |  |  |
| AC | EN IEC 61800-5-1 | $>3.5 \mathrm{~mA}$ | Observe regulations and safety instructions! |
| DC |  | $>10 \mathrm{~mA}$ |  |
| Starting current |  |  |  |
|  |  | $\leq 3 \times$ rated mains current |  |
| Protective measures |  |  |  |
| Earth fault strength |  |  | Earth-fault protected depending on operating status |
| Motor stalling protection |  |  |  |
| Short-circuit strength |  |  |  |
| Overvoltage resistance |  |  |  |
| Motor overtemperature |  |  | $1^{2} \mathrm{xt}$ monitoring |

## Technical data

Standards and operating conditions
EMC data

EMC data

| Operation on public supply systems |  |  | The machine or system manufacturer is responsible for |
| :---: | :---: | :---: | :---: |
| <1 kW | EN IEC 61000-3-2 | With mains choke |  |
| $>1$ kW, mains current $\leq 16$ A |  | No additional measures |  |
| $\text { Mains current > } 16 \text { A } \ldots \leq 75$ A | $\begin{array}{\|l\|} \hline \text { EN IEC } \\ 61000-3-12 \end{array}$ | With mains choke or mains filter | When designed for rated power. |
| Noise emission |  |  |  |
| Category C2 | EN IEC 61800-3 |  | see rated data |
| Category C3 |  |  |  |
| Noise immunity |  |  |  |
|  | EN IEC 61800-3 | Requirements fulfilled |  |

## Motor connection

| Requirements for the shielded motor cable |  |  |  |
| :---: | :---: | :---: | :---: |
| Capacitance per unit length |  | < 150/300 pF/m | $\geq 4 \mathrm{~mm}^{2} /$ AWG 12 |
|  |  | < 75/150 pF/m | $\leq 2.5 \mathrm{~mm}^{2} /$ AWG 14 |
| Electric strength |  | $\mathrm{Uo} / \mathrm{U}=0.6 / 1.0 \mathrm{kV}$ | $\mathrm{U}=$ r.m.s. value from external conductor to external conductor |
|  |  |  | Uo = r.m.s. value external conductor to PE |
|  | UL | $\mathrm{U} \geq 600 \mathrm{~V}$ | $\mathrm{U}=$ r.m.s. value from external conductor to external conductor |

## Environmental conditions

| Energy efficiency |  |  |  |
| :---: | :---: | :---: | :---: |
| High Efficiency | EN IEC 61800-9-2 | Class IE2 |  |
| Climate |  |  |  |
| Storage | $\begin{array}{\|l\|} \hline \text { EN } \\ \text { 60721-3-1:1997 } \end{array}$ | $1 \mathrm{~K} 3\left(-25 \ldots+60{ }^{\circ} \mathrm{C}\right)$ |  |
| Transport | $\begin{array}{\|l\|} \hline \text { EN } \\ 60721-3-2: 1997 \end{array}$ | $2 \mathrm{~K} 3\left(-25 \ldots+70{ }^{\circ} \mathrm{C}\right)$ |  |
| Operation | EN <br> 60721-3-3:1995 + <br> A2:1997 | $3 \mathrm{~K} 3\left(-10 \ldots+60{ }^{\circ} \mathrm{C}\right)$ | Operation at a switching frequency of 2 or 4 kHz : Above $+45^{\circ} \mathrm{C}$ : reduce rated output current by $2.5 \% /{ }^{\circ} \mathrm{C}$ |
|  |  |  | Operation at a switching frequency of 8 or 16 kHz : Above $+40^{\circ} \mathrm{C}$ : reduce rated output current by $2.5 \% /{ }^{\circ} \mathrm{C}$ |
|  |  |  | relative humidity <95\%, condensation not permissible |
|  |  | 3C3 | For chemically active substances |
|  |  | 352 | For mechanically active substances |
| Site altitude |  |  |  |
| 0 ... 1000 m amsl |  |  | Without current derating |
| 1000 ... 4000 m amsl |  |  | Reduce rated output current by 5 \%/1000 m |
| Pollution |  |  |  |
|  | EN IEC 61800-5-1 | Degree of pollution 2 |  |
|  | UL 61800-5-1 |  |  |
| Vibration resistance |  |  |  |
| Transport | $\begin{array}{\|l\|} \hline \text { EN } \\ 60721-3-2: 1997 \end{array}$ | 2M2 (sine, shock) | In original packaging |
| Operation | DNV-CG-0339 | Amplitude 1 mm | 5 ... 13.2 Hz |
|  |  | Acceleration resistant up to 0.7 $\mathrm{g}$ | 13.2 ... 100 Hz |
|  | EN IEC 61800-5-1 | Amplitude 0.075 mm | $10 \ldots 57 \mathrm{~Hz}$ |
|  |  | Acceleration resistant up to 1 g | $57 \ldots 150 \mathrm{~Hz}$ |

## Electrical supply conditions

| Power systems |  |
| :---: | :---: |
| IT | Apply the measures described for IT systems! |
| TN | Voltage to earth: max. 300 V |
| TT |  |

The connection to different supply forms enables a worldwide application of the inverters.
The following is supported:

- 1-phase mains connection 230/240 V ■60
- 3-phase mains connection 230/240 V $\square 70$
- 3-phase mains connection 230/240 V "Light Duty" $\square 76$
- 3-phase mains connection $400 \mathrm{~V} \sqsubset 79$
- 3-phase mains connection 400 V "Light Duty" $■ 89$
- 3-phase mains connection $480 \mathrm{~V} \square 95$
- 3-phase mains connection 480 V "Light Duty" $\square 104$


## 1-phase mains connection 230/240 V

When selecting the inverters, please note:
The inverters i510-Cxxx/230-1 have an integrated RFI filter in the AC mains supply.

The inverters i510-Cxxx/230-2 do not have an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.
The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

## Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz : Max. ambient temperature $45^{\circ} \mathrm{C}$.
- At a switching frequency of 8 kHz or 16 kHz : Max. ambient temperature $40^{\circ} \mathrm{C}$.

| Inverter |  |  | i510-C0.25/230-1 | i510-C0.25/230-2 | i510-C0.37/230-1 | i510-C0.37/230-2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.25 |  | 0.37 |  |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 0.33 |  | 0.5 |  |
| Mains voltage range |  |  | 1/PE AC 170 V ... $264 \mathrm{~V}, 45 \mathrm{~Hz} \ldots 65 \mathrm{~Hz}$ |  |  |  |
| Output voltage |  |  | 3 AC 0-230/240 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 4 |  | 5.7 |  |
| with mains choke |  | A | 3.6 |  | 4.8 |  |
| Apparent output power |  | kVA | 0.6 |  | 0.9 |  |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A |  |  |  |  |
| 4 kHz |  | A | 1.7 |  | 2.4 |  |
| 8 kHz |  | A | 1.7 |  | 2.4 |  |
| 16 kHz |  | A | 1.1 |  | 1.6 |  |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | - |  |  |  |
| 4 kHz |  | W | 15 |  | 18 |  |
| 8 kHz |  | W | 15 |  | 20 |  |
| 16 kHz |  | W | 19 |  | 24 |  |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 2.6 | 2.6 | 3.6 | 3.6 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 1.3 | 1.3 | 1.8 | 1.8 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 3.4 | 3.4 | 4.8 | 4.8 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 1.3 | 1.3 | 1.8 | 1.8 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 50 |  |  |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  |  |
| Category C 2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 15 | - | 15 | - |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 15 | - | 15 | - |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |

## Technical data

1-phase mains connection 230/240 V
Rated data

| Inverter |  |  | i510-C0.55/230-1 | i510-C0.55/230-2 | i510-C0.75/230-1 | i510-C0.75/230-2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.55 |  | 0.75 |  |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 0.75 |  | 1 |  |
| Mains voltage range |  |  | 1/PE AC 170 V ... $264 \mathrm{~V}, 45 \mathrm{~Hz} \ldots 65 \mathrm{~Hz}$ |  |  |  |
| Output voltage |  |  | 3 AC 0-230/240 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 7.6 |  | 10 |  |
| with mains choke |  | A | 7.1 |  | 8.8 |  |
| Apparent output power |  | kVA | 1.2 |  | 1.6 |  |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | 3.2 |  | 4.2 |  |
| 4 kHz |  | A | 3.2 |  | 4.2 |  |
| 8 kHz |  | A | 3.2 |  | 4.2 |  |
| 16 kHz |  | A | 2.1 |  | 2.8 |  |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | 22 |  | 27 |  |
| 4 kHz |  | W | 23 |  | 29 |  |
| 8 kHz |  | W | 25 |  | 33 |  |
| 16 kHz |  | W | 30 |  | 38 |  |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 4.8 | 4.8 | 6.3 | 6.3 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 2.4 | 2.4 | 3.2 | 3.2 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 6.4 | 6.4 | 8.4 | 8.4 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 2.4 | 2.4 | 3.2 | 3.2 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 50 |  |  |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  |  |
| Category $\mathrm{C} 2(\leq 8 \mathrm{kHz})$ |  | m | 20 | - | 20 | - |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 50 | - | 50 | - |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |


| Inverter |  |  | i510-C1.1/230-1 | i510-C1.1/230-2 | i510-C1.5/230-1 | i510-C1.5/230-2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 1.1 |  | 1.5 |  |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 1.5 |  | 2 |  |
| Mains voltage range |  |  | 1/PE AC 170 V ... $264 \mathrm{~V}, 45 \mathrm{~Hz} . . .65 \mathrm{~Hz}$ |  |  |  |
| Output voltage |  |  | 3 AC 0-230/240 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 14.3 |  | 16.7 |  |
| with mains choke |  | A | 11.9 |  | 13.9 |  |
| Apparent output power |  | kVA | 2.2 |  | 2.6 |  |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | 6 |  | 7 |  |
| 4 kHz |  | A | 6 |  | 7 |  |
| 8 kHz |  | A | 6 |  | 7 |  |
| 16 kHz |  | A | 4 |  | 4.7 |  |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | 36 |  | 41 |  |
| 4 kHz |  | W | 37 |  | 43 |  |
| 8 kHz |  | W | 42 |  | 50 |  |
| 16 kHz |  | W | 51 |  | 59 |  |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 9 | 9 | 10.5 | 10.5 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 4.5 | 4.5 | 5.3 | 5.3 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 12 | 12 | 14 | 14 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 4.5 | 4.5 | 5.3 | 5.3 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 50 |  |  |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  |  |
| Category C 2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 20 | - | 20 | - |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 35 | - | 35 | - |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |

## Technical data

1-phase mains connection 230/240 V
Rated data


A residual current device (RCD) is optional.
Fusing data for UL/NEC compliant installations: Fusing data $\square 44$


The RCD type " F " is only permitted in 1-phase operation ( $\mathrm{L} / \mathrm{N}$ )!

| Inverter | Fuse |  |  | Circuit breaker |  |  | RCD |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Max. SCCR | Characteristic | Max. rated current | Max. SCCR | Characteristic | Max. rated current |  | Type |
|  | kA |  | A | kA |  | A | mA |  |
| i510-C0.25/230-1 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.25/230-1 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ F |
| i510-C0.25/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.25/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ F |
| i510-C0.37/230-1 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.37/230-1 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ F |
| i510-C0.37/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.37/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ F |
| i510-C0.55/230-1 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.55/230-1 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ F |
| i510-C0.55/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.55/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ F |
| i510-C0.75/230-1 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.75/230-1 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ F |
| i510-C0.75/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.75/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ F |
| i510-C1.1/230-1 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C1.1/230-1 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ F |
| i510-C1.1/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C1.1/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ F |
| i510-C1.5/230-1 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C1.5/230-1 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ F |
| i510-C1.5/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C1.5/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ F |
| i510-C2.2/230-1 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C2.2/230-1 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ F |
| i510-C2.2/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C2.2/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ F |

The connection data according to UL can be found under: $>$ Connection according to UL $\square 43$

## Technical data

1-phase mains connection 230/240 V
Terminal data

## Terminal data

| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | $0.25 \ldots 0.75$ | 1.1 ... 2.2 |
| :---: | :---: | :---: | :---: | :---: |
| Connection description |  |  | Mains connection |  |
| Connection |  |  | X100 |  |
| Connection type |  |  | Pluggable |  |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 2.5 | 6 |
| Max. Cable cross-section |  | AWG | 12 | 10 |
| Stripping length |  | mm | 8 | 8 |
| Stripping length |  | in | 0.3 | 0.3 |
| Tightening torque |  | Nm | 0.5 | 0.7 |
| Tightening torque |  | lb-in | 4.4 | 6.2 |
| Required tool |  |  | Screwdriver $0.5 \times 3.0$ | Screwdriver $0.6 \times 3.5$ |


| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | $\mathbf{0 . 2 5} \ldots \mathbf{2 . 2}$ |
| :--- | :--- | :--- | :---: |
| Connection description |  |  | PE connection |
| Terminal type |  |  | Schraube |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 6 |
| Max. Cable cross-section |  | AWG | 10 |
| Stripping length |  | mm | 10 |
| Stripping length |  | in | 0.4 |
| Tightening torque |  | Nm | 2 |
| Tightening torque |  | Ib-in | 18 |
| Required tool |  |  | Torx key 20 |


| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | $\mathbf{0 . 2 5} \ldots \mathbf{2 . 2}$ |
| :--- | :--- | :--- | :---: |
| Connection description |  |  | Motor connection |
| Connection |  |  | X105 |
| Connection type |  |  | Pluggable |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 2.5 |
| Max. Cable cross-section |  | AWG | 12 |
| Stripping length |  | mm | 8 |
| Stripping length |  | in | 0.3 |
| Tightening torque |  | Nm | 0.5 |
| Tightening torque |  | lb-in | 4.4 |
| Required tool |  |  | Screwdriver $0.5 \times 3.0$ |

The terminal data for the terminal X3 can be found under: $\downarrow$ Control connections $\mathbb{m} 55$

## RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from $\square 138$
EMC filters can be used both in the side structure and in the substructure.

Maximum motor cable lengths with residual current device (RCD)

| Mains connection |  |  | 1-phase, 230 V |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Inverter |  |  | $\begin{aligned} & \text { i510-C0.25/230-1 } \\ & \text { i510-C0.37/230-1 } \end{aligned}$ | $\begin{aligned} & \text { i510-C0.55/230-1 } \\ & \text { i510-C0.75/230-1 } \end{aligned}$ | $\begin{aligned} & \text { i510-C1.1/230-1 } \\ & \text { i510-C1.5/230-1 } \\ & \text { i510-C2.2/230-1 } \end{aligned}$ |
| With integrated RFI filter |  |  |  |  |  |
| Without EMC category Thermal limitation | Shielded motor cable length | m | 50 | 50 | 50 |
|  | Unshielded motor cable length | m | 100 | 100 | 200 |
| With integrated RFI filter |  |  |  |  |  |
| Category C1 | Shielded motor cable length | m | - | - | - |
| Category C2 |  | m | 15 | 20 | 20 |
|  | Earth-leakage circuit breaker | mA | 30 | 30 | 30 |
| RFI filter Low Leakage |  |  |  |  |  |
| Category C1 | Shielded motor cable length | m | 5 | 5 | 5 |
|  | Earth-leakage circuit breaker | mA | 10 | 10 | 10 |
| RFI filter Short Distance |  |  |  |  |  |
| Category C1 | Shielded motor cable length | m | 25 | 25 | 25 |
| Category C2 |  | m | 50 | 50 | 50 |
|  | Earth-leakage circuit breaker | mA | 30 | 30 | 30 |
| RFI filter Long Distance |  |  |  |  |  |
| Category C1 | Shielded motor cable length | m | 50 | 50 | 50 |
| Category C2 |  | m | 50 | 50 | 50 |
|  | Earth-leakage circuit breaker | mA | 300 | 300 | 300 |

Low Leakage

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current |  | Weight |  | 1 |  |  |  |  |
|  |  | A | mm | kg | m | kHz |  |  |  |  |
| i510-C0.25/230-1 | IOFAE137B100L0000S | 6 | $226 \times 60 \times 50$ | 0.85 | 5 | 4 | - | - | - | - |
| i510-C0.25/230-1 | IOFAE137B100L0000S | 6 | $226 \times 60 \times 50$ | 0.85 | 5 | 8 | - | - | - | - |
| i510-C0.25/230-1 | IOFAE137B100L0000S | 6 | $226 \times 60 \times 50$ | 0.85 | 5 | 16 | - | - | - | - |
| i510-C0.37/230-1 | IOFAE137B100L0000S | 6 | $226 \times 60 \times 50$ | 0.85 | 5 | 4 | - | - | - | - |
| i510-C0.37/230-1 | IOFAE137B100L0000S | 6 | $226 \times 60 \times 50$ | 0.85 | 5 | 8 | - | - | - | - |
| i510-C0.37/230-1 | IOFAE137B100L0000S | 6 | $226 \times 60 \times 50$ | 0.85 | 5 | 16 | - | - | - | - |
| i510-C0.55/230-1 | IOFAE175B100L0000S | 10 | $276 \times 60 \times 50$ | 1 | 5 | 2 | - | - | - | - |
| i510-C0.55/230-1 | IOFAE175B100L0000S | 10 | $276 \times 60 \times 50$ | 1 | 5 | 4 | - | - | - | - |
| i510-C0.55/230-1 | IOFAE175B100L0000S | 10 | $276 \times 60 \times 50$ | 1 | 5 | 8 | - | - | - | - |
| i510-C0.55/230-1 | IOFAE175B100L0000S | 10 | $276 \times 60 \times 50$ | 1 | 5 | 16 | - | - | - | - |
| i510-C0.75/230-1 | IOFAE175B100L0000S | 10 | $276 \times 60 \times 50$ | 1 | 5 | 2 | - | - | - | - |
| i510-C0.75/230-1 | IOFAE175B100L0000S | 10 | $276 \times 60 \times 50$ | 1 | 5 | 4 | - | - | - | - |
| i510-C0.75/230-1 | IOFAE175B100L0000S | 10 | $276 \times 60 \times 50$ | 1 | 5 | 8 | - | - | - | - |
| i510-C0.75/230-1 | IOFAE175B100L0000S | 10 | $276 \times 60 \times 50$ | 1 | 5 | 16 | - | - | - | - |
| i510-C1.1/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 2 | - | - | - | - |
| i510-C1.1/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 4 | - | - | - | - |
| i510-C1.1/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 8 | - | - | - | - |
| i510-C1.1/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 16 | - | - | - | - |
| i510-C1.5/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 2 | - | - | - | - |
| i510-C1.5/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 4 | - | - | - | - |
| i510-C1.5/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 8 | - | - | - | - |
| i510-C1.5/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 16 | - | - | - | - |
| i510-C2.2/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 2 | - | - | - | - |
| i510-C2.2/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 4 | - | - | - | - |
| i510-C2.2/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 8 | - | - | - | - |
| i510-C2.2/230-1 | IOFAE222B100L0000S | 22.5 | $346 \times 60 \times 50$ | 1.35 | 5 | 16 | - | - | - | - |

In order to meet the EMC requirements according to EN IEC 61800-3, the screws marked "IT" on the product must be removed when using the filters listed below.


Technical data

Short distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current |  | Weight | C1 |  | C2 |  | C3 |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C0.25/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 4 | 50 | 4 | - | - |
| i510-C0.25/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 8 | 50 | 8 | - | - |
| i510-C0.25/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 16 | 50 | 16 | - | - |
| i510-C0.37/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 4 | 50 | 4 | - | - |
| i510-C0.37/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 8 | 50 | 8 | - | - |
| i510-C0.37/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 16 | 50 | 16 | - | - |
| i510-C0.55/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 2 | 50 | 2 | - | - |
| i510-C0.55/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 4 | 50 | 4 | - | - |
| i510-C0.55/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 8 | 50 | 8 | - | - |
| i510-C0.55/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 16 | 50 | 16 | - | - |
| i510-C0.75/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 2 | 50 | 2 | - | - |
| i510-C0.75/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 4 | 50 | 4 | - | - |
| i510-C0.75/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 8 | 50 | 8 | - | - |
| i510-C0.75/230-1 | IOFAE175B100S0000S | 10 | $276 \times 60 \times 50$ | 0.77 | 25 | 16 | 50 | 16 | - | - |
| i510-C1.1/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 2 | 50 | 2 | - | - |
| i510-C1.1/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 4 | 50 | 4 | - | - |
| i510-C1.1/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 8 | 50 | 8 | - | - |
| i510-C1.1/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 16 | 50 | 16 | - | - |
| i510-C1.5/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 2 | 50 | 2 | - | - |
| i510-C1.5/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 4 | 50 | 4 | - | - |
| i510-C1.5/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 8 | 50 | 8 | - | - |
| i510-C1.5/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 16 | 50 | 16 | - | - |
| i510-C2.2/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 2 | 50 | 2 | - | - |
| i510-C2.2/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 4 | 50 | 4 | - | - |
| i510-C2.2/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 8 | 50 | 8 | - | - |
| i510-C2.2/230-1 | IOFAE222B100S0000S | 22.5 | $346 \times 60 \times 50$ | 1.02 | 25 | 16 | 50 | 16 | - | - |

## Long distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions ( $\mathrm{H} \times \mathrm{W} \times \mathrm{D}$ ) | Weight | C1 |  | C2 |  | C3 |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C0.25/230-1 | IOFAE175B100D0000S | 10 | $276 \times 60 \times 50$ | 0.82 | 50 | 4 | 50 | 4 | - | - |
| i510-C0.25/230-1 | IOFAE175B100D0000S | 10 | $276 \times 60 \times 50$ | 0.82 | 50 | 8 | 50 | 8 | - | - |
| i510-C0.37/230-1 | IOFAE175B100D0000S | 10 | $276 \times 60 \times 50$ | 0.82 | 50 | 4 | 50 | 4 | - | - |
| i510-C0.37/230-1 | IOFAE175B100D0000S | 10 | $276 \times 60 \times 50$ | 0.82 | 50 | 8 | 50 | 8 | - | - |
| i510-C0.55/230-1 | IOFAE175B100D0000S | 10 | $276 \times 60 \times 50$ | 0.82 | 50 | 4 | 50 | 4 | - | - |
| i510-C0.55/230-1 | IOFAE175B100D0000S | 10 | $276 \times 60 \times 50$ | 0.82 | 50 | 8 | 50 | 8 | - | - |
| i510-C0.75/230-1 | IOFAE175B100D0000S | 10 | $276 \times 60 \times 50$ | 0.82 | 50 | 4 | 50 | 4 | - | - |
| i510-C0.75/230-1 | IOFAE175B100D0000S | 10 | $276 \times 60 \times 50$ | 0.82 | 50 | 8 | 50 | 8 | - | - |
| i510-C1.1/230-1 | IOFAE222B100D0000S | 22.5 | $346 \times 60 \times 50$ | 1.09 | 50 | 4 | 50 | 4 | - | - |
| i510-C1.1/230-1 | IOFAE222B100D0000S | 22.5 | $346 \times 60 \times 50$ | 1.09 | 50 | 8 | 50 | 8 | - | - |
| i510-C1.5/230-1 | IOFAE222B100D0000S | 22.5 | $346 \times 60 \times 50$ | 1.09 | 50 | 4 | 50 | 4 | - | - |
| i510-C1.5/230-1 | IOFAE222B100D0000S | 22.5 | $346 \times 60 \times 50$ | 1.09 | 50 | 8 | 50 | 8 | - | - |
| i510-C2.2/230-1 | IOFAE222B100D0000S | 22.5 | $346 \times 60 \times 50$ | 1.09 | 50 | 4 | 50 | 4 | - | - |
| i510-C2.2/230-1 | IOFAE222B100D0000S | 22.5 | $346 \times 60 \times 50$ | 1.09 | 50 | 8 | 50 | 8 | - | - |

## Technical data

3-phase mains connection 230/240 V
Rated data

## 3-phase mains connection 230/240 V

The inverters i510-Cxxx/230-3 and i510-Cxxx/230-2 do not have an integrated RFI filter in the AC mains supply.
In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

## Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz : Max. ambient temperature $45^{\circ} \mathrm{C}$.
- At a switching frequency of 8 kHz or 16 kHz : Max. ambient temperature $40^{\circ} \mathrm{C}$.


| Inverter |  |  | i510-C1.1/230-2 | i510-C1.5/230-2 | i510-C2.2/230-2 | i510-C4.0/230-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 1.1 | 1.5 | 2.2 | 4 |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 1.5 | 2 | 3 | 5 |
| Mains voltage range |  |  | 3/PE AC 195 V ... $264 \mathrm{~V}, 45 \mathrm{~Hz} . . .65 \mathrm{~Hz}$ |  |  |  |
| Output voltage |  |  | 3 AC 0-230/240 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 7.8 | 9.5 | 13.6 | 20.6 |
| with mains choke |  | A | 5.6 | 6.8 | 9.8 | 15.7 |
| Apparent output power |  | kVA | 2.2 | 2.6 | 3.6 | 6.4 |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | 6 | 7 | 9.6 | 16.5 |
| 4 kHz |  | A | 6 | 7 | 9.6 | 16.5 |
| 8 kHz |  | A | 6 | 7 | 9.6 | 16.5 |
| 16 kHz |  | A | 4 | 4.7 | 6.4 | 11 |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | 36 | 41 | 54 | 113 |
| 4 kHz |  | W | 37 | 43 | 60 | 115 |
| 8 kHz |  | W | 42 | 50 | 70 | 130 |
| 16 kHz |  | W | 51 | 59 | 78 | 116 |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 9 | 10.5 | 14.4 | 24.8 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 4.5 | 5.3 | 7.2 | 12.4 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 12 | 14 | 19.2 | 33 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | S | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 4.5 | 5.3 | 7.2 | 12.4 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 50 |  |  |  |
| Category C 1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  |  |
| Category C 2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  |  |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  |  |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |


| Inverter |  |  | i510-C5.5/230-3 |
| :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 5.5 |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 7.5 |
| Mains voltage range |  |  | 3/PE AC 195 V ... $264 \mathrm{~V}, 45 \mathrm{~Hz}$... 65 Hz |
| Output voltage |  |  | 3 AC 0-230/240 V |
| Rated mains current |  |  |  |
| without mains choke |  | A | 28.8 |
| with mains choke |  | A | 21.9 |
| Apparent output power |  | kVA | 8.7 |
| Rated output current |  |  |  |
| 2 kHz |  | A | 23 |
| 4 kHz |  | A | 23 |
| 8 kHz |  | A | 23 |
| 16 kHz |  | A | 15.3 |
| Power loss |  |  |  |
| 2 kHz |  | W | 166 |
| 4 kHz |  | W | 175 |
| 8 kHz |  | W | 195 |
| 16 kHz |  | W | 159 |
| Overcurrent cycle 180 s |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 34.5 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 |
| Max. output current during the recovery time |  | A | 17.3 |
| Overcurrent cycle 15 s |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 46 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 |
| Max. output current during the recovery time |  | A | 17.3 |
| Cyclic mains switching |  |  | 3 times per minute |
| Brake chopper |  |  |  |
| Max. output current |  |  | - |
| Min. Brake resistor |  |  | - |
| Max. shielded motor cable length |  |  |  |
| without EMC category |  | m | 50 |
| Category $\mathrm{C1}$ ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |
| Category C 2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |
| Max. Unshielded motor cable length |  |  |  |
| without EMC category |  | m | - |

## Fusing data



A residual current device (RCD) is optional.
Fusing data for UL/NEC compliant installations: Fusing data $■ 44$

| Inverter | Fuse |  |  | Circuit breaker |  |  | RCD |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Max. <br> SCCR | Characteristic | Max. rated <br> current | Max. <br> SCCR | Characteristic | Max. rated <br> current |  | Type |
|  | kA |  | A | kA |  | A | mA |  |
| i510-C0.25/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.37/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.55/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.75/230-2 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C1.1/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C1.5/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C2.2/230-2 | 65 | gG/gL, gRL | 32 | 65 | B, C | 32 | $\geq 30$ | Typ B |
| i510-C4.0/230-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 300$ | Typ B |
| i510-C5.5/230-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 300$ | Typ B |

The connection data according to UL can be found under: $\downarrow$ Connection according to UL $\mathbb{0} 43$

## Terminal data

| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | $0.25 \ldots 0.75$ | 1.1 ... 2.2 | $4 \ldots 5.5$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Connection description |  |  | Mains connection |  |  |
| Connection |  |  | X100 |  |  |
| Connection type |  |  | Pluggable |  | Non-pluggable |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 2.5 | 6 | 6 |
| Max. Cable cross-section |  | AWG | 12 | 10 | 10 |
| Stripping length |  | mm | 8 | 8 | 9 |
| Stripping length |  | in | 0.3 | 0.3 | 0.35 |
| Tightening torque |  | Nm | 0.5 | 0.7 | 0.5 |
| Tightening torque |  | lb -in | 4.4 | 6.2 | 4.4 |
| Required tool |  |  | Screwdriver $0.5 \times 3.0$ | Screwdriver $0.6 \times 3.5$ |  |


| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | $\mathbf{0 . 2 5} \ldots \mathbf{5 . 5}$ |
| :--- | :--- | :--- | :---: |
| Connection description |  |  | PE connection |
| Terminal type |  |  | Schraube |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 6 |
| Max. Cable cross-section |  | AWG | 10 |
| Stripping length |  | mm | 10 |
| Stripping length |  | in | 0.4 |
| Tightening torque |  | Nm | 2 |
| Tightening torque |  | lb-in | 18 |
| Required tool |  |  | Torx key 20 |


| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.25 ... 2.2 | $4 \ldots 5.5$ |
| :---: | :---: | :---: | :---: | :---: |
| Connection description |  |  | Motor connection |  |
| Connection |  |  | X105 |  |
| Connection type |  |  | Pluggable | Non-pluggable |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 2.5 | 6 |
| Max. Cable cross-section |  | AWG | 12 | 10 |
| Stripping length |  | mm | 8 | 9 |
| Stripping length |  | in | 0.3 | 0.35 |
| Tightening torque |  | Nm | 0.5 | 0.5 |
| Tightening torque |  | lb -in | 4.4 | 4.4 |
| Required tool |  |  | Screwdriver $0.5 \times 3.0$ | Screwdriver $0.6 \times 3.5$ |

The terminal data for the terminal X3 can be found under: $\downarrow$ Control connections $\mathbb{\square} 55$

## 3-phase mains connection 230/240 V "Light Duty"



The inverters i510-Cxxx/230-3 do not have an integrated RFI filter in the AC mains supply.
In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.
The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

## Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz : Ambient temperature above $40^{\circ} \mathrm{C}$ with a rated output current reduced by $2.5 \% /{ }^{\circ} \mathrm{C}$.
- If the load characteristic "Light Duty" and the switching frequencies 8 kHz or 16 kHz are selected, only the values of the load characteristic "Heavy Duty" are reached.



## Technical data

3-phase mains connection 230/240 V "Light Duty"
Fusing data

Fusing data


A residual current device ( $R C D$ ) is optional.
Fusing data for UL/NEC compliant installations: Fusing data $\mathbb{D} 44$

| Inverter | Fuse |  |  | Circuit breaker |  |  | RCD |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Max. <br> SCCR | Characteristic | Max. rated <br> current | Max. <br> SCCR | Characteristic | Max. rated <br> current | Type |  |
|  | kA |  | A | kA |  | A | mA |  |
| i510-C4.0/230-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 300$ | Typ B |
| i510-C5.5/230-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 300$ | Typ B |

The connection data according to UL can be found under: $>$ Connection according to UL■43

## Terminal data

See "3-phase mains connection 230/240 V" • Terminal data $\square 75$
The terminal data for the terminal X3 can be found under: $\downarrow$ Control connections $■ 55$

## 3-phase mains connection 400 V

## Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz : Max. ambient temperature $45^{\circ} \mathrm{C}$.
- At a switching frequency of 8 kHz or 16 kHz : Max. ambient temperature $40^{\circ} \mathrm{C}$.


## Technical data

3-phase mains connection 400 V
Rated data

| Inverter |  |  | i510-C0.37/400-3 | i510-C0.55/400-3 | i510-C0.75/400-3 | i510-C1.1/400-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.37 | 0.55 | 0.75 | 1.1 |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 0.5 | 0.75 | 1 | 1.5 |
| Mains voltage range |  |  | 3/PE AC 340 V ... $528 \mathrm{~V}, 45 \mathrm{~Hz}$... 65 Hz |  |  |  |
| Output voltage |  |  | 3 AC 0-400/480 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 1.8 | 2.5 | 3.3 | 4.4 |
| with mains choke |  | A | 1.4 | 2 | 2.6 | 3 |
| Apparent output power |  | kVA | 0.9 | 1.2 | 1.6 | 2.2 |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | - | 1.8 | 2.4 | 3.2 |
| 4 kHz |  | A | 1.3 | 1.8 | 2.4 | 3.2 |
| 8 kHz |  | A | 1.3 | 1.8 | 2.4 | 3.2 |
| 16 kHz |  | A | 0.9 | 1.2 | 1.6 | 2.1 |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | - | 24 | 30 | 38 |
| 4 kHz |  | W | 20 | 25 | 32 | 40 |
| 8 kHz |  | W | 24 | 31 | 40 | 51 |
| 16 kHz |  | W | 24 | 31 | 40 | 51 |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 2 | 2.7 | 3.6 | 4.8 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 1 | 1.4 | 1.8 | 2.4 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 2.6 | 3.6 | 4.8 | 6.4 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 1 | 1.4 | 1.8 | 2.4 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 15 | 50 |  |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  | 3 |
| Category C 2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 15 |  |  | 20 |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 15 | 20 |  | 35 |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |


| Inverter |  |  | i510-C1.5/400-3 | i510-C2.2/400-3 | i510-C3.0/400-3 | i510-C4.0/400-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 1.5 | 2.2 | 3 | 4 |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 2 | 3 | 4 | 5 |
| Mains voltage range |  |  | 3/PE AC 340 V ... $528 \mathrm{~V}, 45 \mathrm{~Hz} \ldots 65 \mathrm{~Hz}$ |  |  |  |
| Output voltage |  |  | 3 AC 0-400/480 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 5.4 | 7.8 | 9.6 | 12.5 |
| with mains choke |  | A | 3.7 | 5.3 | 6.9 | 9 |
| Apparent output power |  | kVA | 2.6 | 3.8 | 4.9 | 6.4 |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | 3.9 | 5.6 | 7.3 | 9.5 |
| 4 kHz |  | A | 3.9 | 5.6 | 7.3 | 9.5 |
| 8 kHz |  | A | 3.9 | 5.6 | 7.3 | 9.5 |
| 16 kHz |  | A | 2.6 | 3.7 | 4.9 | 6.3 |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | 45 | 62 | 79 | 102 |
| 4 kHz |  | W | 48 | 66 | 85 | 110 |
| 8 kHz |  | W | 61 | 85 | 110 | 140 |
| 16 kHz |  | W | 61 | 85 | 109 | 140 |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 5.9 | 8.4 | 11 | 14.3 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 2.9 | 4.2 | 5.5 | 7.1 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 7.8 | 11.2 | 14.6 | 19 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 2.9 | 4.2 | 5.5 | 7.1 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 50 |  | 100 |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 3 |  | - |  |
| Category C2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 20 |  |  |  |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 35 |  |  |  |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |

## Technical data

3-phase mains connection 400 V
Rated data


Fusing data


A residual current device (RCD) is optional.
Fusing data for UL/NEC compliant installations: • Fusing data $\square 44$

| Inverter | Fuse |  |  | Circuit breaker |  |  | RCD |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Max. <br> SCCR | Characteristic | Max. rated <br> current | Max. <br> SCCR | Characteristic | Max. rated <br> current |  | Type |
|  | kA |  | A | kA |  | A | mA |  |
| i510-C0.37/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.55/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.75/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C1.1/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C1.5/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C2.2/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C3.0/400-3 | 65 | gG/gL, gRL | 35 | 65 | B, C | 25 | $\geq 30$ | Typ B |
| i510-C4.0/400-3 | 65 | gG/gL, gRL | 35 | 65 | B, C | 25 | $\geq 30$ | Typ B |
| i510-C5.5/400-3 | 65 | gG/gL, gRL | 25 | 65 | B, C | 25 | $\geq 300$ | Typ B |
| i510-C7.5/400-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 30$ | Typ B |
| i510-C11/400-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 30$ | Typ B |

The connection data according to UL can be found under: • Connection according to UL $■ 43$

## Technical data

3-phase mains connection 400 V
Terminal data

## Terminal data

| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.37 ... 2. | $3 . . .4$ | 5.5 | 7.5 ... 11 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Connection description |  |  | Mains connection |  |  |  |
| Connection |  |  | X100 |  |  |  |
| Connection type |  |  | Pluggable |  | Non-pluggable |  |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 2.5 | 4 | 6 | 16 |
| Max. Cable cross-section |  | AWG | 12 | 10 | 10 | 6 |
| Stripping length |  | mm | 8 | 8 | 9 | 11 |
| Stripping length |  | in | 0.3 | 0.3 | 0.35 | 0.43 |
| Tightening torque |  | Nm | 0.5 | 0.6 | 0.5 | 1.2 |
| Tightening torque |  | lb-in | 4.4 | 5.3 | 4.4 | 11 |
| Required tool |  |  | Screwdriver $0.5 \times 3.0$ |  | Screwdriver $0.6 \times 3.5$ | Screwdriver $0.8 \times 4.0$ |


| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | $\mathbf{0 . 3 7} \ldots \mathbf{5 . 5}$ | $\mathbf{7 . 5} \ldots \mathbf{1 1}$ |
| :--- | :--- | :--- | :---: | :---: | :---: |
| Connection description |  |  | PE connection |  |
| Terminal type |  |  | 6 | Schraube |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 10 | 16 |
| Max. Cable cross-section |  | AWG | 10 | 6 |
| Stripping length |  | mm | 0.4 | 11 |
| Stripping length |  | in | 2 | 0.4 |
| Tightening torque |  | Nm | 18 | 3.4 |
| Tightening torque |  | lb-in | Torx key 20 | 30 |
| Required tool |  |  |  | Crosstip screwdriver PZ2 |


| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.37 ... 4 | 5.5 | 7.5 ... 11 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Connection description |  |  | Motor connection |  |  |
| Connection |  |  | X105 |  |  |
| Connection type |  |  | Pluggable | Non-pluggable |  |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 2.5 | 6 | 16 |
| Max. Cable cross-section |  | AWG | 12 | 10 | 6 |
| Stripping length |  | mm | 8 | 9 | 11 |
| Stripping length |  | in | 0.3 | 0.35 | 0.43 |
| Tightening torque |  | Nm | 0.5 | 0.5 | 1.2 |
| Tightening torque |  | lb-in | 4.4 | 4.4 | 11 |
| Required tool |  |  | Screwdriver $0.5 \times 3.0$ | Screwdriver $0.6 \times 3.5$ | Screwdriver $0.8 \times 4.0$ |

The terminal data for the terminal X3 can be found under: $\downarrow$ Control connections $\mathbb{m} 55$

## RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from $\square 138$
EMC filters can be used both in the side structure and in the substructure.

Maximum motor cable lengths with residual current device (RCD)

| Mains connection |  |  | 3-phase, $400 \mathrm{~V} / 480 \mathrm{~V}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Inverter |  |  | i510-C0.37/400-3 | $\begin{aligned} & \text { i510-C0.55/400-3 } \\ & \text { i510-C0.75/400-3 } \end{aligned}$ | i510-C1.1/400-3 <br> i510-C1.5/400-3 <br> i510-C2.2/400-3 <br> i510-C3.0/400-3 <br> i510-C4.0/400-3 | $\begin{aligned} & \text { i510-C5.5/400-3 } \\ & \text { i510-C7.5/400-3 } \\ & \text { i510-C11/400-3 } \end{aligned}$ |
| Without RFI filter |  |  |  |  |  |  |
| Without EMC category Thermal limitation | Max. motor cable length shielded | m | 15 | 50 | 50 | 100 |
|  | Max. motor cable length unshielded | m | 30 | 100 | 200 | 200 |
| With integrated RFI filter |  |  |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | - | - | - | - |
| Category C2 |  | m | 15 | 15 | 20 | 20 |
|  | RCD (optional) | mA | 30 | 30 | 30 | 300 |
| RFI filter Low Leakage |  |  |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | - | - | - | - |
|  | RCD (optional) | mA | - | - | - | - |
| RFI filter Short Distance |  |  |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | 15 | 25 | 25 | 25 |
| Category C2 |  | m | 15 | 50 | 50 | 50 |
|  | RCD (optional) | mA | 30 | 30 | 30 | 30 |
| RFI filter Long Distance |  |  |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | 15 | 50 | 50 | 50 |
| Category C2 |  | m | 15 | 50 | 50 | 100 |
|  | RCD (optional) | mA | 300 | 300 | 300 | 300 |

## Short distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions (Hx W x D | Weight |  |  |  |  |  |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C0.37/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 15 | 4 | 15 | 4 | - | - |
| i510-C0.37/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 15 | 8 | 15 | 8 | - | - |
| i510-C0.37/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 15 | 16 | 15 | 16 | - | - |
| i510-C0.55/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 2 | 50 | 2 | - | - |
| i510-C0.55/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 4 | 50 | 4 | - | - |
| i510-C0.55/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 8 | 50 | 8 | - | - |
| i510-C0.55/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 16 | 50 | 16 | - | - |
| i510-C0.75/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 2 | 50 | 2 | - | - |
| i510-C0.75/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 4 | 50 | 4 | - | - |
| i510-C0.75/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 8 | 50 | 8 | - | - |
| i510-C0.75/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 16 | 50 | 16 | - | - |
| i510-C1.1/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 2 | 50 | 2 | - | - |
| i510-C1.1/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 4 | 50 | 4 | - | - |
| i510-C1.1/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 8 | 50 | 8 | - | - |
| i510-C1.1/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 16 | 50 | 16 | - | - |
| i510-C1.5/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 2 | 50 | 2 | - | - |
| i510-C1.5/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 4 | 50 | 4 | - | - |
| i510-C1.5/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 8 | 50 | 8 | - | - |
| i510-C1.5/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 16 | 50 | 16 | - | - |
| i510-C2.2/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 2 | 50 | 2 | - | - |
| i510-C2.2/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 4 | 50 | 4 | - | - |
| i510-C2.2/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 8 | 50 | 8 | - | - |
| i510-C2.2/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 16 | 50 | 16 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 2 | 50 | 2 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 4 | 50 | 4 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 8 | 50 | 8 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 16 | 50 | 16 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 2 | 50 | 2 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 4 | 50 | 4 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 8 | 50 | 8 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 16 | 50 | 16 | - | - |
| i510-C5.5/400-3 | IOFAE255F100S0001S | 18.3 | $346 \times 90 \times 60$ | 2.05 | 25 | 4 | 50 | 4 | - | - |
| i510-C5.5/400-3 | IOFAE255F100S0001S | 18.3 | $346 \times 90 \times 60$ | 2.05 | 25 | 8 | 50 | 8 | - | - |
| i510-C7.5/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 4 | 50 | 4 | - | - |
| i510-C7.5/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 8 | 50 | 8 | - | - |
| i510-C11/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 4 | 50 | 4 | - | - |
| i510-C11/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 8 | 50 | 8 | - | - |

In order to meet the EMC requirements according to EN IEC 61800-3, the lower of the screws marked "IT" on the product must be removed when using the filters listed below.

| Filters: | IOFAE240F100S0001S <br> IOFAE255F100S0001S <br> IOFAE311F100S0000S |
| :--- | :--- |
|  |  |



Long distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions ( $\mathrm{H} \times \mathrm{W} \times \mathrm{D}$ ) | Weight | C1 |  | C2 |  | C3 |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C0.37/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 15 | 4 | 15 | 4 | - | - |
| i510-C0.37/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 15 | 8 | 15 | 8 | - | - |
| i510-C0.55/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 50 | 4 | 50 | 4 | - | - |
| i510-C0.55/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 50 | 8 | 50 | 8 | - | - |
| i510-C0.75/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 50 | 4 | 50 | 4 | - | - |
| i510-C0.75/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 50 | 8 | 50 | 8 | - | - |
| i510-C1.1/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 4 | 50 | 4 | - | - |
| i510-C1.1/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 8 | 50 | 8 | - | - |
| i510-C1.5/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 4 | 50 | 4 | - | - |
| i510-C1.5/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 8 | 50 | 8 | - | - |
| i510-C2.2/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 4 | 50 | 4 | - | - |
| i510-C2.2/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 8 | 50 | 8 | - | - |
| i510-C3.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 4 | 50 | 4 | - | - |
| i510-C3.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 8 | 50 | 8 | - | - |
| i510-C4.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 4 | 50 | 4 | - | - |
| i510-C4.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 8 | 50 | 8 | - | - |
| i510-C5.5/400-3 | IOFAE255F100D0001S | 18.3 | $346 \times 90 \times 60$ | 1.65 | 50 | 4 | 100 | 4 | - | - |
| i510-C5.5/400-3 | IOFAE255F100D0001S | 18.3 | $346 \times 90 \times 60$ | 1.65 | 50 | 8 | 100 | 8 | - | - |
| i510-C7.5/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 4 | 100 | 4 | - | - |
| i510-C7.5/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 8 | 100 | 8 | - | - |
| i510-C11/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 4 | 100 | 4 | - | - |
| i510-C11/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 8 | 100 | 8 | - | - |

## Technical data

3-phase mains connection 400 V
Sine filters

## Sine filters

| Inverter |  | Sine filters |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Switching frequency | Order code | Rated inductance | Max. output frequency |
|  | kHz |  | mH | Hz |
| i510-C3.0/400-3 | 4 | EZS3-010A200 | 5.10 |  |
| i510-C4.0/400-3 |  | S3-017A200 | 307 |  |
| i510-C5.5/400-3 |  | -017A200 | 3.07 | 150 |
| i510-C7.5/400-3 |  | EZS3-024A200 | 2.50 |  |
| i510-C11/400-3 |  | EZS3-032A200 | 2.00 |  |


| Inverter |  | Sine filters |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Switching frequency | Order code | Rated inductance | Max. output frequency |
|  | kHz |  | mH | Hz |
| i510-C0.37/400-3 |  |  |  |  |
| i510-C0.55/400-3 |  | EZS3-004A200 | 11.0 |  |
| i510-C0.75/400-3 |  | , |  |  |
| i510-C1.1/400-3 |  |  |  |  |
| i510-C1.5/400-3 |  |  |  |  |
| i510-C2.2/400-3 |  | EZS3-010A200 | 5.10 | 150 |
| i510-C3.0/400-3 |  |  |  |  |
| i510-C4.0/400-3 |  | EZS3-017A200 | 3.07 |  |
| i510-C5.5/400-3 |  | EZS3-017A200 | 3.07 |  |
| i510-C7.5/400-3 |  | EZS3-024A200 | 2.50 |  |
| i510-C11/400-3 |  | EZS3-032A200 | 2.00 |  |

## 3-phase mains connection 400 V "Light Duty"

## Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz : Ambient temperature above $40^{\circ} \mathrm{C}$ with a rated output current reduced by $2.5 \% /{ }^{\circ} \mathrm{C}$.
- If the load characteristic "Light Duty" and the switching frequencies 8 kHz or 16 kHz are selected, only the values of the load characteristic "Heavy Duty" are reached.


## Technical data

3-phase mains connection 400 V "Light Duty" Rated data

| Inverter |  |  | i510-C3.0/400-3 | i510-C4.0/400-3 | i510-C5.5/400-3 | i510-C7.5/400-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 4 | 5.5 | 7.5 | 11 |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 5 | 7.5 | 10 | 15 |
| Mains voltage range |  |  | 3/PE AC 340 V ... $528 \mathrm{~V}, 45 \mathrm{~Hz} \ldots 65 \mathrm{~Hz}$ |  |  |  |
| Output voltage |  |  | 3 AC 0-400/480 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 10.3 | 14 | 18.3 | 28 |
| with mains choke |  | A | 8.2 | 11 | 14.5 | 22 |
| Apparent output power |  | kVA | 5.9 | 8 | 10.5 | 15 |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | 8.8 | 11.9 | 15.6 | 23 |
| 4 kHz |  | A | 8.8 | 11.9 | 15.6 | 23 |
| 8 kHz |  | A | - |  |  |  |
| 16 kHz |  | A | - |  |  |  |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | 94 | 125 | 163 | 238 |
| 4 kHz |  | W | 100 | 133 | 173 | 253 |
| 8 kHz |  | W | - |  |  |  |
| 16 kHz |  | W | - |  |  |  |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 11 | 14.3 | 19.5 | 23.6 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 5.5 | 7.1 | 9.8 | 12.4 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 14.6 | 19 | 26 | 33 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 5.5 | 7.1 | 9.8 | 12.4 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 100 |  |  |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  |  |
| Category C 2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 20 |  |  |  |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 35 |  |  | 50 |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |



## Technical data

3-phase mains connection 400 V "Light Duty"
Fusing data

## Fusing data



A residual current device (RCD) is optional.
Fusing data for UL/NEC compliant installations: Fusing data $\square 44$

| Inverter | Fuse |  |  | Circuit breaker |  |  | RCD |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Max. <br> SCCR | Characteristic | Max. rated <br> current | Max. <br> SCCR | Characteristic | Max. rated <br> current |  | Type |
|  | kA |  | A | kA |  | A | mA |  |
| i510-C3.0/400-3 | 65 | gG/gL, gRL | 35 | 65 | B, C | 25 | $\geq 30$ | Typ B |
| i510-C4.0/400-3 | 65 | gG/gL, gRL | 35 | 65 | B, C | 25 | $\geq 30$ | Typ B |
| i510-C5.5/400-3 | 65 | gG/gL, gRL | 25 | 65 | B, C | 25 | $\geq 300$ | Typ B |
| i510-C7.5/400-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 30$ | Typ B |
| i510-C11/400-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 30$ | Typ B |

The connection data according to UL can be found under: © Connection according to UL $■ 43$

## Terminal data

See "3-phase mains connection 400 V" • Terminal data ■84
The terminal data for the terminal X3 can be found under: $\downarrow$ Control connections $■ 55$

## RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from $\square 138$
EMC filters can be used both in the side structure and in the substructure.

Maximum motor cable lengths with residual current device (RCD)

| Mains connection |  |  | 3-phase, $400 \mathrm{~V} / 480 \mathrm{~V}$ |  |
| :---: | :---: | :---: | :---: | :---: |
| Inverter |  |  | i510-C3.0/400-3 | i510-C5.5/400-3 |
|  |  |  | i510-C4.0/400-3 | i510-C7.5/400-3 |
|  |  |  |  | i510-C11/400-3 |
| Without RFI filter |  |  |  |  |
| Without EMC category <br> Thermal limitation | Max. motor cable length shielded | m | 50 | 100 |
|  | Max. motor cable length unshielded | m | 200 | 200 |
| With integrated RFI filter |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | - | - |
| Category C2 |  | m | 20 | 20 |
|  | RCD (optional) | mA | 30 | 300 |
| RFI filter Low Leakage |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | - | - |
|  | RCD (optional) | mA | - | - |
| RFI filter Short Distance |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | 25 | 25 |
| Category C2 |  | m | 50 | 50 |
|  | RCD (optional) | mA | 30 | 30 |
| RFI filter Long Distance |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | 50 | 50 |
| Category C2 |  | m | 50 | 100 |
|  | RCD (optional) | mA | 100 | 300 |

Short distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions ( $\mathrm{H} \times \mathrm{W} \times \mathrm{D}$ ) | Weight | C1 |  | C2 |  | C3 |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 2 | 50 | 2 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 4 | 50 | 4 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 2 | 50 | 2 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 4 | 50 | 4 | - | - |
| i510-C5.5/400-3 | IOFAE255F100S0001S | 18.3 | $346 \times 90 \times 60$ | 2.05 | 25 | 4 | 50 | 4 | - | - |
| i510-C7.5/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 4 | 50 | 4 | - | - |
| i510-C11/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 4 | 50 | 4 | - | - |

In order to meet the EMC requirements according to EN IEC 61800-3, the lower of the screws marked "IT" on the product must be removed when using the filters listed below.

Filters: | IOFAE240F100S0001S |
| ---: |
|  |
|  |
|  |
|  |
|  |
| IOFAE255F100S0001S |
| IOFAE311F100S0000S |



Long distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions (Hx W x D | Weight | C1 |  | C2 |  | C3 |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C3.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 4 | 50 | 4 | - | - |
| i510-C4.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 4 | 50 | 4 | - | - |
| i510-C5.5/400-3 | IOFAE255F100D0001S | 18.3 | $346 \times 90 \times 60$ | 1.65 | 50 | 4 | 100 | 4 | - | - |
| i510-C7.5/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 4 | 100 | 4 | - | - |
| i510-C11/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 4 | 100 | 4 | - | - |

## 3-phase mains connection 480 V

## Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz : Max. ambient temperature $45^{\circ} \mathrm{C}$.
- At a switching frequency of 8 kHz or 16 kHz : Max. ambient temperature $40^{\circ} \mathrm{C}$.


## Technical data

3-phase mains connection 480 V
Rated data

| Inverter |  |  | i510-C0.37/400-3 | i510-C0.55/400-3 | i510-C0.75/400-3 | i510-C1.1/400-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.37 | 0.55 | 0.75 | 1.1 |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 0.5 | 0.75 | 1 | 1.5 |
| Mains voltage range |  |  | 3/PE AC 340 V ... $528 \mathrm{~V}, 45 \mathrm{~Hz}$... 65 Hz |  |  |  |
| Output voltage |  |  | 3 AC 0-400/480 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 1.5 | 2.1 | 2.8 | 3.7 |
| with mains choke |  | A | 1.2 | 1.7 | 2.2 | 2.5 |
| Apparent output power |  | kVA | 0.9 | 1.2 | 1.6 | 2.2 |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | - | 1.6 | 2.1 | 3 |
| 4 kHz |  | A | 1.1 | 1.6 | 2.1 | 3 |
| 8 kHz |  | A | 1.1 | 1.6 | 2.1 | 3 |
| 16 kHz |  | A | 0.7 | 1.1 | 1.4 | 2 |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | - | 24 | 30 | 38 |
| 4 kHz |  | W | 20 | 25 | 32 | 40 |
| 8 kHz |  | W | 24 | 31 | 40 | 51 |
| 16 kHz |  | W | 24 | 31 | 40 | 51 |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 1.7 | 2.4 | 3.2 | 4.5 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 0.8 | 1.2 | 1.6 | 2.3 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 2.2 | 3.2 | 4.2 | 6 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 0.8 | 1.2 | 1.6 | 2.3 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 15 | 50 |  |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  | 3 |
| Category C 2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 15 |  |  | 20 |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 15 | 20 |  | 35 |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |


| Inverter |  |  | i510-C1.5/400-3 | i510-C2.2/400-3 | i510-C3.0/400-3 | i510-C4.0/400-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 1.5 | 2.2 | 3 | 4 |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 2 | 3 | 4 | 5 |
| Mains voltage range |  |  | 3/PE AC 340 V ... $528 \mathrm{~V}, 45 \mathrm{~Hz} \ldots 65 \mathrm{~Hz}$ |  |  |  |
| Output voltage |  |  | 3 AC 0-400/480 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 4.5 | 6.5 | 8 | 10.5 |
| with mains choke |  | A | 3.1 | 4.4 | 5.8 | 7.5 |
| Apparent output power |  | kVA | 2.6 | 3.8 | 4.9 | 6.4 |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | 3.5 | 4.8 | 6.3 | 8.2 |
| 4 kHz |  | A | 3.5 | 4.8 | 6.3 | 8.2 |
| 8 kHz |  | A | 3.5 | 4.8 | 6.3 | 8.2 |
| 16 kHz |  | A | 2.3 | 3.2 | 4.2 | 5.5 |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | 45 | 62 | 79 | 102 |
| 4 kHz |  | W | 48 | 66 | 85 | 110 |
| 8 kHz |  | W | 61 | 85 | 110 | 140 |
| 16 kHz |  | W | 61 | 85 | 109 | 140 |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 5.3 | 7.2 | 9.5 | 12.3 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | s | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 2.6 | 3.6 | 4.7 | 6.2 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 7 | 9.6 | 12.6 | 16.4 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 2.6 | 3.6 | 4.7 | 6.2 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 50 |  | 100 |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 3 |  | - |  |
| Category C2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 20 |  |  |  |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 35 |  |  |  |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |

## Technical data

3-phase mains connection 480 V
Rated data


Fusing data


A residual current device (RCD) is optional.
Fusing data for UL/NEC compliant installations: • Fusing data $\square 44$

| Inverter | Fuse |  |  | Circuit breaker |  |  | RCD |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Max. <br> SCCR | Characteristic | Max. rated <br> current | Max. <br> SCCR | Characteristic | Max. rated <br> current |  | Type |
|  | kA |  | A | kA |  | A | mA |  |
| i510-C0.37/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.55/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C0.75/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C1.1/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C1.5/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C2.2/400-3 | 65 | gG/gL, gRL | 16 | 65 | B, C | 16 | $\geq 30$ | Typ B |
| i510-C3.0/400-3 | 65 | gG/gL, gRL | 35 | 65 | B, C | 25 | $\geq 30$ | Typ B |
| i510-C4.0/400-3 | 65 | gG/gL, gRL | 35 | 65 | B, C | 25 | $\geq 30$ | Typ B |
| i510-C5.5/400-3 | 65 | gG/gL, gRL | 25 | 65 | B, C | 25 | $\geq 300$ | Typ B |
| i510-C7.5/400-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 30$ | Typ B |
| i510-C11/400-3 | 65 | gG/gL, gRL | 40 | 65 | B, C | 40 | $\geq 30$ | Typ B |

The connection data according to UL can be found under: • Connection according to UL $■ 43$

## Technical data

3-phase mains connection 480 V
Terminal data

## Terminal data

| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.37 ... 2. | 3 ... 4 | 5.5 | 7.5 ... 11 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Connection description |  |  | Mains connection |  |  |  |
| Connection |  |  | X100 |  |  |  |
| Connection type |  |  | Pluggable |  | Non-pluggable |  |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 2.5 | 4 | 6 | 16 |
| Max. Cable cross-section |  | AWG | 12 | 10 | 10 | 6 |
| Stripping length |  | mm | 8 | 8 | 9 | 11 |
| Stripping length |  | in | 0.3 | 0.3 | 0.35 | 0.43 |
| Tightening torque |  | Nm | 0.5 | 0.6 | 0.5 | 1.2 |
| Tightening torque |  | lb-in | 4.4 | 5.3 | 4.4 | 11 |
| Required tool |  |  | Screwdriver $0.5 \times 3.0$ |  | Screwdriver $0.6 \times 3.5$ | Screwdriver $0.8 \times 4.0$ |


| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | $\mathbf{0 . 3 7} \ldots \mathbf{5 . 5}$ | 7.5 ... 11 |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| Connection description |  |  | PE connection |  |  |
| Terminal type |  |  | Schraube |  |  |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 6 | 10 | 16 |
| Max. Cable cross-section |  | AWG | 10 | 6 |  |
| Stripping length |  | mm | 0.4 | 11 |  |
| Stripping length |  | in | 2 | 0.4 |  |
| Tightening torque |  | Nm | 18 | 3.4 |  |
| Tightening torque |  | Ib-in | Torx key 20 | 30 |  |
| Required tool |  |  |  | Crosstip screwdriver PZ2 |  |


| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 0.37 ... 4 | 5.5 | 7.5 ... 11 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Connection description |  |  | Motor connection |  |  |
| Connection |  |  | X105 |  |  |
| Connection type |  |  | Pluggable | Non-pluggable |  |
| Max. Cable cross-section |  | $\mathrm{mm}^{2}$ | 2.5 | 6 | 16 |
| Max. Cable cross-section |  | AWG | 12 | 10 | 6 |
| Stripping length |  | mm | 8 | 9 | 11 |
| Stripping length |  | in | 0.3 | 0.35 | 0.43 |
| Tightening torque |  | Nm | 0.5 | 0.5 | 1.2 |
| Tightening torque |  | Ib-in | 4.4 | 4.4 | 11 |
| Required tool |  |  | Screwdriver $0.5 \times 3.0$ | Screwdriver $0.6 \times 3.5$ | Screwdriver $0.8 \times 4.0$ |

The terminal data for the terminal X3 can be found under: $\downarrow$ Control connections $\mathbb{\square} 55$

## RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from $\square 138$
EMC filters can be used both in the side structure and in the substructure.

Maximum motor cable lengths with residual current device (RCD)

| Mains connection |  |  | 3-phase, $400 \mathrm{~V} / 480 \mathrm{~V}$ |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Inverter |  |  | i510-C0.37/400-3 | $\begin{aligned} & \text { i510-C0.55/400-3 } \\ & \text { i510-C0.75/400-3 } \end{aligned}$ | i510-C1.1/400-3 <br> i510-C1.5/400-3 <br> i510-C2.2/400-3 <br> i510-C3.0/400-3 <br> i510-C4.0/400-3 | $\begin{aligned} & \text { i510-C5.5/400-3 } \\ & \text { i510-C7.5/400-3 } \\ & \text { i510-C11/400-3 } \end{aligned}$ |
| Without RFI filter |  |  |  |  |  |  |
| Without EMC category Thermal limitation | Max. motor cable length shielded | m | 15 | 50 | 50 | 100 |
|  | Max. motor cable length unshielded | m | 30 | 100 | 200 | 200 |
| With integrated RFI filter |  |  |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | - | - | - | - |
| Category C2 |  | m | 15 | 15 | 20 | 20 |
|  | RCD (optional) | mA | 30 | 30 | 30 | 300 |
| RFI filter Low Leakage |  |  |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | - | - | - | - |
|  | RCD (optional) | mA | - | - | - | - |
| RFI filter Short Distance |  |  |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | 15 | 25 | 25 | 25 |
| Category C2 |  | m | 15 | 50 | 50 | 50 |
|  | RCD (optional) | mA | 30 | 30 | 30 | 30 |
| RFI filter Long Distance |  |  |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | 15 | 50 | 50 | 50 |
| Category C2 |  | m | 15 | 50 | 50 | 100 |
|  | RCD (optional) | mA | 300 | 300 | 300 | 300 |

## Short distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions (Hx W x D | Weight |  |  |  |  |  |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C0.37/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 15 | 4 | 15 | 4 | - | - |
| i510-C0.37/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 15 | 8 | 15 | 8 | - | - |
| i510-C0.37/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 15 | 16 | 15 | 16 | - | - |
| i510-C0.55/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 2 | 50 | 2 | - | - |
| i510-C0.55/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 4 | 50 | 4 | - | - |
| i510-C0.55/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 8 | 50 | 8 | - | - |
| i510-C0.55/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 16 | 50 | 16 | - | - |
| i510-C0.75/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 2 | 50 | 2 | - | - |
| i510-C0.75/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 4 | 50 | 4 | - | - |
| i510-C0.75/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 8 | 50 | 8 | - | - |
| i510-C0.75/400-3 | IOFAE175F100S0000S | 3.3 | $276 \times 60 \times 50$ | 0.82 | 25 | 16 | 50 | 16 | - | - |
| i510-C1.1/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 2 | 50 | 2 | - | - |
| i510-C1.1/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 4 | 50 | 4 | - | - |
| i510-C1.1/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 8 | 50 | 8 | - | - |
| i510-C1.1/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 16 | 50 | 16 | - | - |
| i510-C1.5/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 2 | 50 | 2 | - | - |
| i510-C1.5/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 4 | 50 | 4 | - | - |
| i510-C1.5/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 8 | 50 | 8 | - | - |
| i510-C1.5/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 16 | 50 | 16 | - | - |
| i510-C2.2/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 2 | 50 | 2 | - | - |
| i510-C2.2/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 4 | 50 | 4 | - | - |
| i510-C2.2/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 8 | 50 | 8 | - | - |
| i510-C2.2/400-3 | IOFAE222F100S0000S | 7.8 | $346 \times 60 \times 50$ | 1.01 | 25 | 16 | 50 | 16 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 2 | 50 | 2 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 4 | 50 | 4 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 8 | 50 | 8 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 16 | 50 | 16 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 2 | 50 | 2 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 4 | 50 | 4 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 8 | 50 | 8 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 16 | 50 | 16 | - | - |
| i510-C5.5/400-3 | IOFAE255F100S0001S | 18.3 | $346 \times 90 \times 60$ | 2.05 | 25 | 4 | 50 | 4 | - | - |
| i510-C5.5/400-3 | IOFAE255F100S0001S | 18.3 | $346 \times 90 \times 60$ | 2.05 | 25 | 8 | 50 | 8 | - | - |
| i510-C7.5/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 4 | 50 | 4 | - | - |
| i510-C7.5/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 8 | 50 | 8 | - | - |
| i510-C11/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 4 | 50 | 4 | - | - |
| i510-C11/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 8 | 50 | 8 | - | - |

In order to meet the EMC requirements according to EN IEC 61800-3, the lower of the screws marked "IT" on the product must be removed when using the filters listed below.

| Filters: | IOFAE240F100S0001S <br> IOFAE255F100S0001S <br> IOFAE311F100S0000S |
| :--- | :--- |
|  |  |



Long Distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions ( ${ }^{\text {x }}$ W x D $)$ | Weight | C1 |  | C2 |  | C3 |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C0.37/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 15 | 4 | 15 | 4 | - | - |
| i510-C0.37/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 15 | 8 | 15 | 8 | - | - |
| i510-C0.55/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 50 | 4 | 50 | 4 | - | - |
| i510-C0.55/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 50 | 8 | 50 | 8 | - | - |
| i510-C0.75/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 50 | 4 | 50 | 4 | - | - |
| i510-C0.75/400-3 | IOFAE175F100D0000S | 3.3 | $276 \times 60 \times 50$ | 0.86 | 50 | 8 | 50 | 8 | - | - |
| i510-C1.1/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 4 | 50 | 4 | - | - |
| i510-C1.1/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 8 | 50 | 8 | - | - |
| i510-C1.5/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 4 | 50 | 4 | - | - |
| i510-C1.5/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 8 | 50 | 8 | - | - |
| i510-C2.2/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 4 | 50 | 4 | - | - |
| i510-C2.2/400-3 | IOFAE222F100D0000S | 7.8 | $346 \times 60 \times 50$ | 1.03 | 50 | 8 | 50 | 8 | - | - |
| i510-C3.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 4 | 50 | 4 | - | - |
| i510-C3.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 8 | 50 | 8 | - | - |
| i510-C4.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 4 | 50 | 4 | - | - |
| i510-C4.0/400-3 | IOFAE240F100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 8 | 50 | 8 | - | - |
| i510-C5.5/400-3 | IOFAE255F100D0001S | 18.3 | $346 \times 90 \times 60$ | 1.65 | 50 | 4 | 100 | 4 | - | - |
| i510-C5.5/400-3 | IOFAE255F100D0001S | 18.3 | $346 \times 90 \times 60$ | 1.65 | 50 | 8 | 100 | 8 | - | - |
| i510-C7.5/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 4 | 100 | 4 | - | - |
| i510-C7.5/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 8 | 100 | 8 | - | - |
| i510-C11/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 4 | 100 | 4 | - | - |
| i510-C11/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 8 | 100 | 8 | - | - |

## Technical data

3-phase mains connection 480 V "Light Duty"
Rated data

## 3-phase mains connection 480 V "Light Duty"

## Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz : Ambient temperature above $40^{\circ} \mathrm{C}$ with a rated output current reduced by $2.5 \% /{ }^{\circ} \mathrm{C}$.
- If the load characteristic "Light Duty" and the switching frequencies 8 kHz or 16 kHz are selected, only the values of the load characteristic "Heavy Duty" are reached.

| Inverter |  |  | i510-C3.0/400-3 | i510-C4.0/400-3 | i510-C5.5/400-3 | i510-C7.5/400-3 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Rated power | $\mathbf{P}_{\text {rated }}$ | kW | 4 | 5.5 | 7.5 | 11 |
| Rated power | $\mathbf{P}_{\text {rated }}$ | hp | 5 | 7.5 | 10 | 15 |
| Mains voltage range |  |  | 3/PE AC $340 \mathrm{~V} \ldots 528 \mathrm{~V}, 45 \mathrm{~Hz} \ldots 65 \mathrm{~Hz}$ |  |  |  |
| Output voltage |  |  | 3 AC 0-400/480 V |  |  |  |
| Rated mains current |  |  |  |  |  |  |
| without mains choke |  | A | 8.6 | 11.2 | 15.3 | 22 |
| with mains choke |  | A | 6.8 | 8.8 | 12.1 | 17.2 |
| Apparent output power |  | kVA | 5.9 | 8 | 10.5 | 15 |
| Rated output current |  |  |  |  |  |  |
| 2 kHz |  | A | 7.6 | 9.8 | 13.2 | 18.3 |
| 4 kHz |  | A | 7.6 | 9.8 | 13.2 | 18.3 |
| 8 kHz |  | A | - |  |  |  |
| 16 kHz |  | A | - |  |  |  |
| Power loss |  |  |  |  |  |  |
| 2 kHz |  | W | 94 | 125 | 163 | 238 |
| 4 kHz |  | W | 100 | 133 | 173 | 253 |
| 8 kHz |  | W | - |  |  |  |
| 16 kHz |  | W | - |  |  |  |
| Overcurrent cycle 180 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 9.5 | 12.3 | 16.5 | 21 |
| Overload time | $\mathrm{T}_{1}$ | s | 60 | 60 | 60 | 60 |
| Recovery time | $\mathrm{T}_{2}$ | S | 120 | 120 | 120 | 120 |
| Max. output current during the recovery time |  | A | 4.7 | 6.2 | 8.3 | 10.5 |
| Overcurrent cycle 15 s |  |  |  |  |  |  |
| Max. output current ( $\leq 8 \mathrm{kHz}$ ) |  | A | 12.6 | 16.4 | 22 | 28 |
| Overload time | $\mathrm{T}_{1}$ | s | 3 | 3 | 3 | 3 |
| Recovery time | $\mathrm{T}_{2}$ | s | 12 | 12 | 12 | 12 |
| Max. output current during the recovery time |  | A | 4.7 | 6.2 | 8.3 | 10.5 |
| Cyclic mains switching |  |  | 3 times per minute |  |  |  |
| Brake chopper |  |  |  |  |  |  |
| Max. output current |  |  | - |  |  |  |
| Min. Brake resistor |  |  | - |  |  |  |
| Max. shielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | 100 |  |  |  |
| Category C1 ( $\leq 8 \mathrm{kHz}$ ) |  | m | - |  |  |  |
| Category C 2 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 20 |  |  |  |
| Category C3 ( $\leq 8 \mathrm{kHz}$ ) |  | m | 35 |  |  | 50 |
| Max. Unshielded motor cable length |  |  |  |  |  |  |
| without EMC category |  | m | - |  |  |  |

## Technical data

3-phase mains connection 480 V "Light Duty" Rated data


Fusing data


A residual current device（ $R C D$ ）is optional．
Fusing data for UL／NEC compliant installations：Fusing data $\square_{4}$

| Inverter | Fuse |  |  | Circuit breaker |  | RCD |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Max． <br> SCCR | Characteristic | Max．rated <br> current | Max． <br> SCCR | Characteristic | Max．rated <br> current |  | Type |
|  | kA |  | A | kA |  | A | mA |  |
| i510－C3．0／400－3 | 65 | gG／gL，gRL | 35 | 65 | B，C | 25 | $\geq 30$ | Typ B |
| i510－C4．0／400－3 | 65 | gG／gL，gRL | 35 | 65 | B，C | 25 | $\geq 30$ | Typ B |
| i510－C5．5／400－3 | 65 | gG／gL，gRL | 25 | 65 | B，C | 25 | $\geq 300$ | Typ B |
| i510－C7．5／400－3 | 65 | gG／gL，gRL | 40 | 65 | B，C | 40 | $\geq 30$ | Typ B |
| i510－C11／400－3 | 65 | gG／gL，gRL | 40 | 65 | B，C | 40 | $\geq 30$ | Typ B |

The connection data according to UL can be found under：$>$ Connection according to UL $\square 43$

## Terminal data

See＂3－phase mains connection 480 V＂－Terminal data $⿴ 囗 十 100$
The terminal data for the terminal X3 can be found under：$\downarrow$ Control connections $■ 55$

## Technical data

3-phase mains connection 480 V "Light Duty"
RFI filters / Mains filters

## RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from $\square 138$
EMC filters can be used both in the side structure and in the substructure.

Maximum motor cable lengths with residual current device (RCD)

| Mains connection |  |  | 3-phase, $400 \mathrm{~V} / 480 \mathrm{~V}$ |  |
| :---: | :---: | :---: | :---: | :---: |
| Inverter |  |  | i510-C3.0/400-3 | i510-C5.5/400-3 |
|  |  |  | i510-C4.0/400-3 | i510-C7.5/400-3 |
|  |  |  |  | i510-C11/400-3 |
| Without RFI filter |  |  |  |  |
| Without EMC category <br> Thermal limitation | Max. motor cable length shielded | m | 50 | 100 |
|  | Max. motor cable length unshielded | m | 200 | 200 |
| With integrated RFI filter |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | - | - |
| Category C2 |  | m | 20 | 20 |
|  | RCD (optional) | mA | 30 | 300 |
| RFI filter Low Leakage |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | - | - |
|  | RCD (optional) | mA | - | - |
| RFI filter Short Distance |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | 25 | 25 |
| Category C2 |  | m | 50 | 50 |
|  | RCD (optional) | mA | 30 | 30 |
| RFI filter Long Distance |  |  |  |  |
| Category C1 | Max. motor cable length shielded | m | 50 | 50 |
| Category C2 |  | m | 50 | 100 |
|  | RCD (optional) | mA | 100 | 300 |

Short distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions ( $\mathrm{H}^{\text {x W x D }}$ ) | Weight | C1 |  | C2 |  | C3 |  |
|  |  | A | mm | kg | m | kHz | m | kHz |  |  |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 2 | 50 | 2 | - | - |
| i510-C3.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 4 | 50 | 4 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 2 | 50 | 2 | - | - |
| i510-C4.0/400-3 | IOFAE240F100S0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 25 | 4 | 50 | 4 | - | - |
| i510-C5.5/400-3 | IOFAE255F100S0001S | 18.3 | $346 \times 90 \times 60$ | 2.05 | 25 | 4 | 50 | 4 | - | - |
| i510-C7.5/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 4 | 50 | 4 | - | - |
| i510-C11/400-3 | IOFAE311F100S0000S | 29 | $371 \times 120 \times 60$ | 2.35 | 25 | 4 | 50 | 4 | - | - |

In order to meet the EMC requirements according to EN IEC 61800-3, the lower
of the screws marked "IT" on the product must be removed when using the filters listed below.

|  |  |
| :--- | :--- |
| Filters: | IOFAE240F100S0001S  <br>  IOFAE255F100S0001S <br>  IOFAE311F100S0000S |
|  |  |



Long distance filter

| Inverter | Filter |  |  |  | Max. shielded motor cable length |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Order code | Rated current | Dimensions (H x W x D) | Weight | $\mathbf{c \|}$ | $\mathbf{C 2}$ | $\mathbf{C 3}$ |  |  |  |
|  |  | $\mathbf{A}$ | $\mathbf{m m}$ | $\mathbf{k g}$ | $\mathbf{m}$ | $\mathbf{k H z}$ | $\mathbf{m}$ | $\mathbf{k H z}$ |  |  |
| i510-C3.0/400-3 | IOFAE24OF100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 4 | 50 | 4 | - | - |
| i510-C4.0/400-3 | IOFAE24OF100D0001S | 14 | $346 \times 60 \times 50$ | 1.42 | 50 | 4 | 50 | 4 | - | - |
| i510-C5.5/400-3 | IOFAE255F100D0001S | 18.3 | $346 \times 90 \times 60$ | 1.65 | 50 | 4 | 100 | 4 | - | - |
| i510-C7.5/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 4 | 100 | 4 | - | - |
| i510-C11/400-3 | IOFAE311F100D0000S | 29 | $371 \times 120 \times 60$ | 2.05 | 50 | 4 | 100 | 4 | - | - |

## Ecodesign Directive

Product information acc. to REGULATION (EU) 2019/1781 (ANNEX I, Section 4)

## Legend

Operating point (f; I) f=relative motor stator frequency; I = relative torque-producing current
Power losses
The power losses at the operating points ( $f$; $I$ ) and in the standby state refer to the rated apparent output power. The power losses for options (e.g. for diagnostics) and for accessories can be found in the additional product documentation on the Internet.

| Performance losses |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0; 25 | f; I | \% | 2.2 | 2.2 | 1.8 | 1.8 | 1.6 | 1.8 | 1.1 | 1.1 |
| 0; 50 | f; I | \% | 2.2 | 2.2 | 1.8 | 1.8 | 1.7 | 1.8 | 1.2 | 1.2 |
| 0; 100 | f; I | \% | 2.4 | 2.4 | 2.0 | 2.0 | 1.9 | 2.1 | 1.5 | 1.6 |
| 50; 25 | f; I | \% | 2.2 | 2.3 | 1.8 | 1.8 | 1.7 | 1.9 | 1.1 | 1.1 |
| 50; 50 | f; I | \% | 2.3 | 2.3 | 1.9 | 1.9 | 1.7 | 1.9 | 1.3 | 1.3 |
| 50; 100 | f; I | \% | 2.6 | 2.6 | 2.2 | 2.2 | 2.1 | 2.3 | 1.7 | 1.7 |
| 90; 50 | f; I | \% | 2.4 | 2.4 | 2.0 | 2.0 | 1.8 | 2.0 | 1.3 | 1.4 |
| 90; 100 | f; I | \% | 2.9 | 2.8 | 2.5 | 2.4 | 2.3 | 2.4 | 1.9 | 1.9 |
| In standby mode |  | \% | 0.9 | 0.9 | 0.6 | 0.6 | 0.5 | 0.5 | 0.4 | 0.4 |
| Efficiency level |  |  | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 |
| Manufacturer |  |  | Lenze SE • Hans-Lenze-Str. 1-31855 Aerzen • GERMANY |  |  |  |  |  |  |  |
| Commercial register number |  |  | Hannover HRB 204803 |  |  |  |  |  |  |  |
| Model identifier of the product |  |  | I51AE125B | I51AE125D | 151AE137B | I51AE137D | I51AE155B | I51AE155D | I51AE175B | I51AE175D |
| Apparent output power |  | kVA | 0.6 | 0.6 | 0.9 | 0.9 | 1.2 | 1.2 | 1.6 | 1.6 |
| Indicative rated output power of the motor |  | kW | 0.25 | 0.25 | 0.37 | 0.37 | 0.55 | 0.55 | 0.75 | 0.75 |
| Rated output current |  | A | 1.7 | 1.7 | 2.4 | 2.4 | 3.2 | 3.2 | 4.2 | 4.2 |
| Maximum operating temperature |  | ${ }^{\circ} \mathrm{C}$ | 45 |  |  |  |  |  |  |  |
| Rated input frequency |  | Hz | 50 |  |  |  |  |  |  |  |
| Rated input voltage |  | V | 230 |  |  |  |  |  |  |  |
| Switching frequency |  | kHz | 4 |  |  |  |  |  |  |  |
| Rated apparent output power |  | kVA | 0.697 | 0.697 | 0.977 | 0.977 | 1.19 | 1.19 | 1.71 | 1.71 |


| Performance losses |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0; 25 | f; I | \% | 0.9 | 1.1 | 0.8 | 1.0 | 0.8 | 0.9 | 1.1 | 0.7 |
| 0; 50 | f; I | \% | 1.1 | 1.3 | 0.9 | 1.1 | 1.0 | 1.1 | 1.3 | 1.0 |
| 0; 100 | f; I | \% | 1.4 | 1.6 | 1.2 | 1.4 | 1.3 | 1.4 | 1.8 | 1.7 |
| 50; 25 | f; I | \% | 1.0 | 1.2 | 0.8 | 1.0 | 0.9 | 1.0 | 1.2 | 0.8 |
| 50; 50 | f; I | \% | 1.1 | 1.4 | 1.0 | 1.2 | 1.1 | 1.2 | 1.5 | 1.1 |
| 50; 100 | f; I | \% | 1.6 | 1.8 | 1.4 | 1.6 | 1.6 | 1.6 | 2.2 | 1.9 |
| 90; 50 | f; I | \% | 1.2 | 1.4 | 1.1 | 1.3 | 1.2 | 1.3 | 1.6 | 1.2 |
| 90; 100 | f; I | \% | 1.9 | 2.0 | 1.7 | 1.8 | 1.9 | 1.9 | 2.5 | 2.3 |
| In standby mode |  | \% | 0.3 | 0.3 | 0.2 | 0.2 | 0.1 | 0.1 | 0.1 | 0.1 |
| Efficiency level |  |  | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 |
| Manufacturer |  |  | Lenze SE • Hans-Lenze-Str. 1-31855 Aerzen • GERMANY |  |  |  |  |  |  |  |
| Commercial register number |  |  | Hannover HRB 204803 |  |  |  |  |  |  |  |
| Model identifier of the product |  |  | 151AE211B | 151AE211D | I51AE215B | I51AE215D | 151AE222B | I51AE222D | I51AE240C | 151AE255C |
| Apparent output power |  | kVA | 2.2 | 2.2 | 2.6 | 2.6 | 3.6 | 3.6 | 6.4 | 8.7 |
| Indicative rated output power of the motor |  | kW | 1.1 | 1.1 | 1.5 | 1.5 | 2.2 | 2.2 | 4 | 5.5 |
| Rated output current |  | A | 6 | 6 | 7 | 7 | 9.6 | 9.6 | 16.5 | 23 |
| Maximum operating temperature |  | ${ }^{\circ} \mathrm{C}$ | 45 |  |  |  |  |  |  |  |
| Rated input frequency |  | Hz | 50 |  |  |  |  |  |  |  |
| Rated input voltage |  | V | 230 |  |  |  |  |  |  |  |
| Switching frequency |  | kHz | 4 |  |  |  |  |  |  |  |
| Rated apparent output power |  | kVA | 2.29 | 2.29 | 3.3 | 3.3 | 4.44 | 4.44 | 7.38 | 9.95 |


| Performance losses |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0; 25 | f; I | \% | 3.1 | 3.3 | 2.2 | 1.9 | 1.2 | 1.1 | 1.4 | 1.2 |
| 0; 50 | f; I | \% | 3.1 | 3.4 | 2.3 | 2.0 | 1.3 | 1.3 | 1.5 | 1.3 |
| 0; 100 | f; I | \% | 3.3 | 3.6 | 2.6 | 2.3 | 1.6 | 1.6 | 1.9 | 1.7 |
| 50; 25 | f; I | \% | 3.1 | 3.4 | 2.2 | 1.9 | 1.3 | 1.2 | 1.4 | 1.2 |
| 50; 50 | f; I | \% | 3.2 | 3.4 | 2.4 | 2.1 | 1.4 | 1.3 | 1.6 | 1.4 |
| 50; 100 | f; I | \% | 3.5 | 3.7 | 2.8 | 2.5 | 1.8 | 1.8 | 2.0 | 1.9 |
| 90; 50 | f; I | \% | 3.3 | 3.5 | 2.5 | 2.2 | 1.5 | 1.5 | 1.6 | 1.5 |
| 90; 100 | f; I | \% | 3.7 | 3.9 | 2.9 | 2.8 | 2.1 | 2.1 | 2.1 | 2.0 |
| In standby mode |  | \% | 0.6 | 0.5 | 0.4 | 0.3 | 0.2 | 0.1 | 0.1 | 0.1 |
| Efficiency level |  |  | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 | IE2 |
| Manufacturer |  |  | Lenze SE • Hans-Lenze-Str. 1-31855 Aerzen • GERMANY |  |  |  |  |  |  |  |
| Commercial register number |  |  | Hannover HRB 204803 |  |  |  |  |  |  |  |
| Model identifier of the product |  |  | I51AE137F | I51AE155F | I51AE175F | I51AE211F | I51AE215F | I51AE222F | 151BE230F | I51BE240F |
| Apparent output power |  | kVA | 0.9 | 1.2 | 1.6 | 2.2 | 2.6 | 3.8 | 4.9 | 6.4 |
| Indicative rated output power of the motor |  | kW | 0.37 | 0.55 | 0.75 | 1.1 | 1.5 | 2.2 | 3 | 4 |
| Rated output current |  | A | 1.3 | 1.8 | 2.4 | 3.2 | 3.9 | 5.6 | 7.3 | 9.5 |
| Maximum operating temperature |  | ${ }^{\circ} \mathrm{C}$ | 45 |  |  |  |  |  |  |  |
| Rated input frequency |  | Hz | 50 |  |  |  |  |  |  |  |
| Rated input voltage |  | V | 400 |  |  |  |  |  |  |  |
| Switching frequency |  | kHz | 4 |  |  |  |  |  |  |  |
| Rated apparent output power |  | kVA | 0.977 | 1.19 | 1.71 | 2.29 | 3.3 | 4.44 | 5.85 | 7.38 |


| Performance losses |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0; 25 | f; I | \% | 1.0 | 0.7 | 0.5 |
| 0; 50 | f; I | \% | 1.1 | 0.8 | 0.7 |
| 0; 100 | f; I | \% | 1.6 | 1.2 | 1.0 |
| 50; 25 | f; I | \% | 1.0 | 0.7 | 0.6 |
| 50; 50 | f; I | \% | 1.2 | 0.9 | 0.7 |
| 50; 100 | f; I | \% | 1.7 | 1.4 | 1.2 |
| 90; 50 | f; I | \% | 1.2 | 0.9 | 0.8 |
| 90; 100 | f; I | \% | 1.9 | 1.6 | 1.4 |
| In standby mode |  | \% | 0.1 | 0.0 | 0.0 |
| Efficiency level |  |  | IE2 | IE2 | IE2 |
| Manufacturer |  |  | Lenze SE • Hans-Lenze-Str. 1-31855 Aerzen • GERMANY |  |  |
| Commercial register number |  |  | Hannover HRB 204803 |  |  |
| Model identifier of the product |  |  | I51AE255F | I51BE275F | I51BE311F |
| Apparent output power |  | kVA | 8.7 | 11 | 16 |
| Indicative rated output power of the motor |  | kW | 5.5 | 7.5 | 11 |
| Rated output current |  | A | 13 | 16.5 | 23.5 |
| Maximum operating temperature |  | ${ }^{\circ} \mathrm{C}$ |  | 45 |  |
| Rated input frequency |  | Hz |  | 50 |  |
| Rated input voltage |  | V |  | 400 |  |
| Switching frequency |  | kHz |  | 4 |  |
| Rated apparent output power |  | kVA | 9.95 | 14.4 | 19.5 |

## Dimensions



The specified installation clearances are minimum dimensions to ensure a sufficient air circulation for cooling purposes. They do not consider the bend radiuses of the connecting cables.

Several i5xx frequency inverters can be mounted directly next to each other, regardless of the device size. No installation clearance is required between the devices.

## Installation clearances

- Maintain the specified installation clearances above and below to the other installations.
- Several devices of the same series can be lined up directly, regardless of the device size. No installation clearance is required between the devices.


## Technical data

Dimensions
0.25 kW ... 0.37 kW

The dimensions in mm apply to:

| 0.25 kW | i510-C0.25/230-1 | i510-C0.25/230-2 |  |
| :--- | :--- | :--- | :--- |
| 0.37 kW | i510-C0.37/230-1 | i510-C0.37/230-2 | i510-C0.37/400-3 |
| Weight | 0.75 kg | 0.75 kg | 0.75 kg |


$0.33 \mathrm{hp} . . .0 .5 \mathrm{hp}$
The dimensions in inch apply to:

| 0.33 hp | i510-C0.25/230-1 | i510-C0.25/230-2 |  |
| :--- | :--- | :--- | :--- |
| 0.5 hp | i510-C0.37/230-1 | i510-C0.37/230-2 | i510-C0.37/400-3 |
| Weight | 1.7 lb | 1.7 lb | 1.7 lb |



8800305

## Technical data

Dimensions
0.55 kW ... 0.75 kW

The dimensions in mm apply to:

| 0.55 kW | i510-C0.55/230-1 | i510-C0.55/230-2 | i510-C0.55/400-3 |
| :--- | :--- | :--- | :--- |
| 0.75 kW | i510-C0.75/230-1 | i510-C0.75/230-2 | i510-C0.75/400-3 |
| Weight | 0.95 kg | 0.95 kg | 0.95 kg |


0.75 hp ... 1 hp

The dimensions in inch apply to:

| 0.75 hp | i510-C0.55/230-1 | i510-C0.55/230-2 | i510-C0.55/400-3 |
| :--- | :--- | :--- | :--- |
| 1 hp | i510-C0.75/230-1 | i510-C0.75/230-2 | i510-C0.75/400-3 |
| Weight | 2.1 lb | 2.1 lb | 2.1 lb |



8800306

## Technical data

Dimensions

## 1.1 kW ... 4 kW

The dimensions in mm apply to:

| 1.1 kW | i510-C1.1/230-1 | i510-C1.1/230-2 | i510-C1.1/400-3 |  |
| :--- | :--- | :--- | :--- | :--- |
| 1.5 kW | i510-C1.5/230-1 | i510-C1.5/230-2 | i510-C1.5/400-3 |  |
| 2.2 kW | i510-C2.2/230-1 | i510-C2.2/230-2 | i510-C2.2/400-3 |  |
| 3 kW |  |  |  | i510-C3.0/400-3 |
| 4 kW |  |  |  | i510-C4.0/400-3 |
| Weight | 1.35 kg | 1.35 kg | 1.35 kg | 1.35 kg |



8800272
$1.5 \mathrm{hp} . . .5 \mathrm{hp}$
The dimensions in inch apply to:

| 1.5 hp | i510-C1.1/230-1 | i510-C1.1/230-2 | i510-C1.1/400-3 |  |
| :--- | :--- | :--- | :--- | :--- |
| 2 hp | i510-C1.5/230-1 | i510-C1.5/230-2 | i510-C1.5/400-3 |  |
| 3 hp | i510-C2.2/230-1 | i510-C2.2/230-2 | i510-C2.2/400-3 |  |
| 4 hp |  |  |  | i510-C3.0/400-3 |
| 5 hp |  |  |  | i510-C4.0/400-3 |
| Weight | 3 lb | 3 lb | 3 lb | 3 lb |



## 4 kW ... 5.5 kW

The dimensions in mm apply to:

| 4 kW | i510-C4.0/230-3 |  |
| :--- | :--- | :--- |
| 5.5 kW | i510-C5.5/230-3 | i510-C5.5/400-3 |
| Weight | 2.1 kg | 2.3 kg |




8800599
$5 \mathrm{hp} . . .7 .5 \mathrm{hp}$
The dimensions in inch apply to:

| 5 hp | i510-C4.0/230-3 |  |
| :--- | :--- | :--- |
| 7.5 hp | i510-C5.5/230-3 | i510-C5.5/400-3 |
| Weight | 4.6 lb | 5 lb |




8800601

Technical data
Dimensions
7.5 kW ... 11 kW

The dimensions in mm apply to:

| 7.5 kW | i510-C7.5/400-3 |
| :--- | :--- |
| 11 kW | i510-C11/400-3 |
| Weight | 3.7 kg |



8800600
$10 \mathrm{hp} . .15 \mathrm{hp}$
The dimensions in inch apply to:

| 10 hp | i510-C7.5/400-3 |
| :--- | :--- |
| 15 hp | i510-C11/400-3 |
| Weight | 8 lb |




## Product extensions

## Overview

The inverters can easily be integrated into the machine. The scalable product extensions serve to flexibly match the required functions to your application.

The integrated standard product extension for the i510 inverter is the control unit with basic I/O.
As the control unit cannot be extended, the i510 inverter is available in two versions:

- With CANopen/Modbus, switchable.
- Without network.

In order to provide a largely uniform documentation, all information and data of the control unit with basic I/O are contained here in the "product extension" chapter.


Inverter without network


Inverter with CAN open and Modbus

## I/O extensions

## Basic I/Os

The basic I/O provides the inverter analog and digital inputs and outputs and is designed for simple applications.
The basic I/O can be purchased with or without the CANopen and Modbus networks. A switch can be used to select between the two networks.


Description of the control terminals

| Input/output | Terminal X3 | Information |
| :---: | :---: | :---: |
| Digital inputs | DI1, DI2, DI3, DI4, DI5 | DI3/DI4 can be optionally used as frequency or encoder input. HIGH active/LOW active switchable LOW $=0 \ldots+3 \mathrm{~V}$, HIGH = +12 V ... +30 V |
|  | DO1 | Digital output (max. 100 mA ) |
| Analog outputs | Al1, Al2 | Can be optionally used as voltage input or current input. |
|  | AO1 | Can be optionally used as voltage output or current output. |
| 10-V output | 10 V | Primarily for the supply of a potentiometer ( $1 \ldots 10 \mathrm{k} \Omega$ ). Max. 10 mA |
| 24-V output | 24 V | Primarily for the supply of digital inputs. (Max. 100 mA ) |
| Reference potential | GND |  |
| Connection system | Plug-in spring terminal |  |

## Product extensions

I/O extensions
Data of control connections

## Data of control connections

Digital inputs

| Switching type |  | PNP |  |
| :--- | :--- | :--- | :--- |
| PNP switching level |  |  |  |
| LOW | V | $<+5$ | IEC 61131-2, type 1 |
| HIGH | V | $>+15$ |  |
| Input resistance | $\mathrm{k} \Omega$ | 4.6 | can be changed by software filtering |
| Cycle time | ms | 1 |  |
| Electric strength of external <br> voltage | V | $\pm 30$ |  |

## Digital outputs

| Switching level |  |  |  |
| :--- | :--- | :--- | :--- |
| LOW | V | $<+5$ | IEC 61131-2, type 1 |
| HIGH | V | $>+15$ | Total current for DO1 and 24V |
| max. output current | mA | 100 |  |
| Cycle time | ms | 1 |  |
| Short-circuit strength |  | Unlimited period |  |
| Electric strength of external <br> voltage | V | $\pm 30$ | LOW |
| Polarity reversal protection |  | Integrated freewheeling diode for switching the <br> inductive load |  |
| Overload behaviour |  | Reduced voltage or periodic switch-off/on |  |
| Reset or switch-on behaviour |  | Output is switched off |  |

## Analog inputs

| Cycle time | ms | 1 |  |
| :---: | :---: | :---: | :---: |
| Resolution of $A / D$ converter | Bit | 12 |  |
| Operation as voltage input |  |  |  |
| Connection designation |  | X3/Al1, X3/AI2 |  |
| Input voltage DC | V | 0 ... 10 |  |
| Input resistance | k $\Omega$ | 70 |  |
| Accuracy | mV | $\pm 50$ | Typical |
| Input voltage in case of open circuit | V | - 0.2 ... 0.2 | Display "0" |
| Electric strength of external voltage | V | $\pm 24$ |  |
| Operation as current input |  |  |  |
| Connection designation |  | X3/Al1, X3/AI2 |  |
| Input current | mA | 0 ... 20 |  |
|  |  | 4 ... 20 | open-circuit monitored |
| Accuracy | mA | $\pm 0.1$ | Typical |
| Input current in case of open circuit | mA | < 0.1 | Display "0" |
| Input resistance | $\Omega$ | < 250 |  |
| Electric strength of external voltage | V | $\pm 24$ |  |

Analog outputs

| Short-circuit strength |  | Unlimited period |  |
| :--- | :--- | :--- | :--- |
| Electric strength of external <br> voltage | V | +24 V |  |
| Operation as voltage output |  |  |  |
| Resolution of D/A converter | Bit | 12 |  |
| Output voltage DC | V | $0 \ldots 10$ |  |
| max. output current | mA | 5 |  |
| min. load resistance | $\mathrm{k} \Omega$ | $\geq 2.2$ | Typical |
| max. capacitive load | $\mu \mathrm{F}$ | 1 |  |
| Accuracy | mV | $\pm 100$ |  |
| Operation as current output |  |  | open-circuit monitored |
| Output current | mA | $0 \ldots 20$ | Typical |

10-V output

| Use |  | Primarily for the supply of a potentiometer (1 .. <br> $10 \mathrm{k} \Omega$ |  |
| :--- | :--- | :--- | :--- |
| Output voltage DC |  |  |  |
| Typical | V | 10 |  |
| Accuracy | mV | $\pm 100$ |  |
| Max. output current | mA | 10 |  |
| Max. capacitive load | $\mu \mathrm{F}$ | 1 |  |
| Short-circuit strength |  | Unlimited period |  |
| Electric strength of external <br> voltage | V | +24 |  |

24-V output

| Use |  | Primarily for the supply of digital inputs | SELV/PELV |
| :--- | :--- | :--- | :--- |
| Output voltage DC |  |  |  |
| Typical | V | 24 |  |
| Area | V | $16 \ldots 28$ |  |
| max. output current | mA | 100 | Total current for DO... and 24V |
| Short-circuit strength |  | Unlimited period |  |
| Electric strength of external <br> voltage | V | +30 |  |
| Excess current release |  | Automatically resettable |  |

## Further control connections

## Relay output

Use a corresponding suppressor circuit in case of an inductive or capacitive load!

| Connection |  |  | Terminal X9: COM | Common contact (Common) |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Terminal X9: NC | Normally closed contact |
|  |  |  | Terminal X9: NO | Normally open contact |
| Minimum DC contact load |  |  |  |  |
|  | Voltage | V | 10 | A correct switching of the relay contacts needs both values to be exceeded simultaneously. |
|  | Current | mA | 10 |  |
| Switching voltage/switching current |  |  |  |  |
| Maximum | AC 240 V | A | 3 | According to UL: General Purpose |
|  | 24 V DC | A | 2 | According to UL: Resistive |
|  | 240 V DC | A | 0.16 |  |



## Networks

The integrated standard product extension for the i510 inverter is the control unit with basic I/O.
As the control unit cannot be extended, the i510 inverter is available in two versions:

- With CANopen/Modbus, switchable.
- Without network.


## Product extensions

Networks
CANopen

## CANopen

CANopen is an internationally approved communication protocol which is designed for commercial and industrial automation applications. High data transfer rates in connection with efficient data formatting provide for the coordination of motion control devices in multiaxis applications.

| Bus-related information |  |  |  |
| :--- | :--- | :--- | :--- |
| CANopen CiA 301 V4.2.0 |  |  |  |
| Commenication medium |  | CAN cable in accordance with ISO 11898-2 |  |
| Use |  | Connection of inverter to a CANopen <br> network |  |
| Connection system |  | Pluggable double spring terminal |  |
| Status display |  | 2 LEDs |  |
| Connection designation |  | X216: CH, CL, CG |  |


| Technical data |  |  |  |
| :---: | :---: | :---: | :---: |
| Bus terminating resistor | $\Omega$ | 120 | Terminated on both sides |
| Integrated bus terminating resistor |  | No |  |
| Network topology |  |  |  |
| Without repeater |  | Line |  |
| With repeater |  | Line or tree |  |
| Device |  |  |  |
| Type |  | Slave |  |
| Max. number without repeater |  | 127 | Per bus segment, incl. host system |
| Address |  | 1 ... 127 | Adjustable via code |
| Baud rate | kbps | 20,50, 125, 250, 500, 800 or 1000 | Adjustable via code |
| Max. bus length | m | 2500, 1000, 500, 250, 100, 50 or 25 | Total cable length depends on the baud rate |
| Max. cable length between two devices |  | Not limited, the max. bus length is decisive |  |
| Process data |  |  |  |
| Transmit PDOs |  | 3 TPDOs with 1 ... 8 Byte (adjustable) |  |
| Receive PDOs |  | 3 RPDOs with 1 ... 8 bytes (adjustable) |  |
| Transmission mode for TPDOs |  |  |  |
| With change of data |  | Yes |  |
| Time-controlled, multiple of | ms | 10 |  |
| After reception |  | 1 ... 240 sync telegrams |  |
| Parameter data |  |  |  |
| SDO channels |  | Max. 2 servers |  |


| Communication time |  |  |
| :---: | :---: | :---: |
| Communication time depends on | Processing time in the inverter | Time between start of a request and arrival of response |
|  | Telegram runtime (baud rate, telegram length) |  |
|  | Nesting depth of network |  |
|  | Bus load |  |


| Processing time of process data |  |  |  |
| :--- | :--- | :--- | :--- |
| Update cycle | ms | 10 | In inverter |
| Processing time | ms | $0 \ldots 1$ |  |
| Application task runtime of the technology <br> application used (tolerance) | ms | $1 \ldots \mathrm{x}$ |  |

[^1]
## Modbus RTU

Modbus is an internationally approved, asynchronous, serial communication protocol, designed for commercial and industrial automation applications.

| Bus-related information |  |  |  |
| :--- | :--- | :--- | :--- |
| Nodbe |  | RS485 (EIA) |  |
| Communication medium |  | Connection of inverter to a Modbus <br> network |  |
| Use |  | Pluggable double spring terminal |  |
| Connection system |  | 2 LEDs |  |
| Status display |  | X216: TA, TB, COM |  |
| Connection designation |  |  |  |


| Technical data |  |  |  |
| :---: | :---: | :---: | :---: |
| Communication profile |  | Modbus RTU |  |
| Bus terminating resistor | $\Omega$ | 120 | Terminated on both sides |
| Integrated bus terminating resistor |  | No |  |
| Network topology |  |  |  |
| Without repeater |  | Line |  |
| Device |  |  |  |
| Type |  | Slave |  |
| Max. number without repeater |  | 32 | Per bus segment, incl. host system |
| Max. number with repeater |  | 90 |  |
| Address |  | 1 ... 247 | Adjustable via code |
| Baud rate | kbps | 4.8 ... 115 | Adjustable via code |
| Max. cable length | m | 12 ... 600 | Per bus segment, depending on the baud rate and the used cable type |
| Max. cable length between two devices |  | Not limited, the max. bus length is decisive |  |
| Data channel |  |  |  |
| SDO channels |  | Max. 2 servers, with 1 ... 8 bytes | Supported functions: Read Holding Registers Preset Single Register Preset Multiple Registers Read/Write 4 x registers |


| Communication time |  |  |
| :---: | :---: | :---: |
| Communication time depends on | Processing time in the inverter | Time between start of a request and arrival of response |
|  | Telegram runtime (baud rate, telegram length) |  |
|  | Nesting depth of network |  |
|  | Bus load |  |


| Processing time of process data |  |  |  |
| :--- | :--- | :--- | :--- |
| Update cycle | ms | 1 | In the inverter |
| Processing time | ms | $0 \ldots 1$ |  |
| Application task runtime of the technology <br> application used (tolerance) | ms | $1 \ldots \mathrm{x}$ |  |


| Other data |
| :--- |
| Note: There are no interdependencies between parameter data and process data. |

Accessories
Overview

## Accessories

## Overview

A package of accessories optimally matched to the inverter is available for your applications.
Moreover, the pluggable modules make commissioning and diagnostics easier.


Further accessories: DIN rail

## Operation and diagnostics

## Keypad

Parameter setting and diagnostics
Thanks to the intuitive operating structure, the navigation keys allow a quick and easy access to the most important parameters, either to configure functions or to query current values.
Parameters and actual values are indicated on the easy-to-read display.


## Keypad

| Order code | Type |
| :--- | :--- |
| I5MADK0000000s | LCD display <br> Display in German/English |

## External keypad

Installation in user interface
The external keypad kit facilitates installation of a I5MADK000000S keypad in an IP65 housing for mounting to the control cabinet wall.


| External keypad kit | Type |
| :--- | :--- |
| Order code | without connecting cable <br> with connecting cable 3 m <br> I5MADR0000000S <br> I5MADR0000001S |
| I5MADR0000002S | with connecting cable 5 m |
| The I5MADK000000S keypad is not part of the delivery. |  |

## Accessories

Operation and diagnostics
USB module

## USB module

Interface to the PC
Connect the inverter via a USB 2.0 connection cable to a PC on which the Lenze "EASY Starter" engineering tool is installed. Configure the inverter with the "EASY Starter" using graphical user interfaces. You can create diagnostics with trend functions or observe parameter values.
Parameterising without supplying the inverter with voltage: in many cases, the USB interface of the PC is sufficient for the voltage supply if you connect the inverter directly to the PC without a hub.


| USB module |  |
| :--- | :--- |
| Order code | Version |
| I5MADU0000000S | Parameterization without voltage supply of the inverter is possible. <br> USB 2.0 connecting cable required |

Connecting cable

| Order code | Length | Type |
| :--- | :--- | :--- |
| EWL0085/S | 3 m | USB 2.0-connecting cable (A-plug to micro B-plug) |
| EWL0086/S | 5 m |  |

## WLAN module

Communicate wirelessly with the inverter, via a PC using the Lenze Engineering Tool "EASY Starter" or the Lenze "SMART Keypad App" for Android and iOS smartphones.


## AWARNING!

- This product contains FCC ID: QOQWF121/IC: 5123A-BGTWF121
- To comply with FCC and Industry Canada RF radiation exposure limits for general population, the transmitter with its antenna must be installed such that a minimum separation distance of 20 cm is maintained between the radiator (antenna) and all persons at all times.
- This product must not be collocated or operated in conjunction with any other antenna or transmitter.
- Le produit contient un module transmetteur certifié FCC ID: QOQWF121/IC: 5123ABGTWF121
- Afin de se conformer aux réglementations de la FCC et d'Industry Canada relatives aux limites d'exposition aux rayonnements RF pour le grand public, le transmetteur et son antenne doivent être installés de sorte qu'une distance minimale de 20 cm soit constamment maintenue entre le radiateur (antenne) et toute personne.
Le produit ne doit pas être utilisé en combinaison avec d’autres antennes ou transmetteurs.

The module can be used if the certification is recognized in a country according to one of these standards.

| Conformity and approvals |  |  |
| :--- | :--- | :--- |
| CE | RED | EN 301489-1 V2.1.1:2016 |
|  |  | EN 301489-17 V3.1.1:2016 |
|  | EN 300328 V2.1.1:2016 |  |
| FCC | Part 15.107/15.109 <br> ICES-003 |  |

Additional conformities and approvals:

- IC
- CMIIT

| LED status displays |  |  |  |  | LED 2 | LED 3 |  |
| :---: | :---: | :---: | :--- | :---: | :---: | :---: | :---: |
| LED 1 | TX/RX (yellow) | WLAN (green) |  |  |  |  |  |
| Power (green) | Communication status | WLAN status |  |  |  |  |  |
| Supply voltage status | OFF | OFF | No voltage |  |  |  |  |
| OFF | ON | ON | Self-test (approx. 1 s) |  |  |  |  |
| ON | OFF | OFF | Ready for operation <br> No active WLAN connection |  |  |  |  |
| ON | Flashing | ON | Communication active |  |  |  |  |
| ON | OFF | Blinking | Client Mode <br> Waiting for connection |  |  |  |  |
| ON | OFF | OFF | Trouble |  |  |  |  |

## Accessories

Operation and diagnostics
Blanking cover

| Connection data (default setting) |  |
| :--- | :--- |
| IP address | 192.168 .178 .1 |
| SSID | <Product type>_<10-digit identifier> |
| Password | password |


| WLAN module |  |
| :--- | :--- |
| Order code | Type |
| I5MADW0000000S | Range in open space: 100 m , conditions on site may restrict the range. |

## Blanking cover

## Protection and optics

The blanking cover protects the terminals and provides for uniform optics if no other module is plugged on.


| Blanking cover | Type |  |
| :--- | :--- | :--- |
| Order code |  | VPE |
|  | Protection against dust <br> Uniform optics | Piece |
| I5ZAA0000M | 4 |  |

## Control and display elements

## Potentiometer

For the external selection of an analog setpoint.
The setpoint selection (e.g. motor speed) can be manually set via the external potentiometer.
The potentiometer is connected to the analog input terminals of the inverter.
The position is displayed on the scale via the rotary knob.
The components have to be ordered separately.


| Potentiometer |  | Name |
| :--- | :--- | :--- |
| Order code | Potentiometer | Type |
| ERPD0010K0001W | Rotary knob | $10 \mathrm{k} \Omega / 1 \mathrm{~W}$ |
| ERZO001 | Scale | Diameter 36 mm |
| ERZO002 |  | Scale $0 \ldots 100 \%$, <br> Diameter 62 mm |

## Memory modules

For standard set-up, Lenze offers its customers multipacked, unwritten memory modules (EPM). In combination with the EPM copier, the EPMs can be duplicated at any location.

A memory module is included in the scope of supply of the inverter.


| Memory module | Type | VPE |
| :--- | :--- | :--- |
| Order code |  | Piece |
|  | Easily pluggable <br> Duplicate data set with memory module copier | 12 |

## Memory module copier

For duplicating data on memory modules for a faster standard set-up.
The memory module copier is a copying system for all memory modules from Lenze. With the help of simple optical user guidance, the data of a module is copied quickly and reliably to another memory module.


Memory module copiers

| Order code | Type |
| :--- | :--- |
| EZAEDE1001 | Data set copier for memory modules |

## Mains chokes

- Mains chokes reduce the feedback effects of the inverter on the supplying mains by their high inductive resistance reducing high-frequency interference.
- The effective mains current is reduced which saves energy.
- Mains chokes can be used without restrictions in conjunction with RFI filters.
- Please note that the use of a mains choke reduces the mains voltage at the input of the inverter by 4 \% (typical voltage drop across the mains choke in the rated point).


The matching assignment of these accessories is specified in the technical data of the devices.

## RFI filters / Mains filters

RFI and mains filters are used to ensure compliance with the EMC requirements of EN IEC 61800-3. This standard defines the EMC requirements for electrical drive system in various categories.

- RFI filters are capacitive accessory components. RFI filters reduce conducted noise emissions. RFI filters are also called EMC filters.
- Mains filters are a combination of mains choke and RFI filter. Mains filters reduce the conducted noise emission.


## Definition of the environments

(EN IEC 61800-3)

## First environment

The first environment comprises residential buildings or locations that are directly connected to a low-voltage system for supplying residential areas.

## Second environment

The second environment comprises facilities or locations that are not directly connected to a low-voltage system for supplying residential areas.

## Category C1

Category C1 defines the requirements for drive systems that are intended for the use in the first environment at a rated voltage lower than 1000 V .
The limit values of the EN IEC 61800-3 comply with EN 55011 class B.

## Category C2

Category C2 defines the requirements for permanently installed fixed drive systems that are intended for the use in the first environment at a rated voltage lower than 1000 V . Installation and commissioning may only be carried out by specialist personnel with EMC knowledge.
The limit values of the EN IEC 61800-3 comply with EN 55011 class A group 1.

## Category C3

Category C3 defines the requirements for drive systems that are exclusively intended for the use in the second environment at a rated voltage lower than 1000 V .

The limit values of the EN IEC 61800-3 comply with EN 55011 class A group 2.
When working with stricter line-bound noise emission requirements which cannot be met using the radio interference suppression measures integrated in the inverter, external filters can be used. The filters can be installed below or next to the inverter.

If necessary, the internal filters have to be deactivated when external filters are used. For this purpose, remove the IT screws of the inverters.


Comparison of integrated and external RFI filters

| RFI filter | Filter types |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :---: |
|  | Integrated in the inverter | External |  |  |  |
|  |  | Low Leakage | Short Distance | Long Distance |  |
| Use | In standard applications | In mobile systems | With short cable length | At switching frequencies <br> 4 kHz and 8 kHz. |  |
| Optimization |  |  |  | For low leakage current |  |
| Reduces noise emissions | Cable-guided and radiated | Cable-guided | Cable-guided | Cable-guided |  |

The matching assignment of these accessories is specified in the technical data of the devices.

## Sine filter

A sinusoidal filter in the motor cable limits the rate of voltage rise and the capacitive charge/ discharge currents between the conductors that occur during inverter operation.

Only use a sinusoidal filter with standard asynchronous motors 0 to 550 V .
Operation only with V/f or square-law V/f characteristic control.
Set the switching frequency permanently to the specified value.
Limit the output frequency of the inverter to the given value.


The matching assignment of these accessories is specified in the technical data of the devices.

## Brake switches

For switching an electromechanical brake.
The brake switch consists of a rectifier and an electronic circuit breaker. It is mounted on the control cabinet plate. Control is performed using a digital output on the inverter.


| Brake switches |  | Half-wave rectifiers | Bridge rectifiers |
| :--- | :--- | :---: | :---: |
| Order code |  | E82ZWBRE | E82ZWBRB |
| Input voltage | V | AC 320-550 | AC 180-317 |
| Output voltage | V | DC 180 (with AC 400) | DC 225 (with AC 500) |

## Accessories

Mounting
Shield mounting kit

## Mounting

## Shield mounting kit

## Motor cable

If the shielding of the motor cable is centrally connected to an earthing busbar in the control cabinet, no shielding is required.
For a direct connection of the shielding of the motor cable to the inverter, the optionally available accessories can be used consisting of shield sheet and fixing clips or wire clamps.


| Inverter | Shield mounting kit |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Order code | Packaging unit | Order code | Packaging unit |
|  |  | Unit |  | Unit |
| i510-C0.25/230-1 | EZAMBHXM018/M | $5 x$ motor shield plate <br> 5x fixing clip <br> 5 x wire clamp (cable diameter 0.157 ... <br> 0.591 in ( $4 \ldots 15 \mathrm{~mm}$ )) | EZAMBHXM018/S | $1 \times$ motor shield plate <br> 1x fixing clip <br> 1 x wire clamp (cable diameter 0.157 ... <br> 0.591 in ( $4 \ldots 15 \mathrm{~mm}$ )) |
| i510-C0.25/230-2 |  |  |  |  |
| i510-C0.37/230-1 |  |  |  |  |
| i510-C0.37/230-2 |  |  |  |  |
| i510-C0.55/230-1 |  |  |  |  |
| i510-C0.55/230-2 |  |  |  |  |
| i510-C0.75/230-1 |  |  |  |  |
| i510-C0.75/230-2 |  |  |  |  |
| i510-C1.1/230-1 |  |  |  |  |
| i510-C1.1/230-2 |  |  |  |  |
| i510-C1.5/230-1 |  |  |  |  |
| i510-C1.5/230-2 |  |  |  |  |
| i510-C2.2/230-1 |  |  |  |  |
| i510-C2.2/230-2 |  |  |  |  |
| i510-C4.0/230-3 |  | 5 x motor shield plate |  | $1 \times$ motor shield plate |
| i510-C5.5/230-3 | EZAMBHXM015/M | $5 x$ fixing clip <br> $5 x$ wire clamp (cable diameter 0.157 ... <br> 0.591 in ( $4 \ldots 15 \mathrm{~mm}$ )) <br> $5 \mathrm{x} \mathrm{M} 4 \times 12$ screw | EZAMBHXM015/S | $1 x$ fixing clip <br> $1 \times$ wire clamp (cable diameter 0.157 ... <br> 0.591 in ( $4 \ldots 15 \mathrm{~mm}$ )) <br> $1 \times \mathrm{M} 4 \times 12$ screw |
|  |  |  |  |  |
| i510-C0.37/400-3 | EZAMBHXM018/M | $5 x$ motor shield plate <br> $5 x$ fixing clip <br> 5 x wire clamp (cable diameter 0.157 ... <br> 0.591 in ( $4 \ldots 15 \mathrm{~mm}$ )) | EZAMBHXM018/S | 1 x motor shield plate <br> $1 x$ fixing clip <br> 1 x wire clamp (cable diameter 0.157 ... <br> 0.591 in ( $4 \ldots 15 \mathrm{~mm}$ )) |
| i510-C0.55/400-3 |  |  |  |  |
| i510-C0.75/400-3 |  |  |  |  |
| i510-C1.1/400-3 |  |  |  |  |
| i510-C1.5/400-3 |  |  |  |  |
| i510-C2.2/400-3 |  |  |  |  |
| i510-C3.0/400-3 |  |  |  |  |
| i510-C4.0/400-3 |  |  |  |  |
| i510-C5.5/400-3 | EZAMBHXM015/M | $5 x$ motor shield plate <br> $5 x$ fixing clip <br> $5 x$ wire clamp (cable diameter $0.157 \ldots$ <br> 0.591 in ( $4 \ldots 15 \mathrm{~mm}$ )) <br> 5x M4x12 screw | EZAMBHXM015/S | 1x motor shield plate <br> $1 x$ fixing clip <br> 1 x wire clamp (cable diameter 0.157 ... <br> 0.591 in ( $4 \ldots 15 \mathrm{~mm}$ )) <br> 1x M4x12 screw |
| i510-C7.5/400-3 |  | 5 x motor shield plate |  | $1 \times$ motor shield plate |
| i510-C11/400-3 | EZAMBHXMB16/M | $5 x$ fixing clip <br> $5 x$ wire clamp (cable diameter $0.394 \ldots$ <br> 0.787 in ( 10 ... 20 mm )) <br> 5x M4x12 screw | EZAMBHXMB16/S | $1 x$ fixing clip <br> $1 x$ wire clamp (cable diameter 0.394 ... <br> 0.787 in ( 10 ... 20 mm )) <br> $1 \times \mathrm{M} 4 \times 12$ screw |

## Terminal strips

For connecting the inverter, the connections are equipped with pluggable terminal strips. Pluggable terminal strips are available separately for service purposes or if cable harnesses need to be physically separated.

| Inverter | Terminal strips <br> Mains connection X100 |  | Terminal strips <br> Motor connection X105 |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Order code | VPE | Order code | VPE |
|  |  | Piece |  | Piece |
| i510-C0.25/230-1 | EZAEVE032/M | 10 | EZAEVE038/M | 10 |
| i510-C0.37/230-1 |  |  |  |  |
| i510-C0.55/230-1 |  |  |  |  |
| i510-C0.75/230-1 |  |  |  |  |
| i510-C1.1/230-1 | EZAEVE033/M |  |  |  |
| i510-C1.5/230-1 |  |  |  |  |
| i510-C2.2/230-1 |  |  |  |  |
| i510-C0.25/230-2 | EZAEVE034/M | 10 |  |  |
| i510-C0.37/230-2 |  |  |  |  |
| i510-C0.55/230-2 |  |  |  |  |
| i510-C0.75/230-2 |  |  |  |  |
| i510-C1.1/230-2 | EZAEVE035/M |  |  |  |
| i510-C1.5/230-2 |  |  |  |  |
| i510-C2.2/230-2 |  |  |  |  |
| i510-C0.37/400-3 | EZAEVE036/M | 10 |  |  |
| i510-C0.55/400-3 |  |  |  |  |
| i510-C0.75/400-3 |  |  |  |  |
| i510-C1.1/400-3 |  |  |  |  |
| i510-C1.5/400-3 |  |  |  |  |
| i510-C2.2/400-3 |  |  |  |  |
| i510-C3.0/400-3 | EZAEVE037/M | 5 | EZAEVE039/M |  |
| i510-C4.0/400-3 |  |  |  |  |


| Terminal strips | Order code | VPE | Terminal strips | Order code | VPE |
| :--- | :--- | :--- | :--- | :--- | :--- |
|  |  | Piece |  |  | Piece |
| Relay X9 | EZAEVE030/M | 10 | CANopen / Modbus X216 | EZAEVE042/M | 10 |

## Accessories

Mounting
DIN rail

## DIN rail

In accordance with EN 60175, the inverter can be mounted onto a DIN rail $35 \mathrm{~mm} \times 7.5 \mathrm{~mm}$. For this purpose, a mounting set is available.


| Mounting set | Can be used for inverters |
| :--- | :--- |
| Order code | Order code |
| I5ZABODR1S | I5xAE125x, I5xAE137x, I5xAE155x, I5xAE175x |
| I5ZABODR2S | I55AE175Ax, I5xAE211x, I5xAE215x, I5xAE222x, I5xxE230x, I5xxE240x, I5xxE255x |

## Purchase order

## Notes on ordering

The inverters are supplied as complete devices. A control unit with basic I/O is integrated. As the control unit cannot be extended, the i510 inverter is available in two versions:

- With CANopen/Modbus, switchable.
- Without network.


## „EASY Product Finder"

The »EASY Product Finder« helps you to configure your required product in next to no time. In addition, you can retrieve all important technical details such as data sheets, CAD data, and EPLAN data.
The link and the QR code lead directly to the "EASY Product Finder": EASY Product Finder


## Purchase order

Order code

## Order code

## Delivery as complete inverter

Order data: Order code of the complete device.

## Order example

| Description of the component | Order code |
| :--- | :--- |
| Complete inverter |  |
| 3-phase mains connection 400 V |  |
| Power 0.75 kW (i510-C0.75/400-3) | I51AE175F10010001S |
| Without safety engineering (not available for i510) |  |
| Default setting of parameters: EU region (50-Hz systems) |  |

## i510 inverter

| Power |  | Inverter | Order code |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| kW $\quad$ hp |  |  |  |  |  |  |
| 1-phase mains connection $230 / 240 \mathrm{~V}$, EMC filter integrated |  |  |  |  |  |  |
| 0.25 | 0.33 | i510-C0.25/230-1 | 151AE125B1 | 0V1 |  |  |
| 0.37 | 0.5 | i510-C0.37/230-1 | 151AE137B1 |  |  |  |
| 0.55 | 0.75 | i510-C0.55/230-1 | 151AE155B1 |  |  |  |
| 0.75 | 1 | i510-C0.75/230-1 | 151AE175B1 |  |  |  |
| 1.1 | 1.5 | i510-C1.1/230-1 | 151AE211B1 |  |  |  |
| 1.5 | 2 | i510-C1.5/230-1 | 151AE215B1 |  |  |  |
| 2.2 | 3 | i510-C2.2/230-1 | 151AE222B1 |  |  |  |
| 1/3-phase mains connection 230/240 V, EMC filter not integrated |  |  |  |  |  |  |
| 0.25 | 0.33 | i510-C0.25/230-2 | 151AE125D1 | OVO |  |  |
| 0.37 | 0.5 | i510-C0.37/230-2 | 151AE137D1 |  |  |  |
| 0.55 | 0.75 | i510-C0.55/230-2 | 151AE155D1 |  |  |  |
| 0.75 | 1 | i510-C0.75/230-2 | 151AE175D1 |  |  |  |
| 1.1 | 1.5 | i510-C1.1/230-2 | 151AE211D1 |  |  |  |
| 1.5 | 2 | i510-C1.5/230-2 | 151AE215D1 |  |  |  |
| 2.2 | 3 | i510-C2.2/230-2 | 151AE222D1 |  |  |  |
| 4 | 5.5 | i510-C4.0/230-3 | 151AE240C1 |  |  |  |
| 5.5 | 7.5 | i510-C5.5//230-3 | 151AE255C1 |  |  |  |
| 3-phase mains connection 400/480 V, EMC filter integrated |  |  |  |  |  |  |
| 0.37 | 0.5 | i510-C0.37/400-3 | 151AE137F1 | 0V1 |  |  |
| 0.55 | 0.75 | i510-C0.55/400-3 | 151AE155F1 |  |  |  |
| 0.75 | 1 | i510-C0.75/400-3 | 151AE175F1 |  |  |  |
| 1.1 | 1.5 | i510-C1.1/400-3 | 151AE211F1 |  |  |  |
| 1.5 | 2 | i510-C1.5/400-3 | 151AE215F1 |  |  |  |
| 2.2 | 3 | i510-C2.2/400-3 | 151AE222F1 |  |  |  |
| 3 | 4 | i510-C3.0/400-3 | 151BE230F1 |  |  |  |
| 4 | 5.5 | i510-C4.0/400-3 | 151BE240F1 |  |  |  |
| 5.5 | 7.5 | i510-C5.5/400-3 | 151AE255F1 |  |  |  |
| 7.5 | 10 | i510-C7.5/400-3 | 151BE275F1 |  |  |  |
| 11 | 15 | i510-C11/400-3 | 151BE311F1 |  |  |  |
| Application |  |  |  |  |  |  |
| Default parameter setting: Region EU (50-Hz networks) |  |  |  |  | 0 |  |
| Default parameter setting: Region US (60-Hz networks) |  |  |  |  | 1 |  |
| Design types |  |  |  |  |  |  |
| Basic I/O without network |  |  |  |  |  | 000S |
| Basic I/O with CANopen/Modbus |  |  |  |  |  | 0015 |

## Environmental notes and recycling

Lenze has been certified to the worldwide environmental management standard for many years (DIN EN ISO 14001). As part of our environmental policy and the associated climate responsibility, please note the following information on hazardous ingredients and the recycling of Lenze products and their packaging:


Lenze products are partly subject to the EU Directive on the restriction of certain hazardous substances in electrical and electronic equipment 2011/65/EU: RoHS Directive [UKCA: S.I. 2012/3032 - The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012] . This is documented accordingly in the EU declaration of conformity and with the CE mark.


Lenze products are not subject to EU Directive 2012/19/EU: Directive on waste electrical and electronic equipment (WEEE) [UKCA: S.I. 2013/3113 - The Waste Electrical and Electronic Equipment Regulations 2013] , but some contain batteries/rechargeable batteries in accordance with EU Directive 2006/66/EC: Battery Directive [UKCA: S.I. 2009/890 - The Waste Batteries and Accumulators Regulations 2009]. The disposal route, which is separate from household waste, is indicated by corresponding labels with the "crossed-out trash can".
Any batteries/rechargeable batteries included are designed to last the life of the product and do not need to be replaced or otherwise removed by the end user.


Lenze products are usually sold with cardboard or plastic packaging. This packaging complies with EU Directive 94/62/EC: Directive on packaging and packaging waste [UKCA: S.I. 1997/648 - The Producer Responsibility Obligations (Packaging Waste) Regulations 1997] . The required disposal route is indicated by material-specific labels with the "recycling triangle". Example: "21-other cardboard"

REACH Lenze products are subject to REGULATION (EC) No 1907/2006: REACH Regulation [UKCA: S.I. 2008/2852 - The REACH Enforcement Regulations 2008]. When used as intended, exposure of substances to humans, animals and the environment is excluded.

Lenze products are industrial electrical and electronic products and are disposed of professionally. Both the mechanical and electrical components such as electric motors, gearboxes or inverters contain valuable raw materials that can be recycled and reused. Proper recycling and thus maintaining the highest possible level of recyclability is therefore important and sensible from an economic and ecological point of view.

- Coordinate professional disposal with your waste disposal company.
- Separate mechanical and electrical components, packaging, hazardous waste (e.g. gear oils) and batteries/rechargeable batteries wherever possible.
- Dispose of the separated waste in an environmentally sound and proper manner (no household waste or municipal bulky waste).

| What? | Material | Disposal instructions |
| :--- | :--- | :--- |
| Pallets | Wood | Return to manufacturers, freight forwarders or <br> reusable materials collection system |
| Packaging material | Paper, cardboard, pasteboard, plastics | Collect and dispose of separately |
| Products |  | As electronic waste give to professional disposer for <br> recycling |
| Electronic devices | Metal, plastics, circuit boards, heatsinks | Drain oil and dispose of separately |
|  | Oil | Dispose as metal scrap |
|  | Casting, steel, aluminium | As engine scrap give to professional disposer for <br> recycling |
| Motors | Casting, copper, rotors, magnets, potting compound |  |
| Dry-cell batteries/rechargeable <br> batteries |  | As used batteries give to professional disposer for <br> recycling |

Further information on Lenze's environmental and climate responsibility and on the topic of energy efficiency can be found on the Internet:
www.Lenze.com $\rightarrow$ search word: "Sustainability"

## Appendix

## Good to know

## Operating modes of the motor

Operating modes S1 ... S10 as specified by EN 60034-1 describe the basic stress of an electrical machine.

In continuous operation a motor reaches its permissible temperature limit if it outputs the rated power dimensioned for continuous operation. However, if the motor is only subjected to load for a short time, the power output by the motor may be greater without the motor reaching its permissible temperature limit. This behaviour is referred to as overload capacity.

Depending on the duration of the load and the resulting temperature rise, the required motor can be selected reduced by the overload capacity.
The most important operating modes
Continuous operation S1
Intermittent operation S3

Sequence of identical duty cycles comprising operation with a constant load and subsequent standstill. Start-up and braking processes do not have an impact on the winding temperature. The steady-state is not reached. The guide values apply to a cycle duration of 10 minutes. The power increase depends on the cycle duration and on the load period/ downtime ratio.

| $P$ | Power |
| :--- | :--- |
| $t$ | Time |
| $t_{L}$ | Idle time |
| $\vartheta$ | Temperature |

Sequence of identical duty cycles comprising operation with a constant load and subsequent no-load operation. The motor cools down during the no-load phase. Start-up and braking processes do not have an impact on the winding temperature. The steady-state is not reached. The guide values apply to a cycle duration of 10 minutes. The power increase depends on the cycle duration and on the load period/idle time ratio.
$\mathrm{P}_{\mathrm{V}} \quad$ Power loss
$t_{B} \quad$ Load period
$\mathrm{t}_{\mathrm{S}} \quad$ Cycle duration

## Motor control types

The inverter provides various motor control types.

## Linear V/f characteristic control

The output voltage is increased proportionately to the output frequency.
In case of low output frequencies, the motor voltage can be increased to ensure a minimum current for the breakaway torque. In the field weakening range, the output voltage of the inverter is constant (mains voltage) and the frequency can be further increased depending on the load. The maximum torque of the motor is reduced proportionately to the square of the frequency increase, the maximum output power of the motor being constant.

Application areas are for instance: Single drives with constant load.


## Square-law V/f characteristic control

The output voltage is increased squarely to the output frequency.
In case of low output frequencies, the motor voltage can be increased to ensure a minimum current for the breakaway torque. In the field weakening range, the output voltage of the inverter is constant (mains voltage) and the frequency can be further increased depending on the load. The maximum torque of the motor is reduced squarely to the frequency increase, the maximum output power of the motor being constant.
Application areas are for instance:

- Pumps
- Fans
- Ventilators

V Voltage
f Frequency
M Torque
$\mathrm{f}_{\mathrm{N}} \quad$ Rated frequency


## VFCeco

The VFCeco mode has a special effect in the partial load operational range. Usually, threephase AC motors are supplied there with a higher magnetising current than required by the operating conditions. The VFCeco mode reduces the losses in the partial load operational range so that savings up to $30 \%$ are possible.


| V | Voltage |
| :--- | :--- |
| $\mathrm{U}_{\mathrm{AC}}$ | Mains voltage |
| $\mathrm{U}_{\mathrm{N}}$ | Rated voltage |

[^2]
## Sensorless vector control (SLVC)

In vector control, an inverted voltage model is used for calculation. The parameters are detected via a parameter identification. The inverter determines the angle between current and voltage. This imposes a current on the motor".

Compared to the V/f characteristic control, the vector control serves to achieve improved drive characteristics thanks to:

- higher torque throughout the entire speed range
- higher speed accuracy and higher concentricity factor
- higher efficiency


| M | Torque |
| :--- | :--- |
| n | Speed |

$M_{N} \quad$ Rated torque
n Speed
$\mathrm{n}_{\mathrm{N}} \quad$ Rated speed
Application areas are for instance:

- Single drives with changing loads
- Single drives with high starting duty
- Sensorless speed control of three-phase AC motors


## Switching frequencies

On an inverter, the term "switching frequency" is understood to mean the frequency with which the input and outputs of the output module (inverter) are switched. On an inverter, the switching frequency can generally be set to values between 2 and 16 kHz , whereby the selection is based on the respective power output.
As switching the modules cause heat losses, the inverter can provide higher output currents at low switching frequencies than at high frequencies. Additionally, it is distinguished between the operation at a permanently set switching frequency and a variably set switching frequency. Here, the switching frequency is automatically reduced as a function of the device utilization.

At a higher switching frequency, the noise generation is less.
Options for the switching frequency:

- 2 kHz
- 4 kHz
- 8 kHz
- 12 kHz
- 16 kHz
- variable (automatic adaptation)


## Enclosures

The protection class indicates the suitability of a product for specific ambient conditions with regard to humidity as well as the protection against contact and the ingress of foreign particles. The protection classes are classified in the EN 60034-5/ EN IEC 60529.

The first code number after the code letters IP indicates the protection against the ingress of foreign particles and dust. The second code number refers to the protection against the ingress of humidity.

| Code number 1 | Degree of protection | Code number $\mathbf{2}$ | Degree of protection |
| :--- | :--- | :--- | :--- |
| 0 | No protection | 0 | No protection |
| 1 | Protection against the ingress of foreign particles $\mathrm{d}>$ <br> 50 mm. No protection in case of deliberate access. | 1 | Protection against vertically dripping water (dripping <br> water). |
| 2 | Protection against medium-sized foreign particles, <br> $\mathrm{d}>12 \mathrm{~mm}$, keeping away fingers or the like. | 2 | Protection against diagonally falling water (dripping <br> water), $15^{\circ}$ compared to normal service position. |
| 3 | Protection against small foreign particles $\mathrm{d}>2.5 \mathrm{~mm}$. <br> Keeping away tools, wires or the like. | 3 | Protection against spraying water, up to $60^{\circ}$ from <br> vertical. |
| 4 | Protection against granular foreign particles, $\mathrm{d}>1 \mathrm{~mm}$, <br> keeping away tools, wire or the like. | 4 | Protection against spraying water from all directions. |
| 5 | Protection against dust deposits (dust-protected), <br> complete protection against contact. | 5 | Protection against water jets from all directions. |
| 6 | Protection against the ingress of dust (dust-proof), <br> complete protection against contact. | 6 | Protection against choppy seas or heavy water jets <br> (flood protection). |

## Appendix

Glossary

## Glossary

Definitions in functional safety

| Abbreviation | Meaning |
| :---: | :---: |
| AIE | Acknowledge In Error, error acknowledgement |
| AIS | Acknowledge In Stop, restart acknowledgement |
| OFF state | Triggered signal status of the safety sensors |
| CCF | Common Cause Error (also $\beta$-value) |
| EC_FS | Error Class Fail Safe |
| EC_SS1 | Error Class Safe Stop 1 |
| EC_SS2 | Error Class Safe Stop 2 |
| EC_STO | Error Class Safe Torque Off Stop 0 |
| ON state | Signal status of the safety sensors in normal operation |
| FIT | Failure In Time, 1 FIT = 10-9 Error/h |
| FMEA | Failure Mode and Effect Analysis |
| FSoE | FailSafe over EtherCAT |
| GSDML | Device description file with PROFINET-specific data to integrate the configuring software of a PROFINET controller. |
| HFT | Hardware Failure Tolerance |
| Cat. | Category according to EN ISO 13849-1 |
| nBD | Speed value Base-Drive, internally determined actual speed from standard application |
| nSD | Safe-Drive speed value, internally determined actual speed from the safety application |
| n_safe | Actual speed determined from validation of nBD and nSD. Enters the further processing of the speed-dependent safety functions. |
| OSSD | Output Signal Switching Device, tested signal output |
| pBD | Base-Drive position value, internally determined actual position from standard application |
| pSD | Safe-Drive position value, internally determined actual position from the safety application |
| p_safe | Actual position determined from validation of pBD and pSD . Enters the further processing of the position-dependent safety functions. |
| PELV | Protective Extra Low Voltage |
| PL | Performance Level according to EN ISO 13849-1 |
| PM | Plus-Minus - switched signal paths |
| PP | Plus-Plus - switched signal paths |
| PS | PROFIsafe |
| PWM | Pulse Width Modulation |
| SCS | Safe Creeping Speed |
| SD-In | Safe Digital Input |
| SD-Out | Safe Digital Output |
| SELV | Safety Extra Low Voltage |
| SFF | Safe Failure Fraction |
| SIL | Safety Integrity Level according to EN IEC 61508 |

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[^0]:    - EMC-compliant installation ■39
    - Standards and operating conditions $■ 57$

[^1]:    Other data
    Note: There are no interdependencies between parameter data and process data.

[^2]:    Frequency
    Rated frequency
    $f_{\text {max }} \quad$ Max. frequency

